# Advanced 3D graphics for movies and games (NPGR010)

# - Multiple Importance Sampling

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Slides of prof. Jaroslav Křivánek, minor edits by Jiří Vorba

# **Sampling of environment lighting**



$$L_{\text{out}}(\omega_{\text{out}}) = \int_{H(\mathbf{x})} L_{\text{in}}(\omega_{\text{in}}) \cdot f_r(\omega_{\text{in}} \to \omega_{\text{out}}) \cdot \cos \theta_{\text{in}} \, \mathrm{d}\omega_{\text{in}}$$

# **Sampling of environment lighting**

BRDF IS 600 samples

MIS



Diffuse only

Ward BRDF,  $\alpha$ =0.2

Ward BRDF,  $\alpha$ =0.05

Ward BRDF,  $\alpha$ =0.01

# **Sampling of environment lighting**

- Two different sampling strategies for generating the incoming light direction ω<sub>in</sub>
  - **1. BRDF-proportional sampling -**  $p_a(\omega_{in})$
  - **2.** Environment map-proportional sampling  $p_{\rm b}(\omega_{\rm in})$

# What is wrong with using either of the two strategies alone?



## **Better strategy**

$$\frac{1}{2}p_a(x) + \frac{1}{2}p_b(x)$$



# **Example: Sum of two Gaussians**



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# Notes on the previous slides

- We have a complex multimodal integrand g(x) that we want to numerically integrate using a MC method with importance sampling. Unfortunately, we do not have a PDF that would mimic the integrand in the entire domain. Instead, we can draw the sample from two different PDFs,  $p_a$  and  $p_b$  each of which is a good match for the integrand under different conditions i.e. in different part of the domain.
- However, the estimators corresponding to these two PDFs have extremely high variance shown on the slide. We can use Multiple Importance Sampling (MIS) to combine the sampling techniques corresponding to the two PDFs into a single, robust, combined technique. The MIS procedure is extremely simple: sample from both techniques p<sub>a</sub> and p<sub>b</sub>, and then weight the samples appropriately.
- This estimator is really powerful at suppressing outlier samples such as those that you would obtain by picking *x*\_from the tail of *p<sub>a</sub>*, where g(*x*) might still be large. Without having *p<sub>b</sub>* at our disposal, the MC estimator would be dividing the large g(*x*) by the small *p<sub>a</sub>* (*x*), producing an outlier sample.
- The combined technique has a much higher chance of producing this particular *x* (because it can sample it also from  $p_b$ ), so the combined estimator divides g(x) by  $[p_a(x) + p_b(x)] / 2$ , which yields a much more reasonable sample value.
- I want to note that what I'm showing here is called the "balance heuristic" and is a part of a wider theory on weighted combinations of estimators proposed by Veach and Guibas.

# **Multiple Importance Sampling**

# Eric Veach [1997]

Sci-Tech Awards: Eric Veach

Scientific and Engineering Award **Eric Veach** for his foundational research on efficient Monte Carlo path tracing for image synthesis

# **Multiple Importance Sampling**

- Given *n* sampling techniques (i.e. pdfs)  $p_1(x), ..., p_n(x)$
- We take  $n_i$  samples  $X_{i,1}$ , ...,  $X_{i,n_i}$  from each technique
- Combined estimator

**Combination weights** 

(different for each sample)



# Unbiasedness of the combined estimator

The MIS estimator is unbiased...

$$E[F] = \dots = \int \left[\sum_{i=1}^{n} w_i(x)\right] f(x) \, \mathrm{d}x \equiv \int f(x)$$

... provided the weighting functions sum up to 1

$$\forall x: \qquad \sum_{i=1}^n w_i(x) = 1$$

# **Choice of the weighting functions**

- **Objective:** minimize the variance of the combined estimator
- 1. Arithmetic average (very bad combination)

$$w_i(x) = \frac{1}{n}$$

## 2. Balance heuristic (very good combination)

••••

# **Balance heuristic**

Combination weights

$$\hat{w}_i(\mathbf{x}) = \frac{n_i p_i(\mathbf{x})}{\sum_k n_k p_k(\mathbf{x})}$$

# MIS estimator with the Balance heuristic

Plugging Balance heuristic weights into the MIS formula

$$F = \sum_{i=1}^{n} \sum_{j=1}^{n_i} \frac{f(X_{i,j})}{\sum_k n_k p_k(X_{i,j})},$$

