

# Radiometry and Radiosity

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# Global illumination, radiosity

## Based on **physics**

- energy transport (light transport) in simulated environment
- first usage of radiosity in image synthesis: Cindy Goral (SIGGRAPH 1984)

Radiosity is able to compute **diffuse light**, secondary lighting...

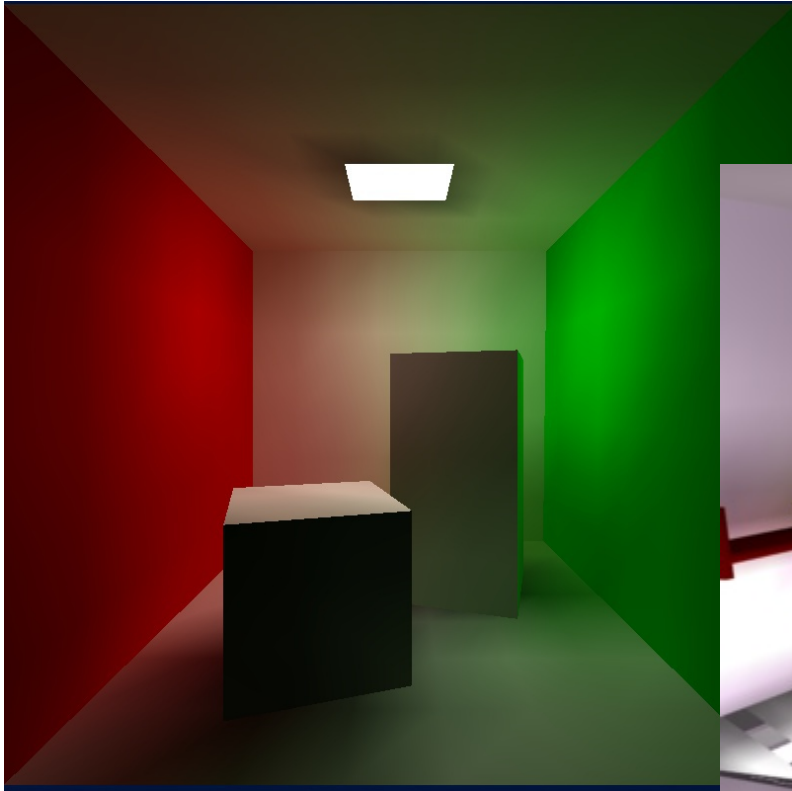
**Basic radiosity** cannot do sharp reflections, mirrors...

Time consuming computation

- Radiosity: light propagation only, R-T or GPU: rendering



# Radiosity – examples



© David Bařina (WiKi)

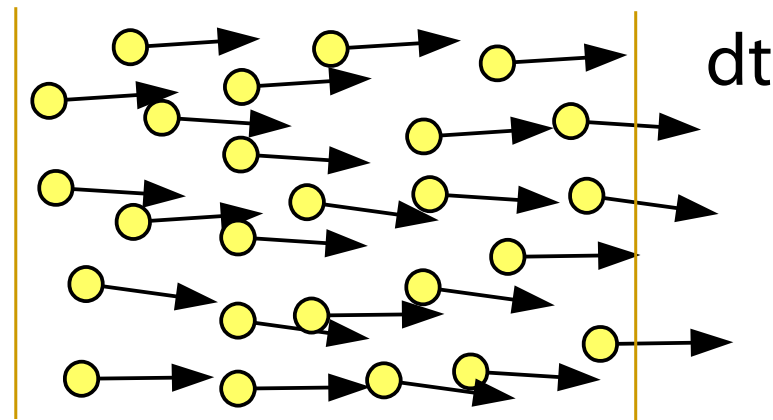


# Basic radiometry I

## Radiant flux, Radiant power

$$\Phi = \frac{dQ}{dt} \quad [\text{W}]$$

Number of photons (converted to energy) per time unit  
(100W bulb:  $\sim 10^{19}$  photons/s, eye pupil from a monitor:  $10^{12}$  photons/s)



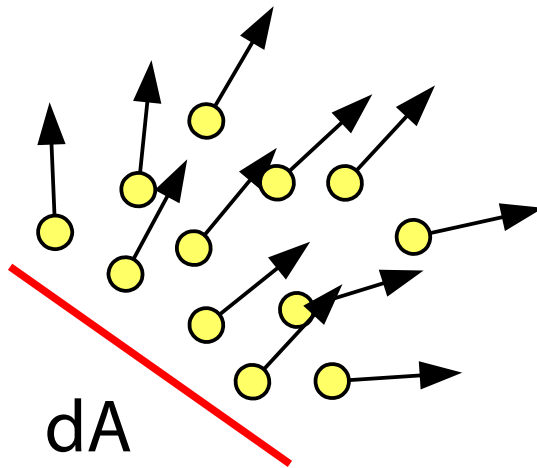


# Basic radiometry II

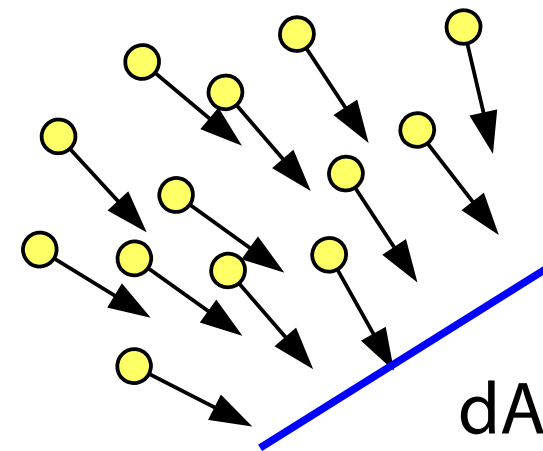
## Irradiance, Radiant exitance, Radiosity

$$E(x) = \frac{d\Phi(x)}{dA(x)} \quad [\text{W/m}^2]$$

Photon areal density (converted to energy) incident or radiated per time unit



$dt$





# Basic radiometry III

## Radiance

$$L(\boldsymbol{x}, \boldsymbol{\omega}) = \frac{d^2 \Phi(\boldsymbol{x}, \boldsymbol{\omega})}{dA_{\boldsymbol{\omega}}^{\perp}(\boldsymbol{x}) d\sigma(\boldsymbol{\omega})} \quad [ \text{W/m}^2/\text{sr} ]$$

Number of photons (converted to energy) per time unit passing through a small area perpendicular to the direction  $\boldsymbol{\omega}$ .

Radiation is directed to a small cone around the direction  $\boldsymbol{\omega}$ .

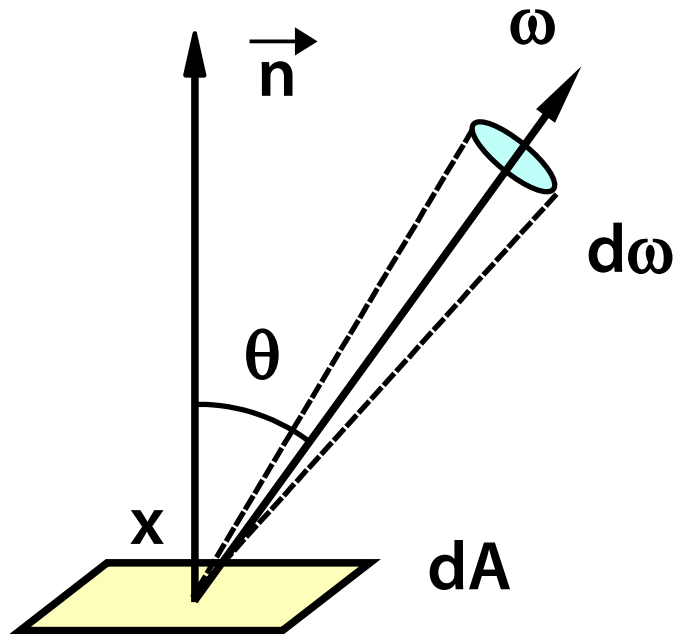
Radiance is a quantity defined as a **density** with respect to  $dA^{\perp}$  and with respect to solid angle  $d\sigma(\boldsymbol{\omega})$ .



