



Interactive Synthesis of Constrained Motion from Example Movements

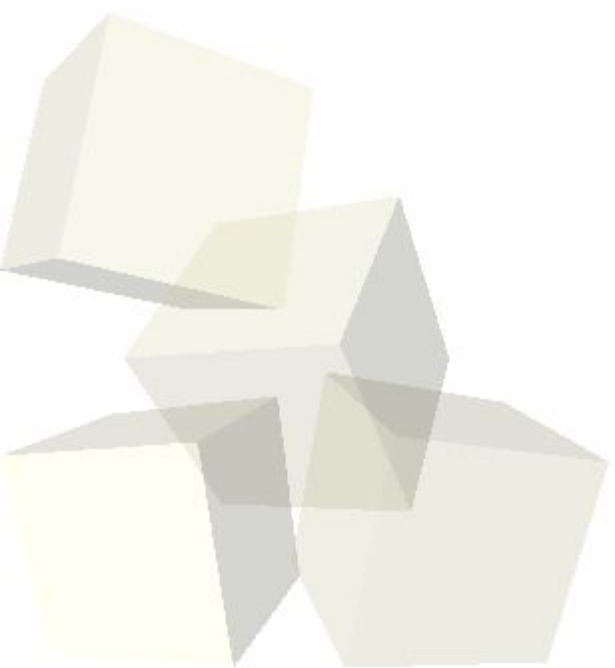
Jaroslav Semančík, Josef Pelikán, Jiří Žára

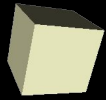
Charles University in Prague
Czech Republic

7. September 2004, Marbella



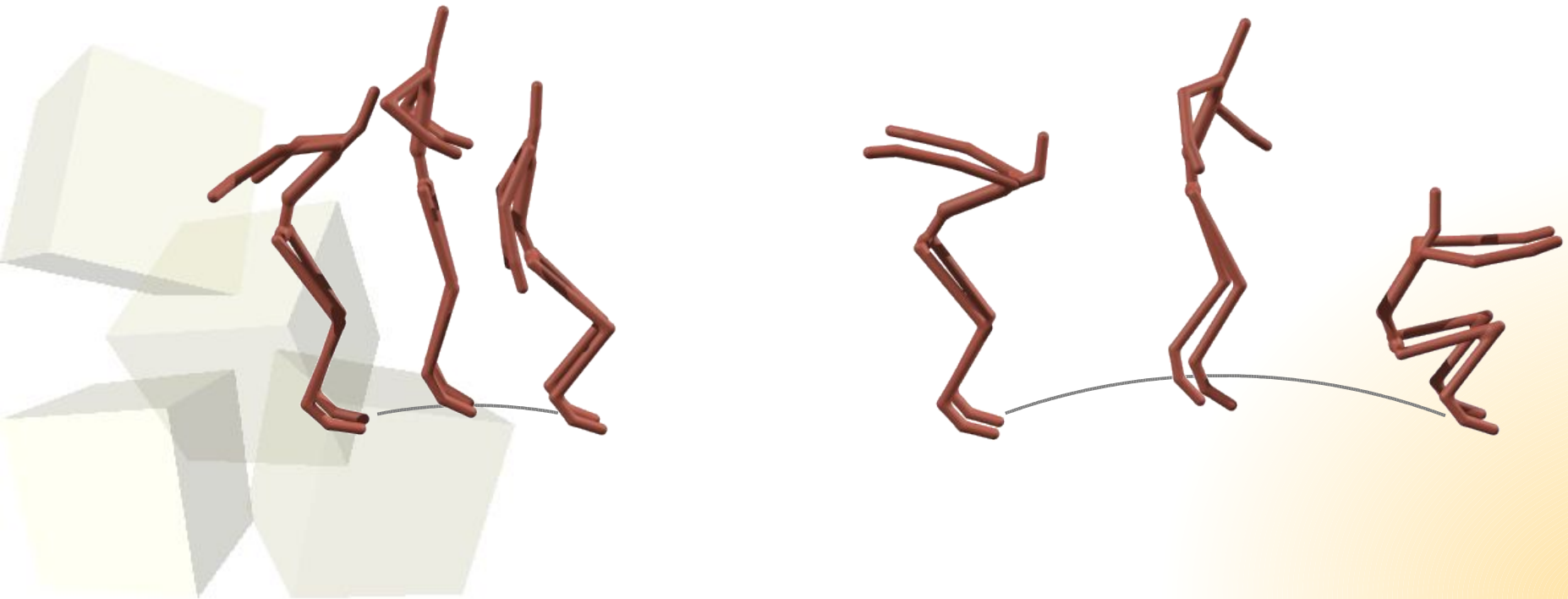
- Realistic motion of a human figure
- Motion capture
- Interactive virtual environments
- Motion library





