

Image warping – deformations

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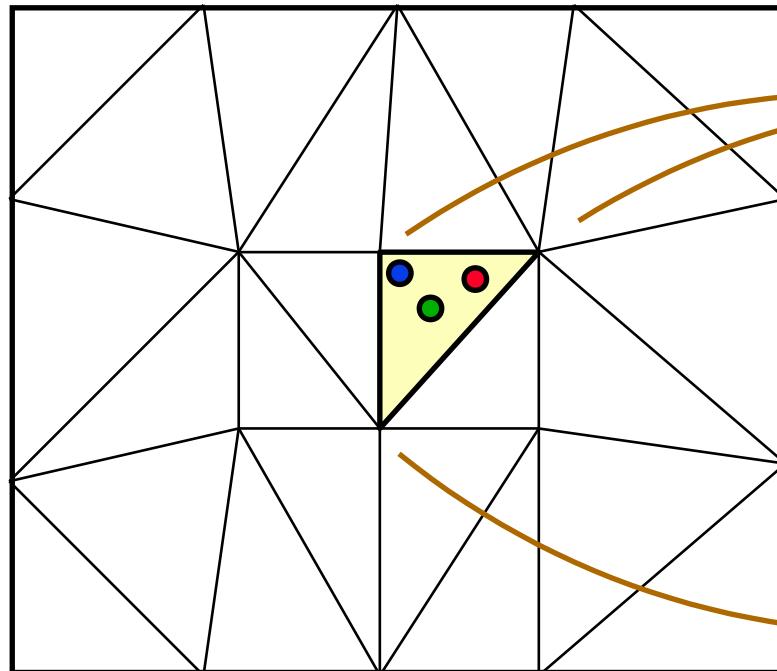


Deformation mapping

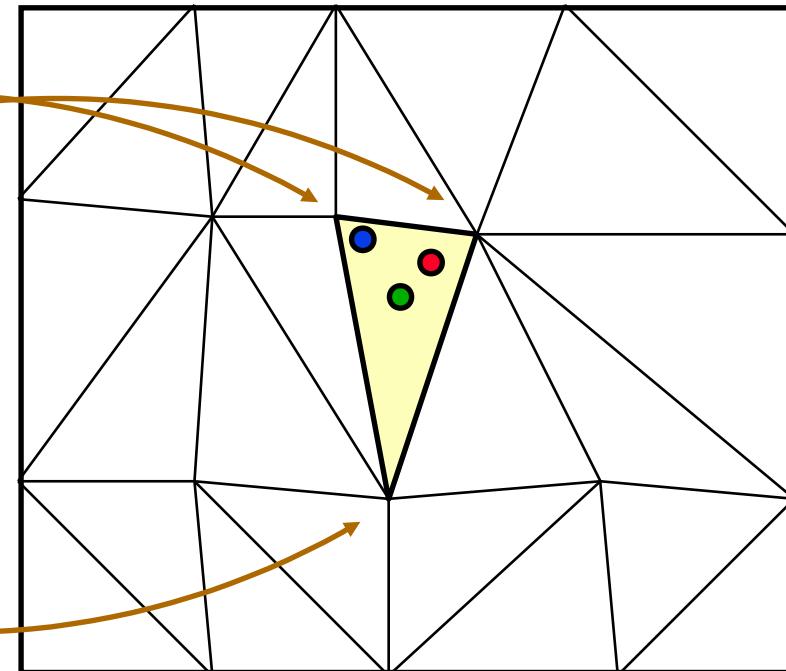
- ◆ **explicit, analytic function**
 - 3D graphics: texture mapping (surface of a solid), perspective distortion..
 - global deformation function
- ◆ **free-form functions**
 - interactive (user, GUI)
 - image space covered by function elements / handles / control points
 - change of one element has only local impact