# Radiance I

Received/emitted radiance in direction  $\omega$

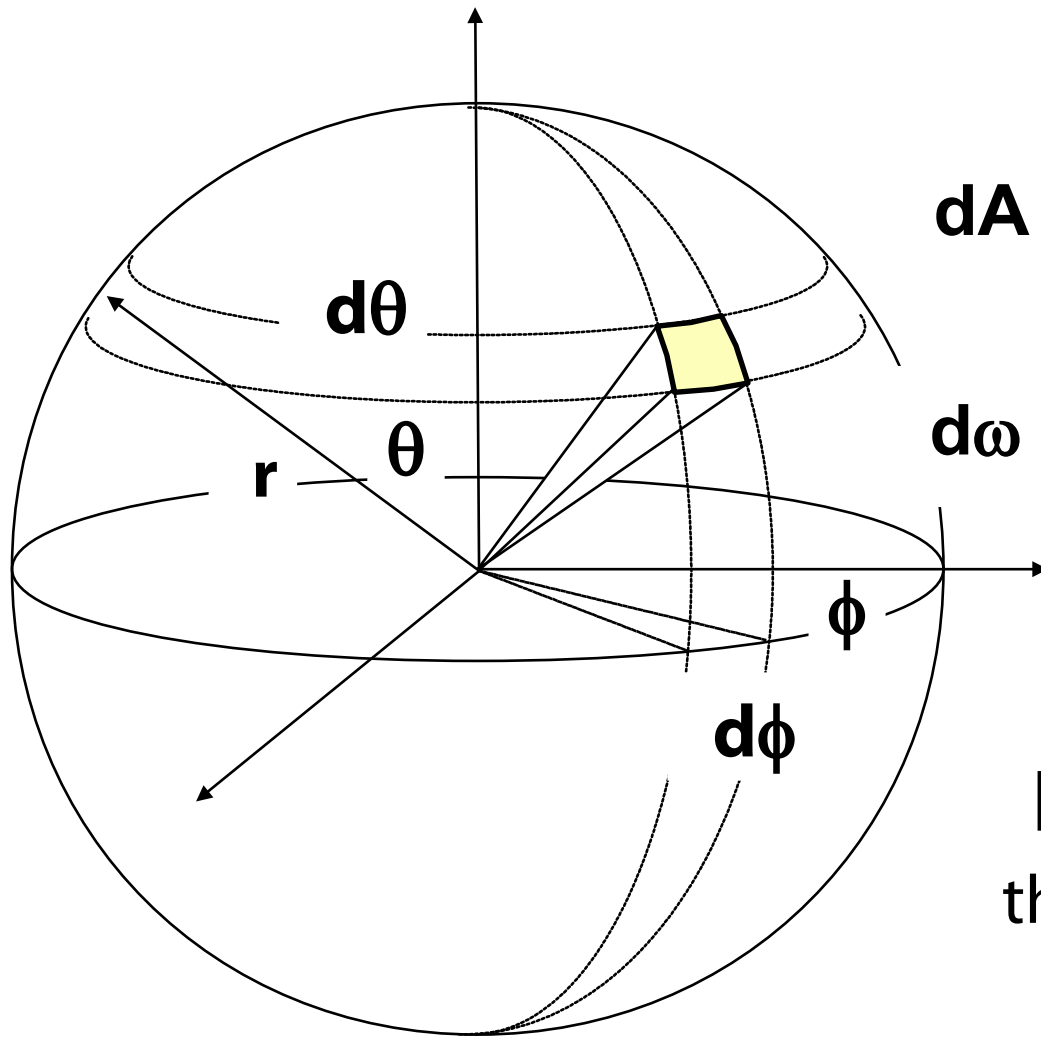
–  $L_{\text{in}}(\omega)$  ( $L_{\text{e}}(\omega), L_{\text{out}}(\omega)$ ) [ W/(m<sup>2</sup>· sr) ]



$$\begin{aligned} L_{\text{out}}(\mathbf{x}, \omega) &= \frac{d^2\Phi}{dA d\omega \cos\theta} \\ &= \frac{dB_{\text{out}}}{d\omega \cos\theta} \\ &= \frac{dl}{dA \cos\theta} \end{aligned}$$



# Solid angles



$$dA = r^2 \sin\theta \, d\theta \, d\phi$$

$$d\omega = \frac{dA}{r^2} = \sin\theta \, d\theta \, d\phi$$

$[\omega]$  ... steradian (sr)