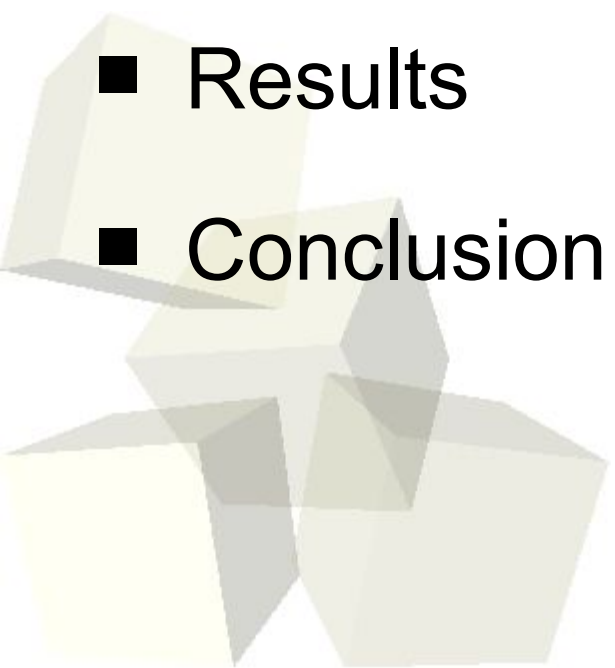
(2) Motivation

- Constraints – imposed by terrain or by user
- Parameterized movements
- How to generate realistic parametrized motion in real-time?





- Motion capture and blending
- Parameterized motion library
- Movement synthesis
- Continuous motion
- Results
- Conclusion and future work





- Real motion of a human body is recorded
- Source of the most realistic motion
- Set of marker trajectories