Triangle mesh



source

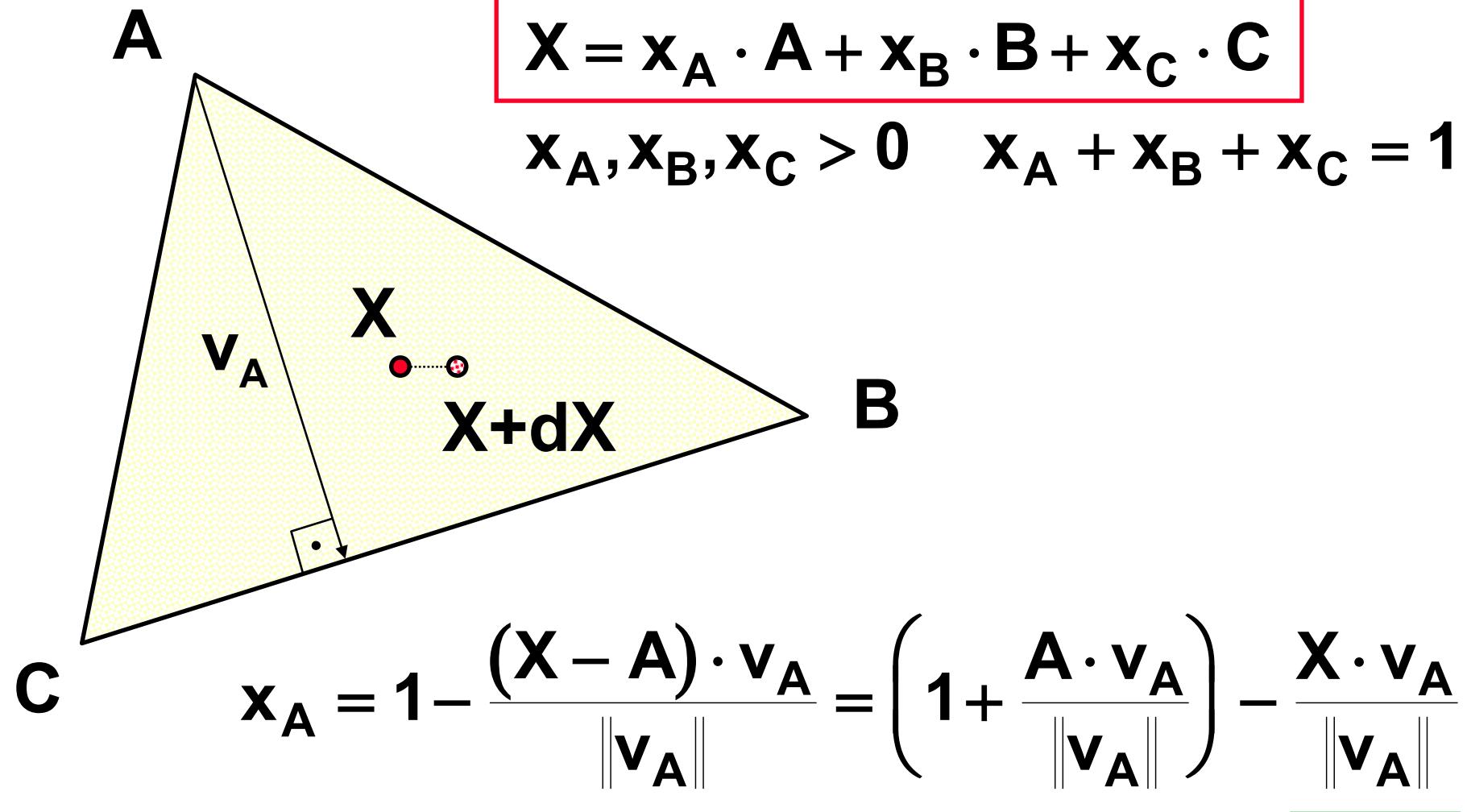


target

Identical mesh topology!