the whole sphere ...  $4\pi$

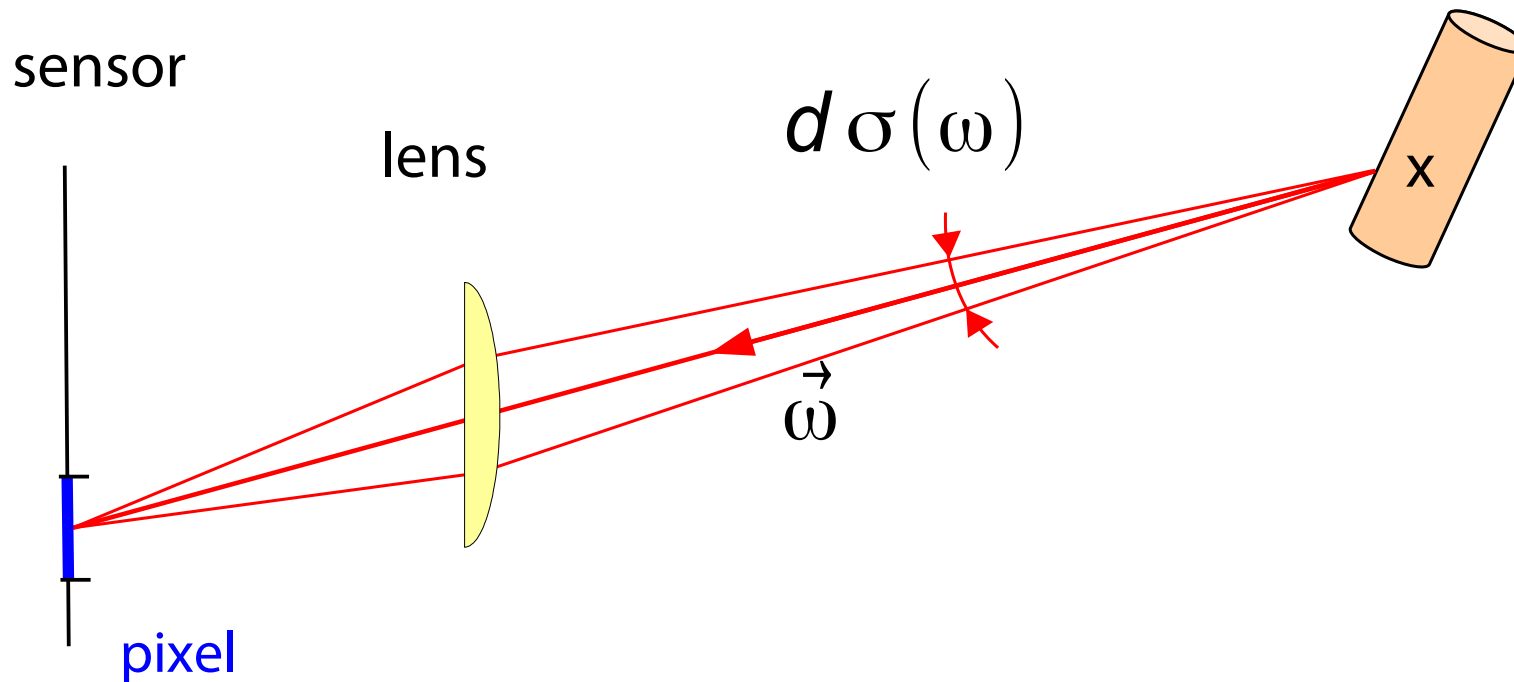
sr





# Radiance II

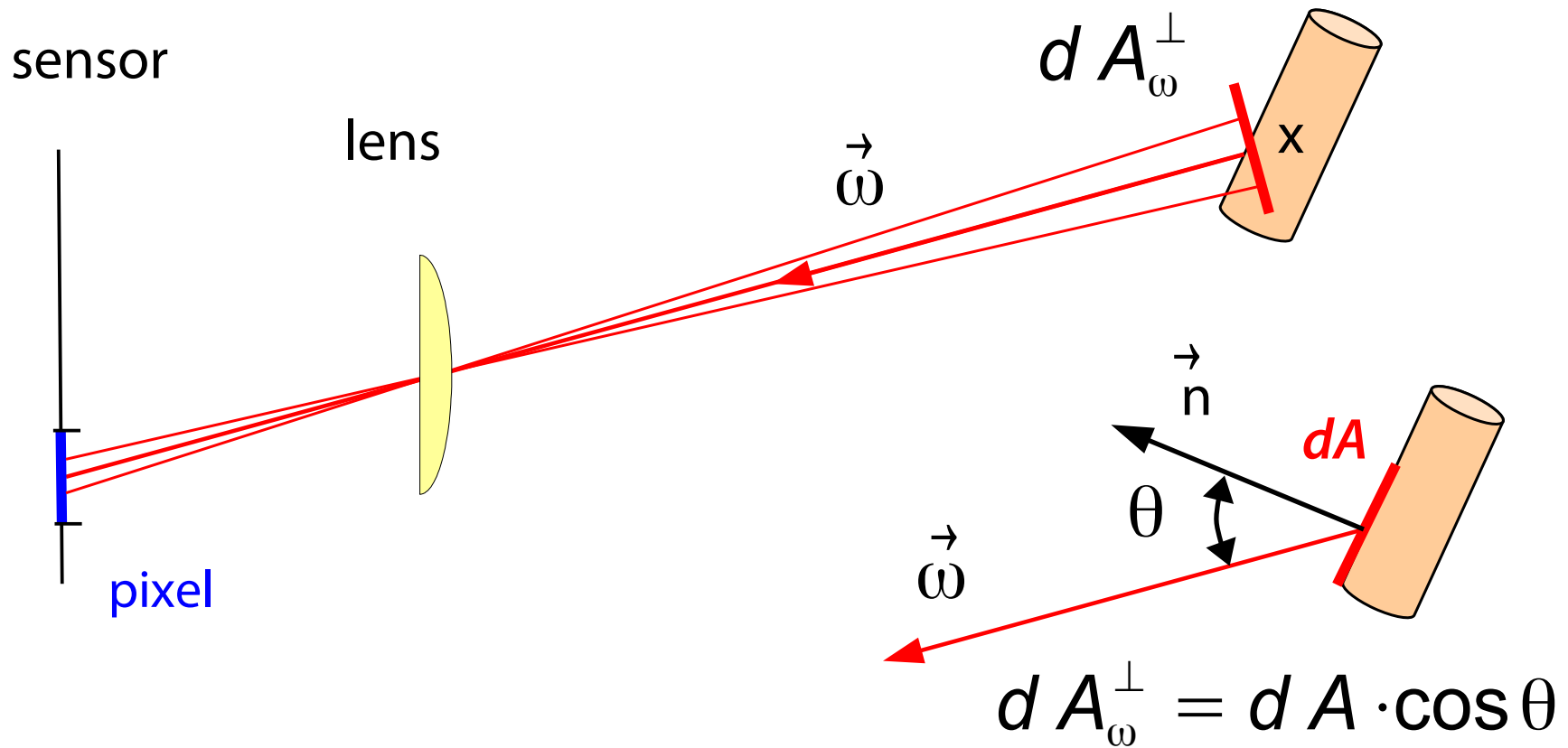
$$\Phi(x, \omega) \propto d\sigma(\omega)$$





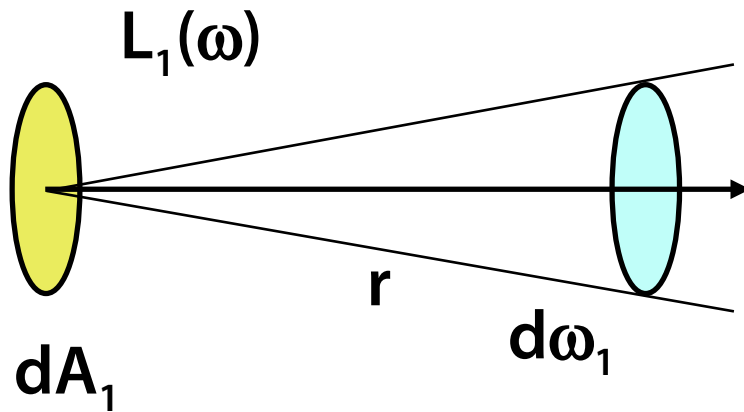
# Radiance III

$$\Phi(x, \omega) \propto dA_{\omega}^{\perp}(x)$$





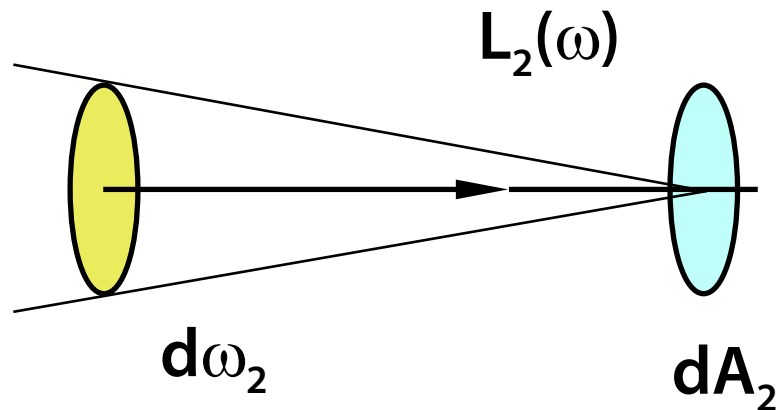
# Energy preservation law (ray / fiber)