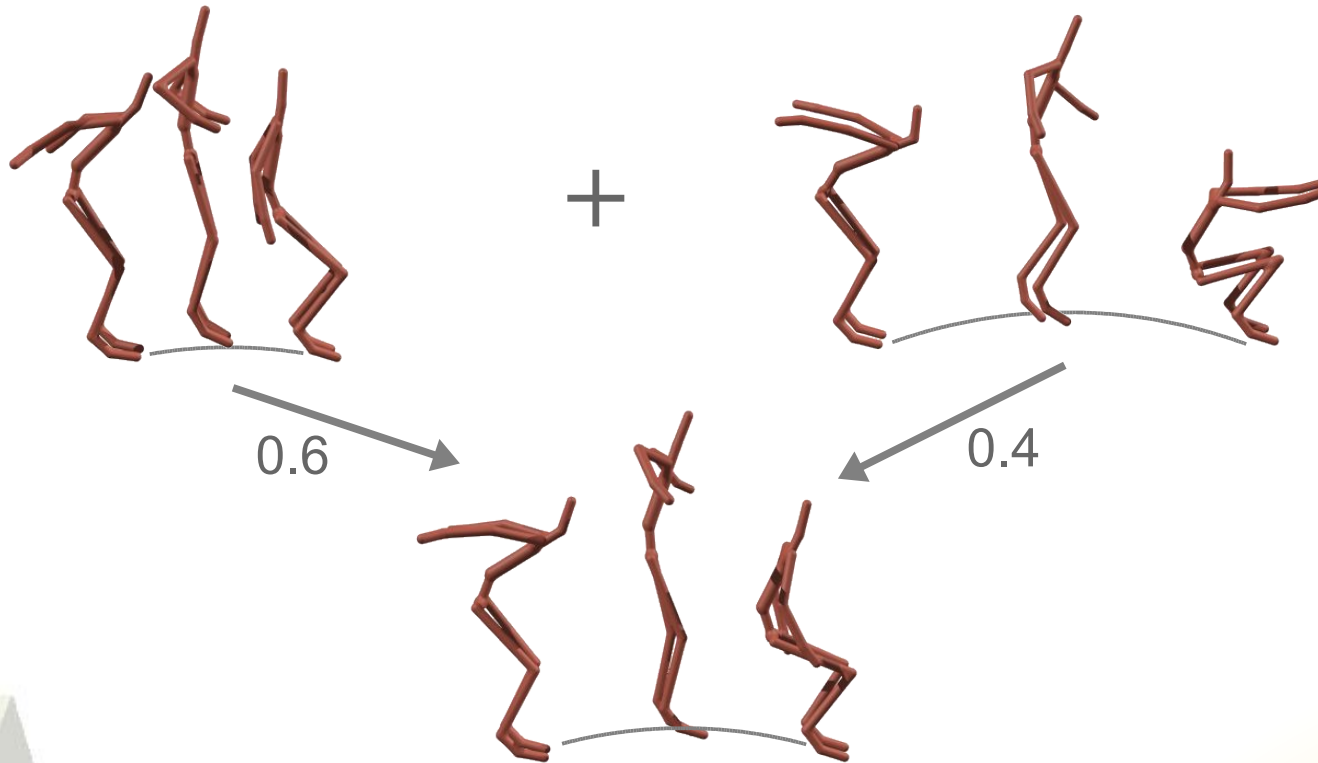
↓ postprocessing

- Motion of a virtual skeleton
- Only a record of a motion planned in advance





- New variations as a weighted sum

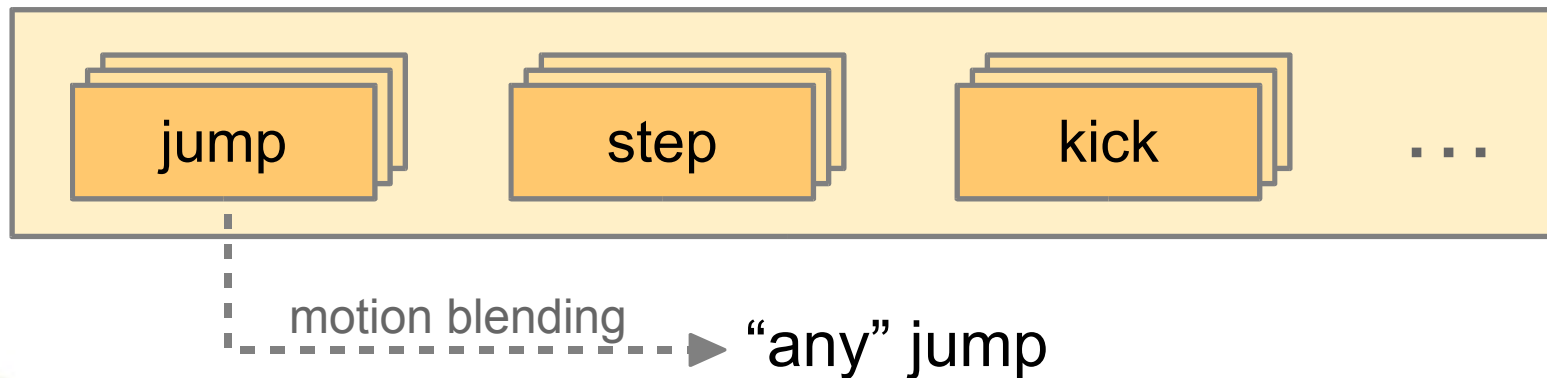


- Generally
$$\mathbf{M} = \sum_i w_i \mathbf{M}_i$$



Parameterized Motion Library