- The contribution of a sample does not depend on which technique (pdf) it came from
- Effectively, the sample is drawn from a weighted average of the individual pdfs – as can be seen from the form of the estimator

# **Balance heuristic**

• The balance heuristic **is almost optimal** [Veach 97]

- No other weighting has variance much lower than the balance heuristic
- Our work
   [Kondapaneni et al. 2018] revises MIS
  - If you allow negative weights, one can improve over the balance heuristic a lot

#### **Optimal Multiple Importance Sampling**

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Fig. 1. Equal-sample comparison (20 per technique per pixel) of direct illumination estimated by an MIS combination of two light sampling techniques (Trained and Unform, see Sec. 8.2 for details) with our optimal weights (top row) and the power heuristic (bottom row). The faste-color images b) show per pixel average MIS weight values as determined by the two weighting strategies. Unlike any of the existing MIS weighting heuristics, the optimal weights can have negative values, which provides additional opportunity for variance reduction, leading to an overall 9.6 times lower error per sample taken than the power heuristic in this scene.

Multiple Importance Sampling (MIS) is a key technique for achieving cobatteness of Monte Carlo estinators in computer graphics and other fields. We derive optimal weighting functions for MIS halt provably minimize the straince of an MIS estimator, given a set of sampling technologies. We show that the resulting variance relations over the balance heuristic can be higher assumed only nov engative weights in their proof. We theoretically analygical constraints and the strain of the strain of the straints by the variance of the optimal MIS weights and show the relation to the variance of the haltence heuristic. Furthermore, we establish is ningeraphelo of nontine angular, We apply the new optimal weights in integraconsiderations when choosing the appropriate sampling techniques for a given integration problem.

horn' addresses: Ivo Kondapaneni, Charlen University, Pragne: Petr Vevola, Charles versity, Pagge, Bender Legins, a. s. Pragne; Davad Gristmann, Sauland University Hordoens, Tomis Stavan BJ Anatrika, Vennae, Philipp Shaulah, Sauland University, Articlesen, DHS, Saudruicken, Javolak Wrivinske, Charles University, Pragne, Render Sondapaneni and Petr Vévola share the first authorship of this work.  $CCS\ Concepts: \bullet\ Mathematics\ of\ computing\ \to\ Probability\ and\ statistics; \bullet\ Computing\ methodologies\ \to\ Rendering.$ 

Additional Key Words and Phrases: Monte Carlo integration, Multiple Importance Sampling, combined estimators

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#### 1 INTRODUCTION

Monte Carlo (MC) integration is an essential tool in light transport simulation (Pharet el. 2106; Vacch 1997) and other fields of science and engineering (Eslos and Whitlock 2008). An inherent problem of MC integration is its solve overvegrence, which is why numerous variance reduction schemes have been proposed, notably importance sampling. Its extension, known as multiple importance sampling (MDS) [Vacch and Guibas 1995], is particularly versatile as it enables combining different sampling technicus in a robust wav

# MIS for direct illumination from enviro lights

# **Application of MIS to environment light sampling**

- Recall: Two sampling strategies for generating the incident direction ω<sub>i</sub>
  - **1. BRDF-proportional sampling -**  $p_a(\omega_{in})$
  - **2.** Environment map-proportional sampling  $p_{\rm b}(\omega_{\rm in})$
- Plug formulas for  $p_a(\omega_{in})$  and  $p_b(\omega_{in})$  into the general MIS formulas above

# **Direct illumination: Two strategies**

- Which strategy should we choose?Both!
- Both strategies estimate the same quantity L<sub>out</sub>(**x**, ω<sub>out</sub>)
   A mere sum would estimate 2 × L<sub>out</sub>(**x**, ω<sub>out</sub>), which is wrong
- We need a weighted average of the techniques, but how to choose the weights? → MIS