$$L_1 d\omega_1 dA_1 = L_2 d\omega_2 dA_2$$

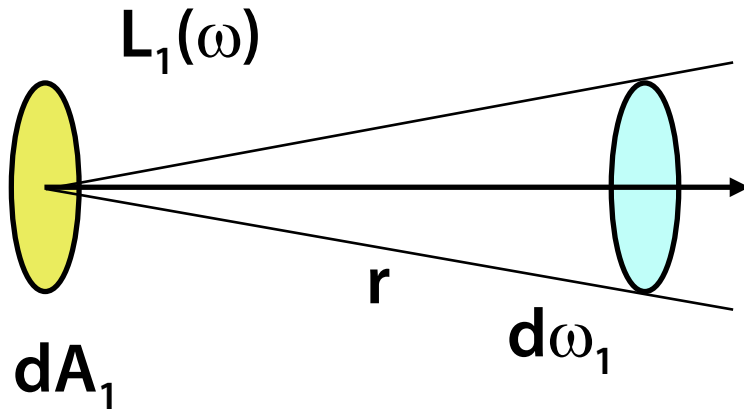
emitted  
power

received  
power





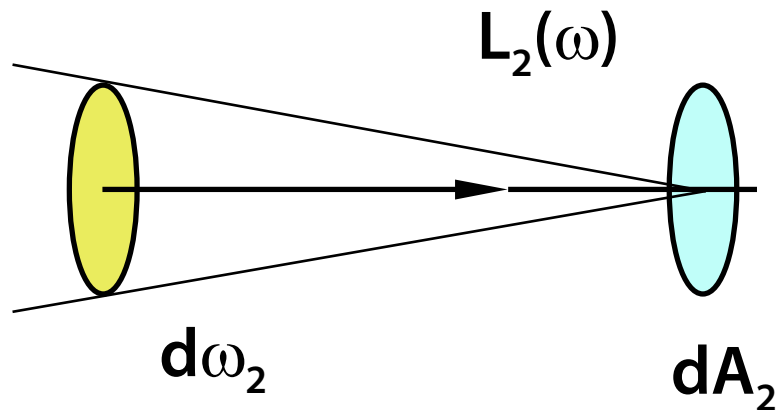
# Energy preservation law (ray / fiber)



$$L_1 d\omega_1 dA_1 = L_2 d\omega_2 dA_2$$

$$\begin{aligned} \underline{T} &= d\omega_1 dA_1 = d\omega_2 dA_2 = \\ &= \frac{dA_1 dA_2}{r^2} \end{aligned}$$

ray capacity



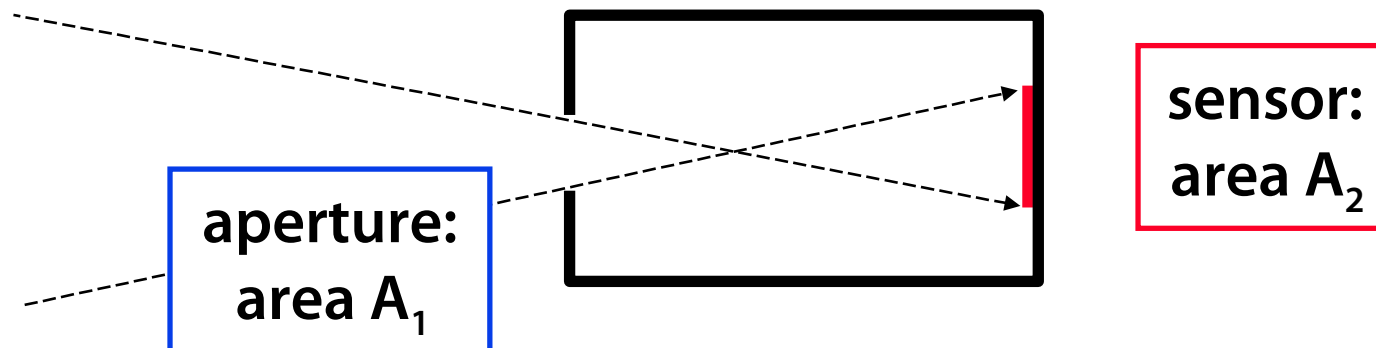
$$L_1 = L_2$$

ray ... radiance L



# Light measurement

Measured quantity is proportional to radiance from visible scene

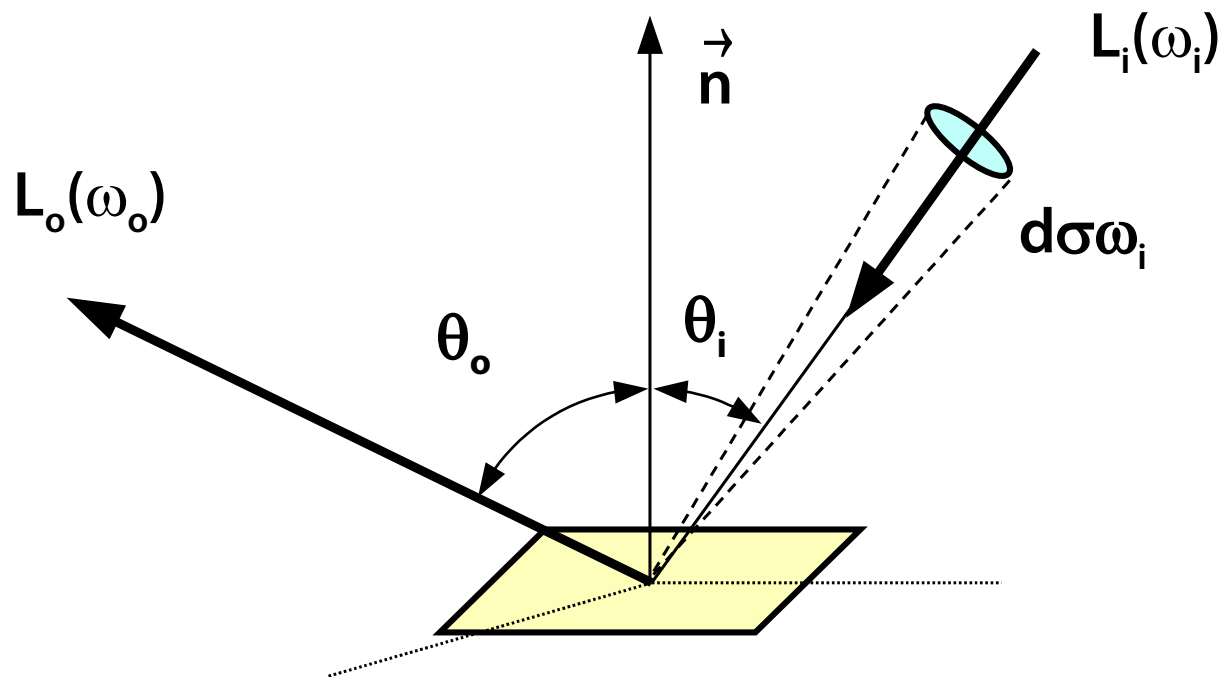


$$\underline{R} = \int_{A_2} \int_{\Omega} L_{in}(\mathbf{A}, \omega) \cdot \cos \theta \, d\omega \, dA = \underline{L_{in}} \cdot T$$



# BSDF (Local transfer function)

(„Bidirectional Scattering Distribution Function“, older term: BRDF)



$$f_s(\omega_i \rightarrow \omega_o) = \frac{dL_o(\omega_o)}{dE(\omega_i)} = \frac{dL_o(\omega_o)}{L_i(\omega_i) \cos \theta_i d\sigma^\perp(\omega_i)}$$