- Library of motion captured examples
- Several variations of each movement

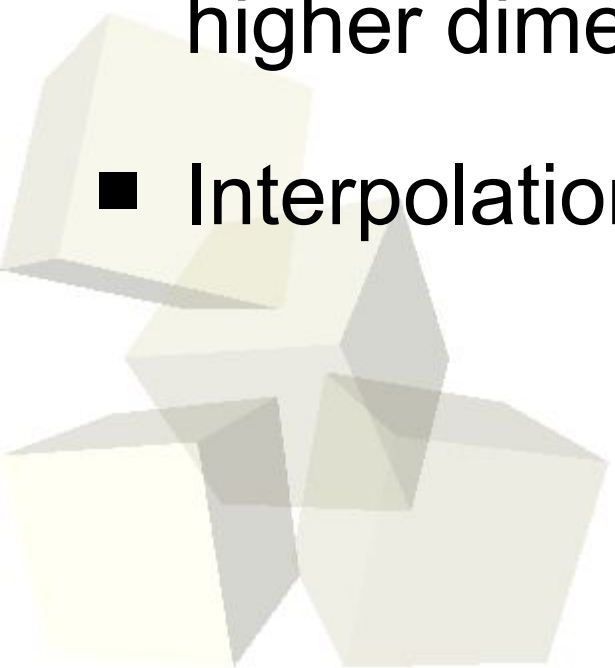


- How to specify a movement to create?
- By weights / by parameters



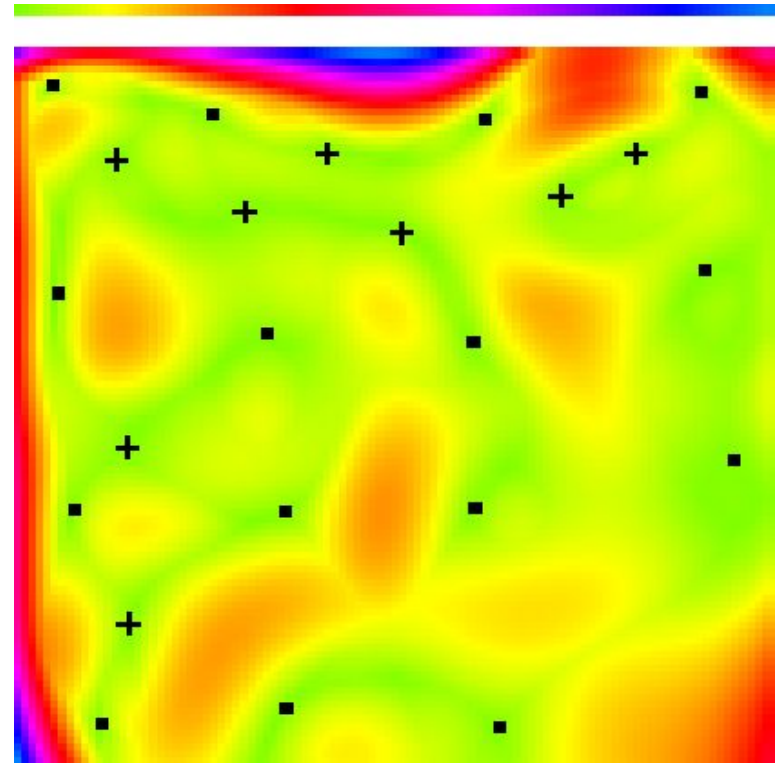
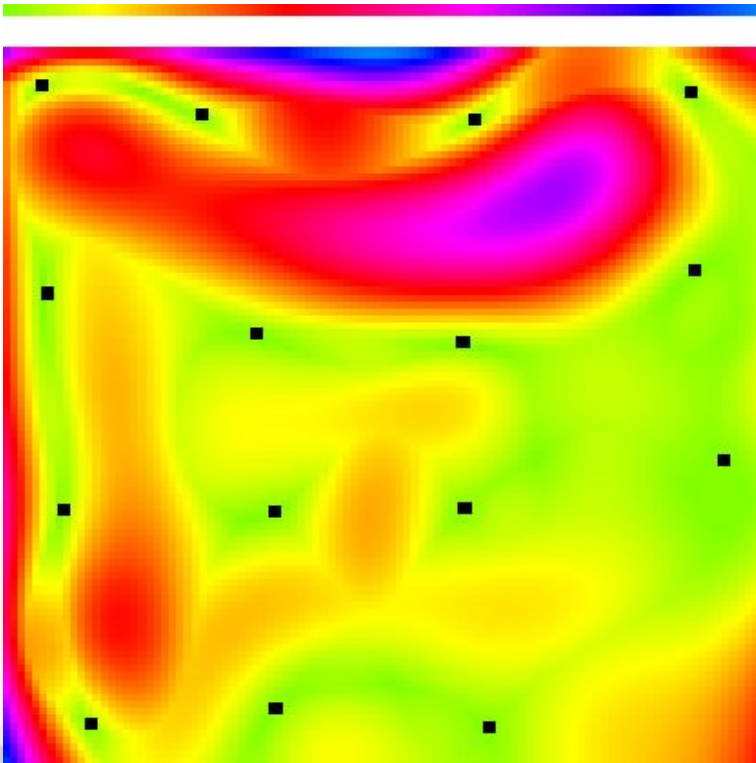
Movement Synthesis