# **MIS weight calculation**

MIS weight for a sample direction generated by BRDF lobe sampling



• Here, we assume one sample from each of the two strategies

# **MIS for enviro sampling – Algorithm**

```
Vec3 omegaInA = generateBrdfSample();
float pdfA = evalBrdfPdf(omegaInA);
float pdfAsIfFromB = evalEnvMapPdf(omegaInA);
float misWeightA = pdfA / (pdfA + pdfAsIfFromB);
Rqb outRadianceEstimate = misWeightA *
       incRadiance(omegaInA) *
       brdf(omegaOut, omegaInA) *
       max(0, dot(omegaInA, surfNormal) / pdfA;
Vec3 omegaInB = generateEnvMapSample();
float pdfB = evalEnvMapPdf(omegaInB);
float pdfAsIfFromA = evalBrdfPdf(omegaInB);
float misWeightB = pdfB / (pdfB + pdfAsIfFromA);
outRadianceEstimate += misWeightB *
       incRadiance(omegaInB) *
       brdf(omegaOut, omegaInB) *
       max(0, dot(omegaInB, surfNormal) / pdfB;
```

# **MIS applied to enviro sampling**

BRDF IS 600 samples

MIS



Diffuse only

Ward BRDF,  $\alpha$ =0.2

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Ward BRDF,  $\alpha$ =0.01

# MIS for direct illumination from area lights

# **Area light sampling – Motivation**



#### Sampling technique (pdf) p<sub>a</sub>: BRDF sampling

Sampling technique (pdf) p<sub>b</sub>: Light source area sampling Image: Alexander Wilkie

# **Recall: Irradiance estimate and G** term

Reformulate the reflection integral (change of variables)

$$E(\mathbf{x}) = \int_{H(\mathbf{x})} L_{i}(\mathbf{x}, \omega_{i}) \cdot \cos \theta_{i} \, d\omega_{i}$$
  
= 
$$\int_{A} L_{e}(\mathbf{y} \rightarrow \mathbf{x}) \cdot V(\mathbf{y} \leftrightarrow \mathbf{x}) \cdot \frac{\cos \theta_{y} \cdot \cos \theta_{x}}{\|\mathbf{y} - \mathbf{x}\|^{2}} \, dA$$

• PDF for uniform sampling of the surface area:

$$p(\mathbf{y}) = \frac{1}{|A|}$$

# **MIS-based combination**



**Arithmetic average** Preserves **bad** properties of both techniques MIS w/ the balance heuristic Bingo!!!

# Area light sampling – Classic Veach's example



#### BRDF proportional sampling

#### Light source area sampling

# **MIS-based combination**

### Multiple importance sampling & Balance heuristic (Veach & Guibas, 95)



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# **Direct illumination: Two strategies**

## BRDF proportional sampling

- Better for large light sources and/or highly glossy BRDFs
- The probability of hitting a small light source is small -> high variance, noise

## Light source area sampling

- Better for smaller light sources
- It is the only possible strategy for point sources
- For large sources, many samples are generated outside the BRDF lobe -> high variance, noise

# **Example PDFs**

## BRDF sampling: p<sub>a</sub>(ω)

- Depends on the BRDF, e.g. the formulas for physicallybased Phong BRDF from the last lecture
- Light source area sampling: p<sub>b</sub>(ω)

$$p_b(\omega) = \frac{1}{|A|} \frac{||\mathbf{x} - \mathbf{y}||^2}{\cos \theta_{\mathbf{y}}}$$
Conversion of the uniform pdf 1/|A|  
from the area measure (dA) to the solid  
angle measure (d\omega)

# **Contributions of the sampling techniques**



#### w<sub>a</sub> \* BRDF sampling

w<sub>b</sub> \* light source area sampling

# **Alternative MIS heuristics**

# **Alternative combination heuristics**

## • "Low variance problems"

 Whenever one sampling technique yields a very low variance estimator, balance heuristic can be suboptimal



(a) Sampling the BSDF

(b) Sampling the lights

(c) The balance heuristic

# **Alternative combination heuristics**

## • "Low variance problems"

- Whenever one sampling technique yields a very low variance estimator, balance heuristic can be suboptimal
- "Power heuristic" or other heuristics can be better in such a case – see next slide





(a) The balance heuristic.









(b) The cutoff heuristic ( $\alpha = 0.1$ ).





# **Other examples of MIS applications**

In the following we apply MIS to combine full path sampling techniques for calculating light transport in participating media.

## **Full transport**

#### rare, fwd-scattering fog

#### back-scattering high albedo

#### back-scattering

# **Medium transport only**



#### Beam-Beam 1D (=photon beams)



#### Point-Beam 2D (=BRE)







#### Beam-Beam 1D

#### Point-Beam 2D



# Bidirectional PT





#### Point-Beam 2D



Bidirectional PT

# UPBP (our algorithm) 1 hour