# Helmholtz law (reciprocity)

For real surfaces (physically plausible)

$$\mathbf{f}(\omega_{\text{in}} \rightarrow \omega_{\text{out}}) = \mathbf{f}(\omega_{\text{out}} \rightarrow \omega_{\text{in}})$$

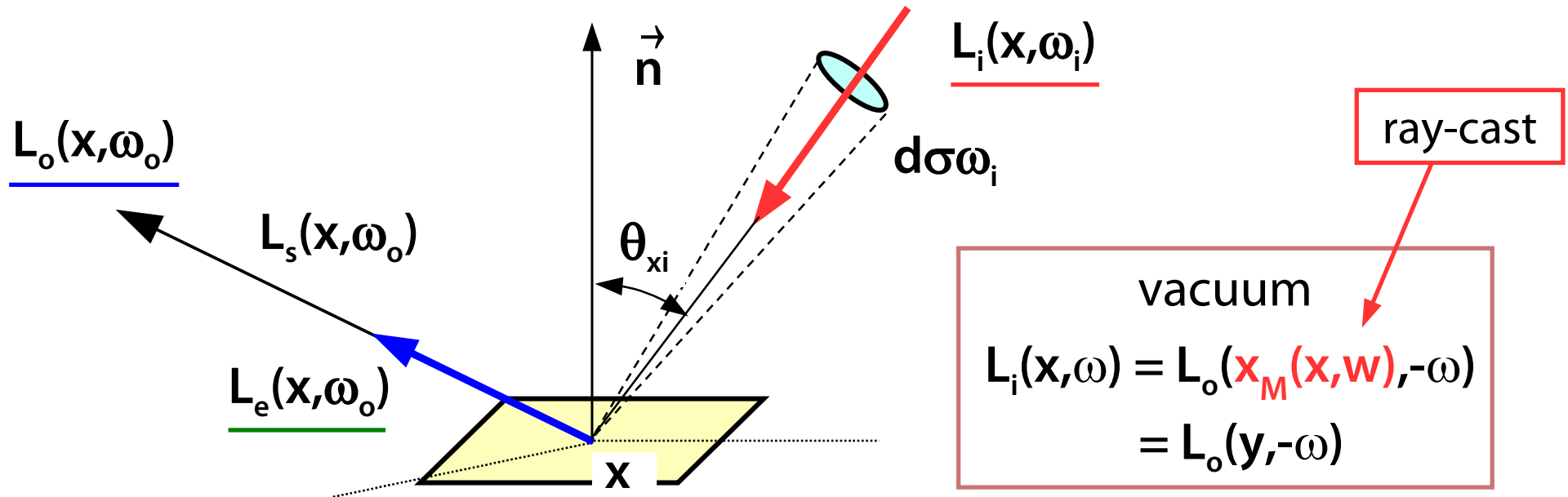
General **BSDF** needs not be isotropic (invariant to rotation around the surface normal)

– metal surfaces polished in one direction...

$$\mathbf{f}(\theta_{\text{in}}, \phi_{\text{in}}, \theta_{\text{out}}, \phi_{\text{out}}) \neq \mathbf{f}(\theta_{\text{in}}, \phi_{\text{in}} + \phi, \theta_{\text{out}}, \phi_{\text{out}} + \phi)$$



# Local rendering equation



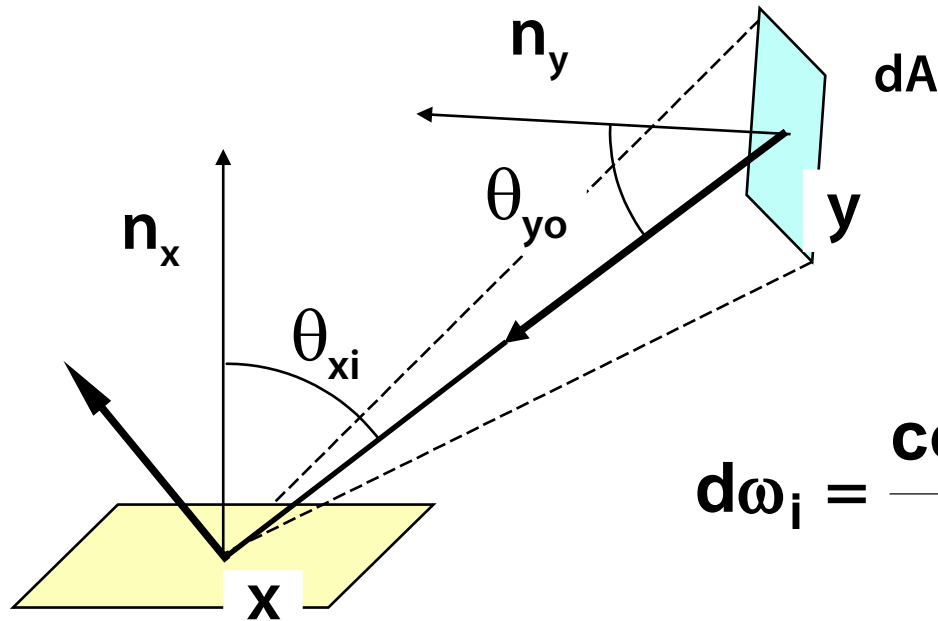
own emission at  $\mathbf{x}$

$$L_o(\mathbf{x}, \omega_o) = L_e(\mathbf{x}, \omega_o) + \int L_o(\mathbf{y}, -\omega_i) \cdot f_s(\mathbf{x}, \omega_i \rightarrow \omega_o) \cdot d\sigma_x^\perp(\omega_i)$$





# Radiance received from a surface



$$d\omega_i = \frac{\cos \theta_{y_o} dA}{\|x - y\|^2}$$

Geometric term: 
$$G(y, x) = \frac{\cos \theta_{y_o} \cos \theta_{x_i}}{\|x - y\|^2}$$