- Task: Calculate weights for blending from given parameters.
- Multidimensional scattered interpolation in parameter space
- Using radial basis functions – well scalable to higher dimensions
- Interpolation error



Reduction of Interpolation Error

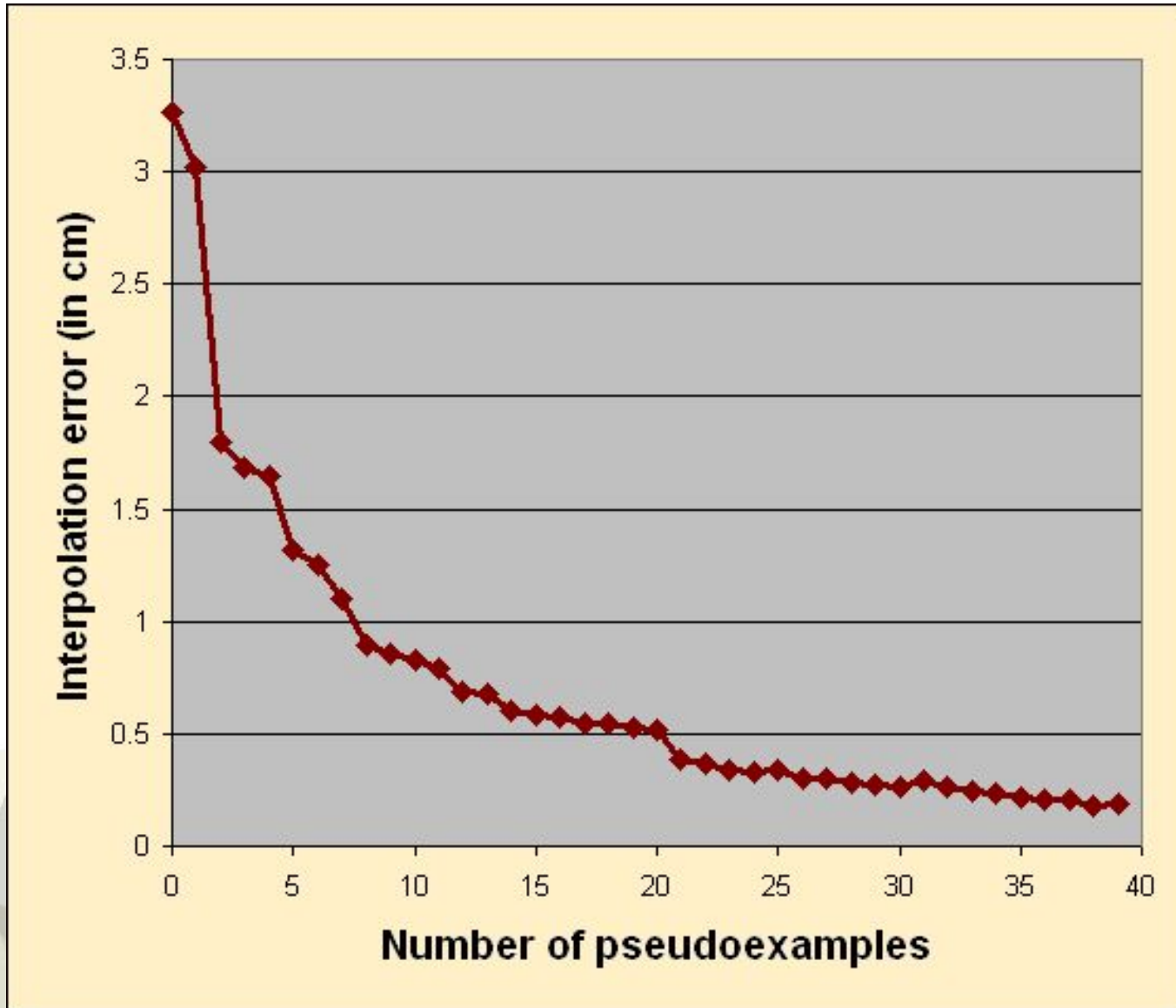
- Refinement by pseudoexamples



Interpolation error in parameter space, original vs. with added pseudoexamples.



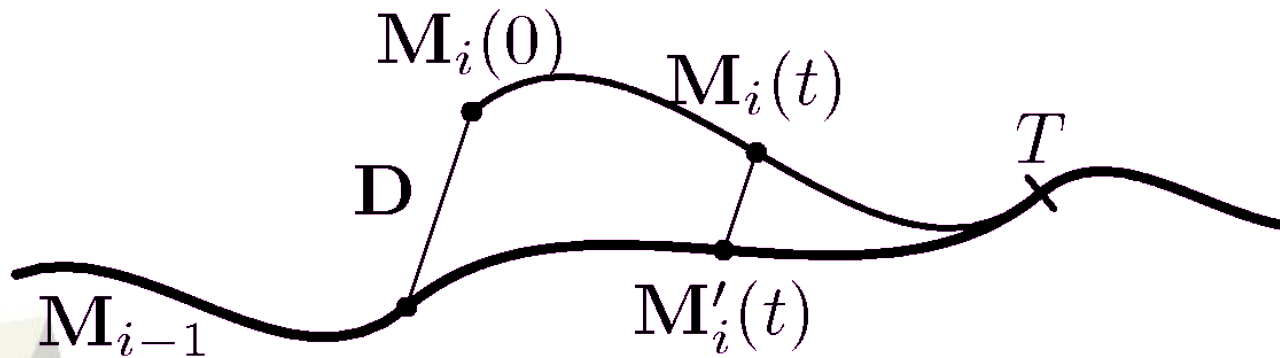
(2) Reduction of Interpolation Error





Continuous Motion

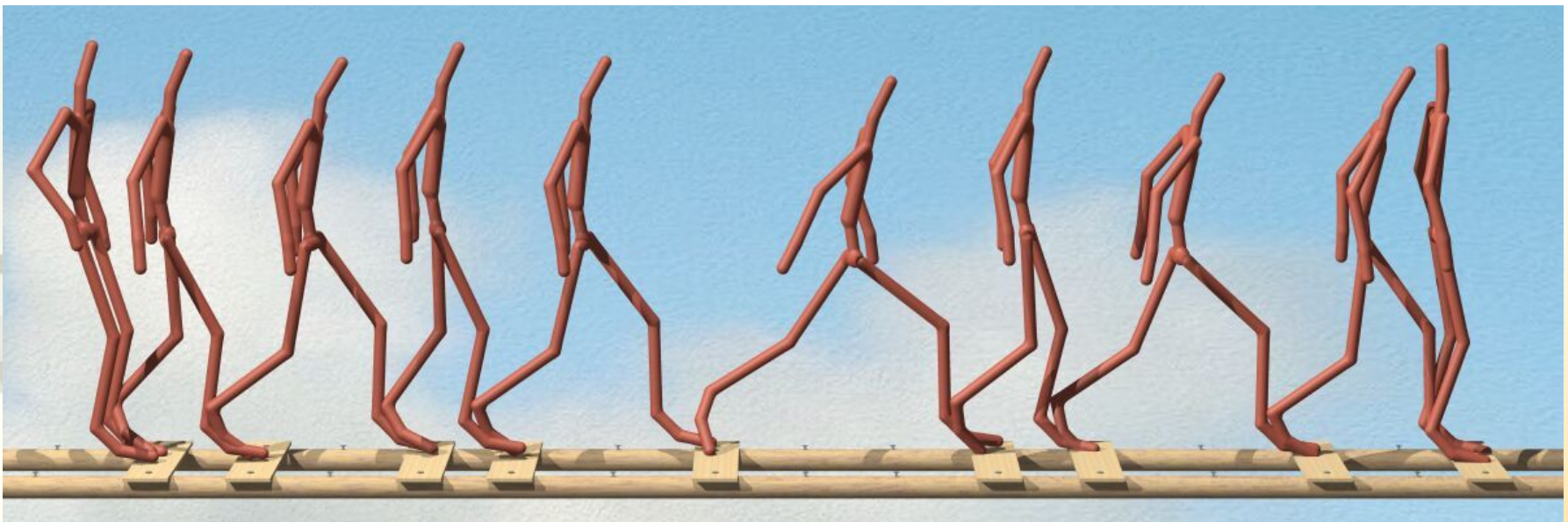
- Motion = sequence of movements
- Smooth movement transitions
- Postures in successive movements may differ