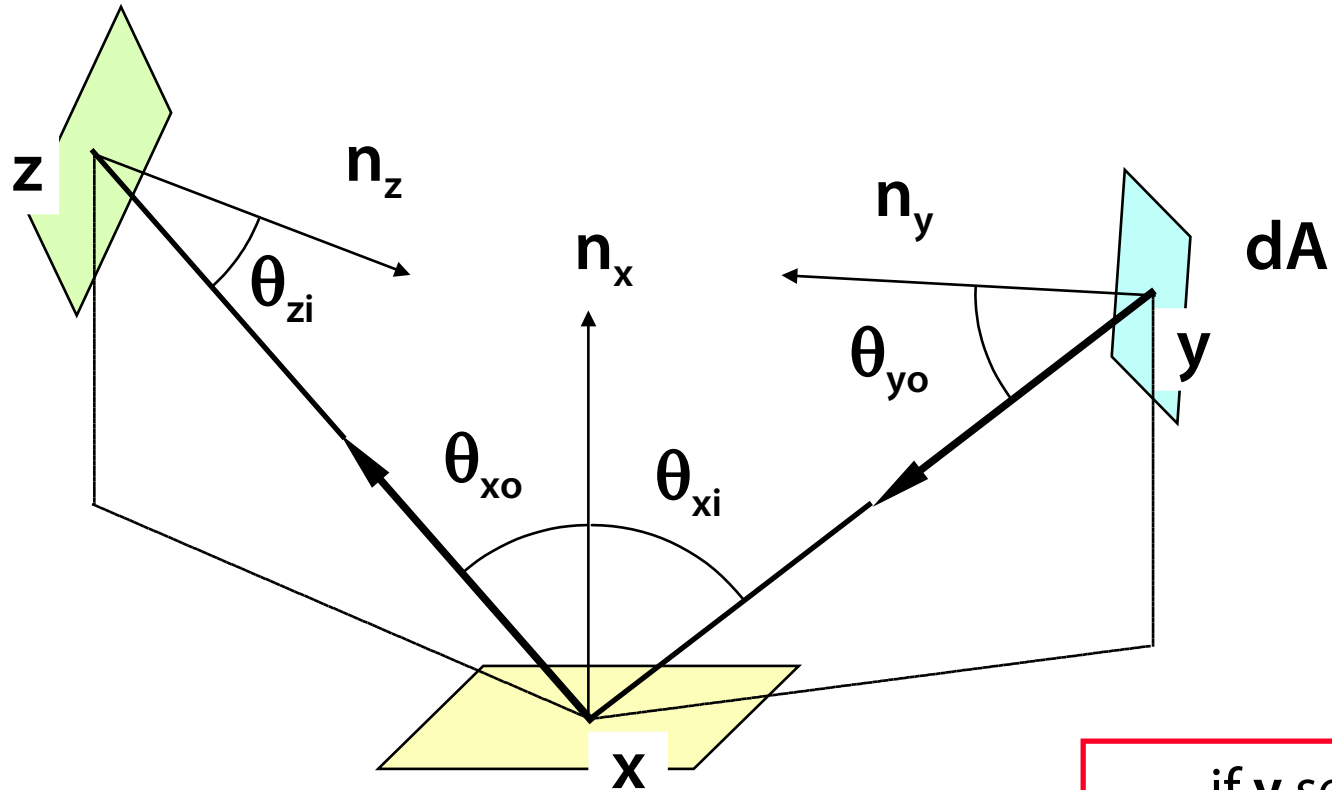
# Radiance received from a surface

$$\begin{aligned} L_o(\mathbf{x}, \omega_o) &= \text{integral over all incoming directions} \\ &= L_e(\mathbf{x}, \omega_o) + \int_{\Omega} \mathbf{f}(\mathbf{x}, \omega_i \rightarrow \omega_o) \cdot L_i(\mathbf{x}, \omega_i) \cdot \cos \theta_{xi} \, d\omega_i = \\ &= L_e(\mathbf{x}, \omega_o) + \int_S \mathbf{f}(\mathbf{x}, \omega_i \rightarrow \omega_o) \cdot L_o(\mathbf{y}, -\omega_i) \cdot \mathbf{G}(\mathbf{y}, \mathbf{x}) \, dA \\ & \text{integral over an emitting surface} \end{aligned}$$

(assumption: the whole surface  $S$  is visible from  $\mathbf{x}$ )



# Reflected light



(terminology only)

$$\underline{L}(\mathbf{y}, \mathbf{x}) = L_o(\mathbf{y}, \mathbf{x} - \mathbf{y}) = L_i(\mathbf{x}, \mathbf{y} - \mathbf{x})$$
$$\underline{f}(\mathbf{y}, \mathbf{x}, \mathbf{z}) = f(\mathbf{x}, (\mathbf{y} - \mathbf{x}) \rightarrow (\mathbf{z} - \mathbf{x}))$$

if y sees x



# Indirect radiance equation

$$V(\mathbf{y}, \mathbf{x}) = \begin{cases} 1 & \text{if } \mathbf{y} \text{ sees } \mathbf{x} \\ 0 & \text{else} \end{cases}$$

$$\underline{L(\mathbf{x}, \mathbf{z})} = \underline{L_e(\mathbf{x}, \mathbf{z})} + \int_S \underline{f(\mathbf{y}, \mathbf{x}, \mathbf{z})} \cdot \underline{L(\mathbf{y}, \mathbf{x})} \cdot \underline{G(\mathbf{y}, \mathbf{x})} \cdot \underline{V(\mathbf{y}, \mathbf{x})} \, dA$$

own (emitted)  
radiant exitance

BRDF

geometric  
terms



# Radiosity equation

Assumption – **ideal diffuse** (Lambertian) surface

- **BRDF** is not dependent on incoming/outgoing angles
- outgoing radiance  $L(\mathbf{y}, \omega)$  is independent on direction  $\omega$

$$L(\mathbf{x}, \mathbf{z}) = L_e(\mathbf{x}, \mathbf{z}) + f(\mathbf{x}) \cdot \int_S L(\mathbf{y}, \mathbf{x}) \cdot \mathbf{G}(\mathbf{y}, \mathbf{x}) \cdot \mathbf{V}(\mathbf{y}, \mathbf{x}) \, dA$$

$$L(\mathbf{x}, \mathbf{z}) = \mathbf{B}(\mathbf{x}) / \pi, \quad L_e(\mathbf{x}, \mathbf{z}) = \mathbf{E}(\mathbf{x}) / \pi, \quad f(\mathbf{x}) = \rho(\mathbf{x}) / \pi$$

$$\mathbf{B}(\mathbf{x}) = \mathbf{E}(\mathbf{x}) + \rho(\mathbf{x}) \cdot \int_S \mathbf{B}(\mathbf{y}) \cdot \frac{\mathbf{G}(\mathbf{y}, \mathbf{x}) \cdot \mathbf{V}(\mathbf{y}, \mathbf{x})}{\pi} \, dA$$



# Discrete solution

$$\mathbf{B}(\mathbf{x}) = \mathbf{E}(\mathbf{x}) + \rho(\mathbf{x}) \cdot \int_{\mathbf{S}} \mathbf{B}(\mathbf{y}) \cdot \mathbf{g}(\mathbf{y}, \mathbf{x}) \, dA$$

where  $\mathbf{g}(\mathbf{y}, \mathbf{x}) = \frac{\mathbf{G}(\mathbf{y}, \mathbf{x}) \cdot \mathbf{V}(\mathbf{y}, \mathbf{x})}{\pi}$

Solution  $\mathbf{B}$  is infinite-dimensional

Discretization of the task

- **Monte-Carlo** ray-tracing (dependent on camera)
- classical **radiosity** (finite/boundary elements FEM)



# General radiosity method

- ① Object surfaces divided into set of **elements**
- ② Definition of **knot points** on elements
  - **radiosity** will be computed there
- ③ Choice of an **approximation method** and error metric
  - basis functions for convex blend from knot points
- ④ **Coefficients** of linear equation system
  - “form-factors”



# General radiosity method

- 5 Solution of a **linear equation system**
  - result: radiosities at knot points
- 6 Reconstruction of values on **whole surfaces**
  - linear blends using basis functions and knot point radiosities
- 7 **Rendering** of results (arbitrary view)
  - light is proportional to radiosity





# Remarks

Step ③ is performed in the **algorithm design** phase

- does not appear in the implementation

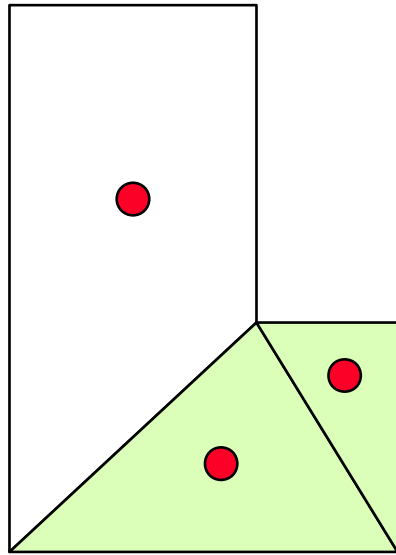
Some **advanced methods** do not strictly follow the sequence

① to ⑦

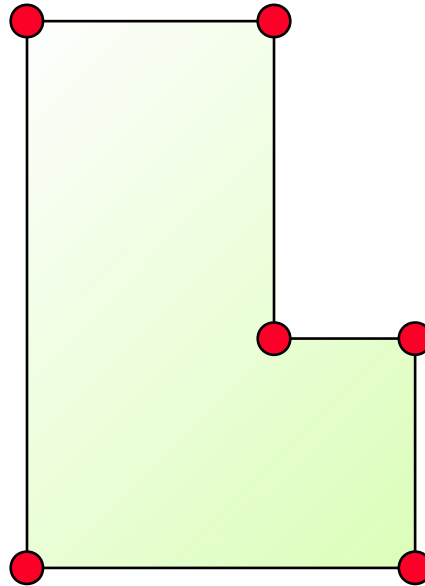
- sometimes a computation flow goes back to some previous phase, some phases could be iterated...



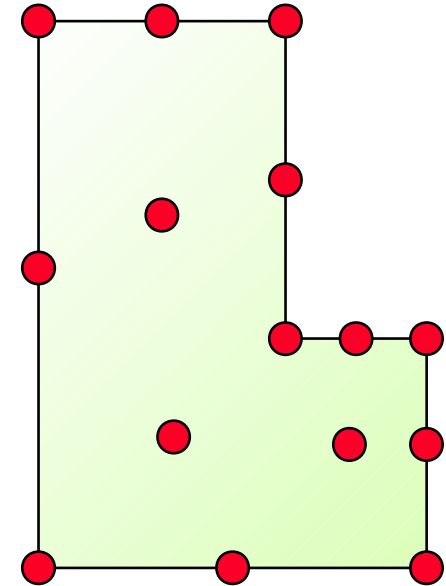
# Radiosity approximation



**constant**  
(knots in  
centers)



**bilinear**  
(knots in  
vertices)



**quadratic**  
(more inside  
knots...)



# Constant elements

On every element  $A_i$  **constant reflectivity** is assumed  $\rho$ , radiosity  $B$   
= average of  $B(\mathbf{x})$

– terminology:  $\rho_i, \mathbf{B}_i$  for  $i = 1 \dots N$

$$\mathbf{B}(\mathbf{x}) = \mathbf{E}(\mathbf{x}) + \rho(\mathbf{x}) \cdot \int_S \mathbf{B}(\mathbf{y}) \cdot \mathbf{g}(\mathbf{y}, \mathbf{x}) \, dA$$

$$\mathbf{B}_i = \mathbf{E}_i + \rho_i \cdot \frac{1}{A_i} \int_{A_i} \left[ \sum_{j=1}^N \mathbf{B}_j \int_{A_j} \mathbf{g}(\mathbf{y}, \mathbf{x}) \, dA_j \right] dA_i$$

average over  
area  $A_i$

radiosity received in point  $\mathbf{x}$  (lying on  $A_i$ )



# Basic radiosity equation

Swapping sum and integral

$$B_i = E_i + \rho_i \cdot \sum_{j=1}^N B_j \cdot \frac{1}{A_i} \int_{A_i} \int_{A_j} g(y, x) dA_j dA_i$$

Geometric term – **form factor**  $F_{ij}$   
(part of energy irradiated from  $A_i$  received directly by  $A_j$ )

$$B_i = E_i + \rho_i \cdot \sum_{j=1}^N B_j F_{ij} \quad \left[ \frac{W}{m^2} \right]$$



# Intuitive derivation

$$B_i A_i = E_i A_i + \rho_i \cdot \sum_{j=1}^N B_j A_j F_{ji} \quad [w]$$

Emitted power = own power + reflected power

„Reciprocal rule“

$$A_j F_{ji} = A_i F_{ij}$$

$$B_i A_i = E_i A_i + \rho_i \cdot \sum_{j=1}^N B_j F_{ij} A_i \quad \Bigg| \cdot A_i^{-1}$$

$$B_i = E_i + \rho_i \cdot \sum_{j=1}^N B_j F_{ij} \quad \left[ \frac{W}{m^2} \right]$$



# System of linear equations

$$\underline{B_i} - \rho_i \cdot \sum_{j=1}^N \underline{B_j} F_{ij} = E_i \quad i = 1..N$$

$$\begin{bmatrix} 1 - \rho_1 F_{1,1} & -\rho_1 F_{1,2} & \dots & -\rho_1 F_{1,N} \\ -\rho_2 F_{2,1} & 1 - \rho_2 F_{2,2} & \dots & -\rho_2 F_{2,N} \\ \dots & \dots & \dots & \dots \\ -\rho_N F_{N,1} & -\rho_N F_{N,2} & \dots & 1 - \rho_N F_{N,N} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \dots \\ B_N \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \dots \\ E_N \end{bmatrix}$$

Vector of unknown vars  $[B_i]$



# System of linear equations

For **planar (convex) surfaces**:  $F_{ii} = 0$

- the diagonal contains only unit values

**Nondiagonal items** are usually very small (abs value)

- matrix is “diagonally dominant”

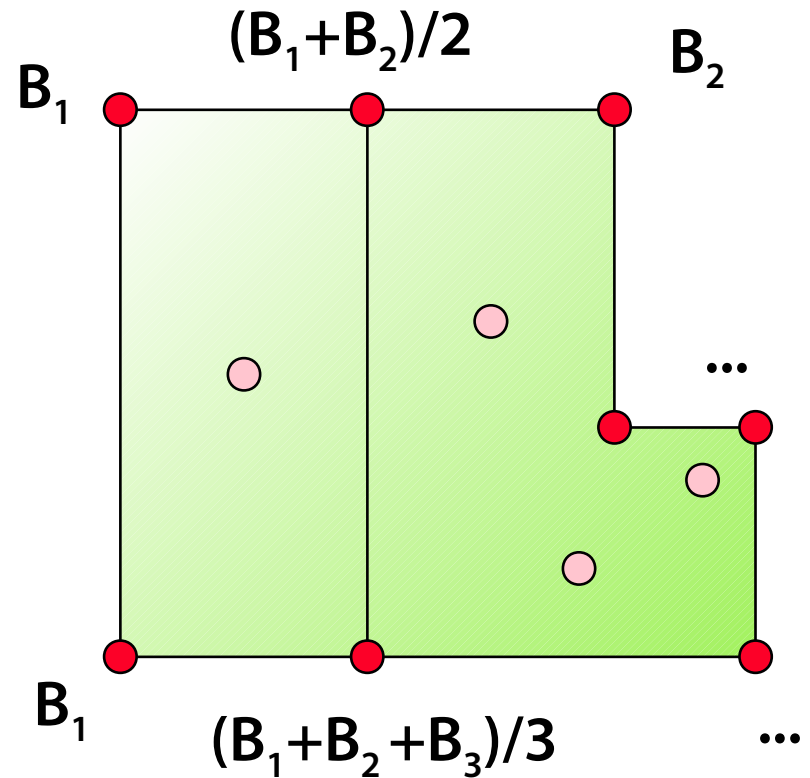
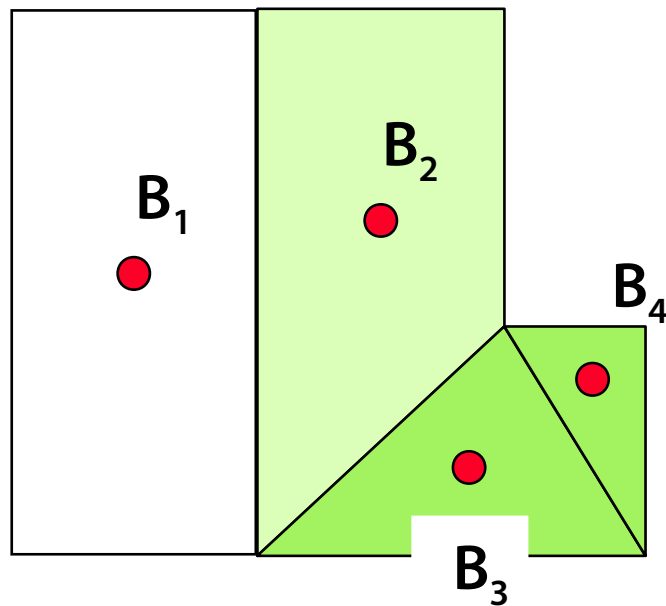
⇒ system is stable and can be solved by **iterative methods**  
(Jacobi, Gauss-Seidel)