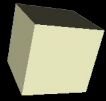


- Adjustment by eased-out “difference posture”



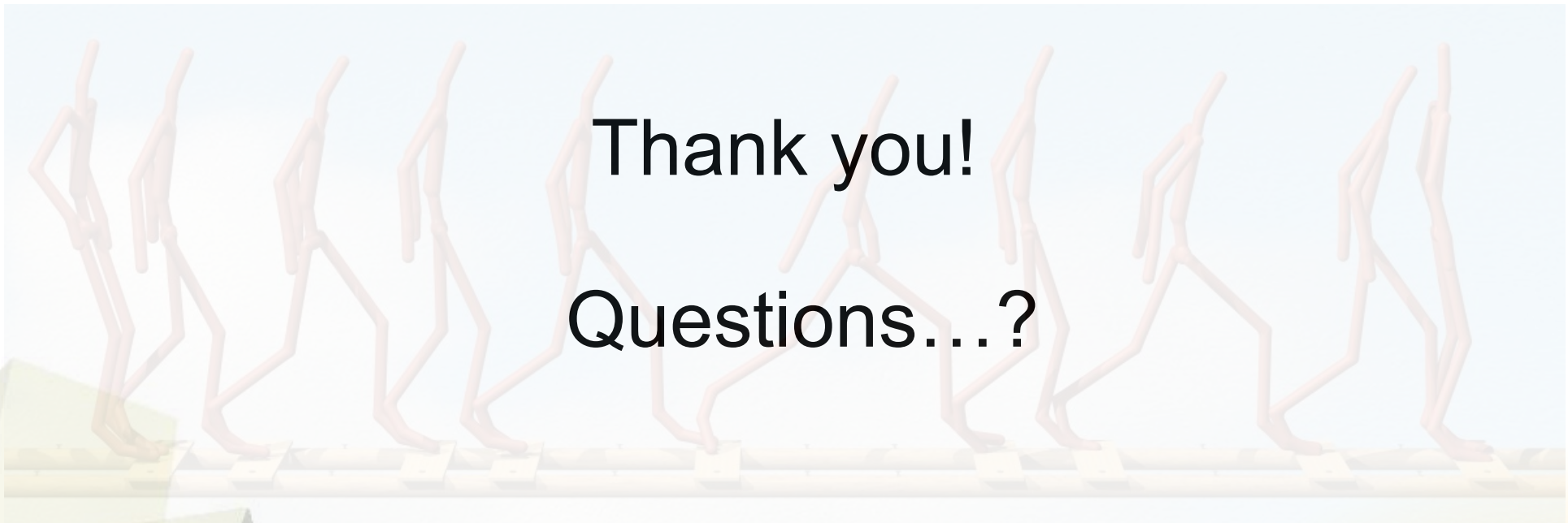
- Walk with variable length of a step
- 15 examples, library size ~320 KB
- Error <1cm, thousands of steps /sec.
- Foot sliding





Conclusion and Future Work

- Realistic parameterized motion
- Extremely high real-time performance
→ videogames
- Constraints on end-effectors needed
- Future work
 - Automatic choice of representative movement variations



Thank you!

Questions...?