For a **change of light (light sources)**  $[E_i]$  system needs not to be fully re-computed, only the reverse phase could be done



# Radiosity transfer to vertices

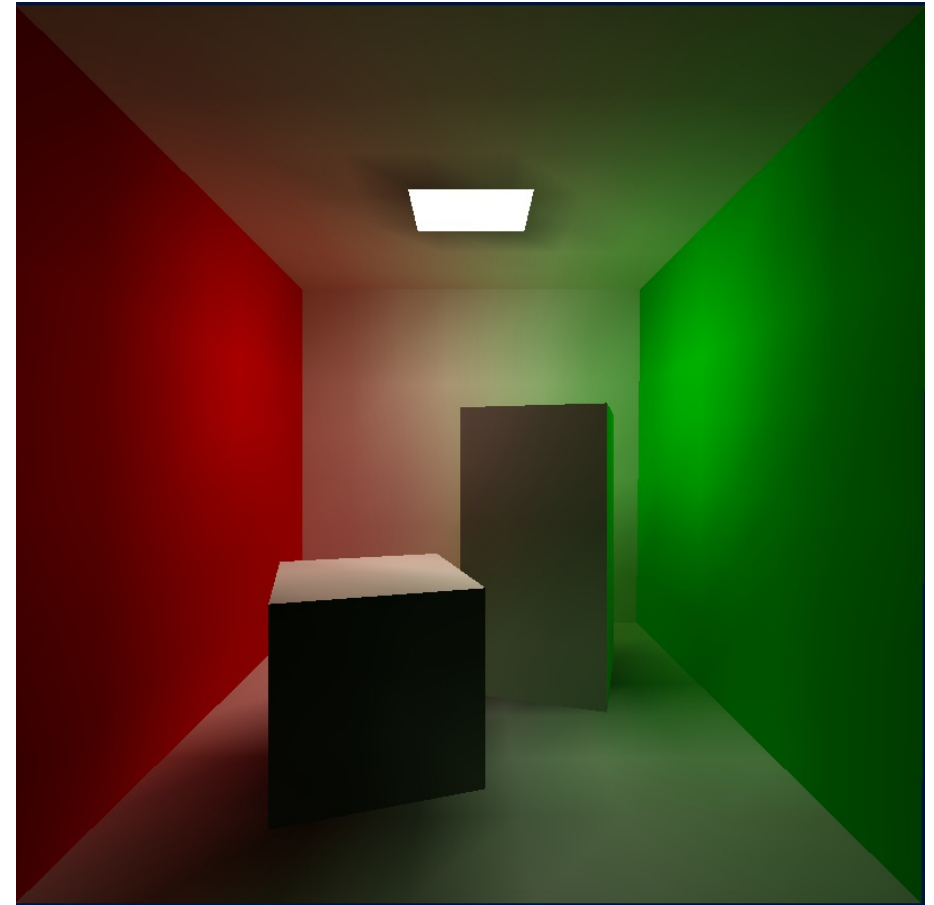
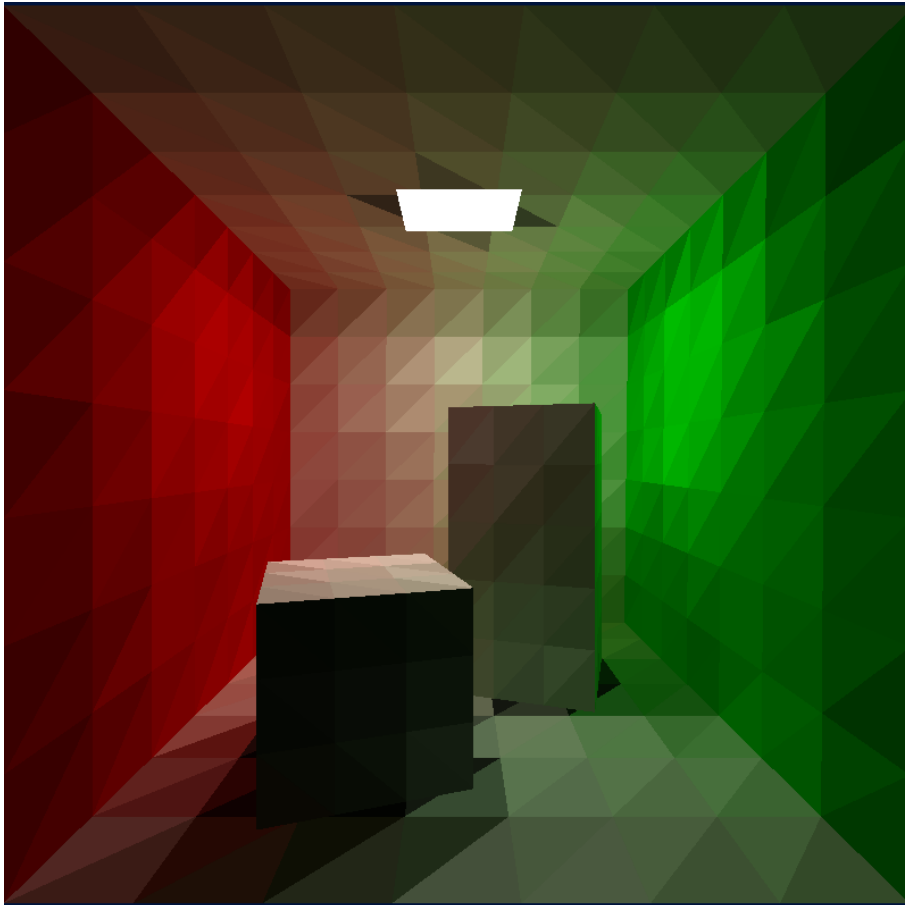
Even in constant element approach usage of some color interpolation method is recommended (**Gouraud**)







# Linear color interpolation





# References

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**C. M. Goral, K. E. Torrance, D. P. Greenberg, B. Battaile:** *Modeling the Interaction of Light Between Diffuse Surfaces*, CG vol 18(3), SIGGRAPH 1984

**A. Glassner:** *Principles of Digital Image Synthesis*, Morgan Kaufmann, 1995, 871-937

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**J. Foley, A. van Dam, S. Feiner, J. Hughes:** *Computer Graphics, Principles and Practice*, 793-804