Barycentric coordinates



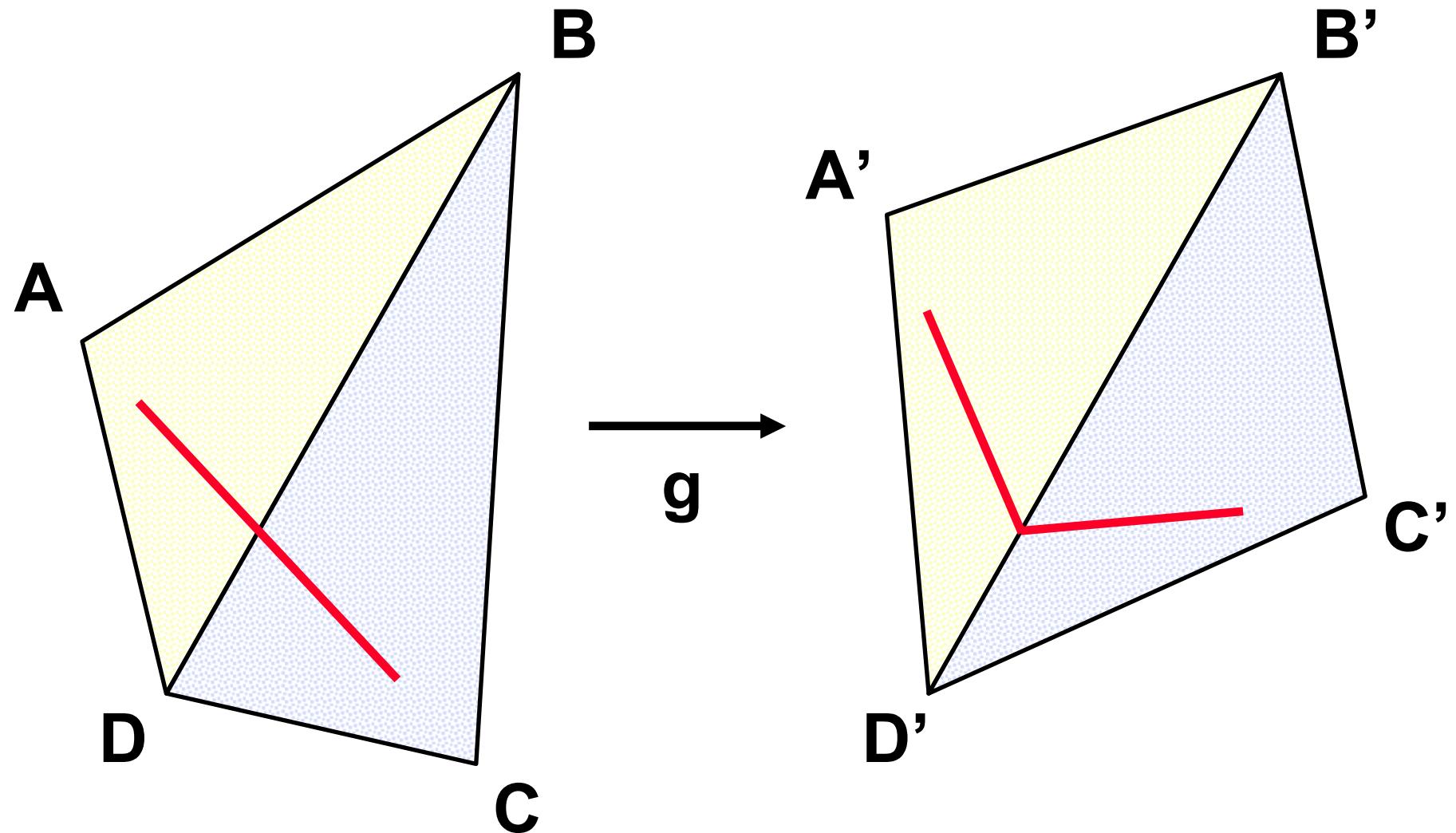


Algorithm

- ◆ **scanline pass through target image**
 - barycentric coordinates are linear inside a triangle
(finite difference method)
- ◆ **list of sorted triangle edges**
 - crossing the edge .. changing triangles
- ◆ **next scanline**
 - delete ending edges
 - update continued edges
 - insert starting edges (consequent on ending ones)



Discontinuity (1st order)



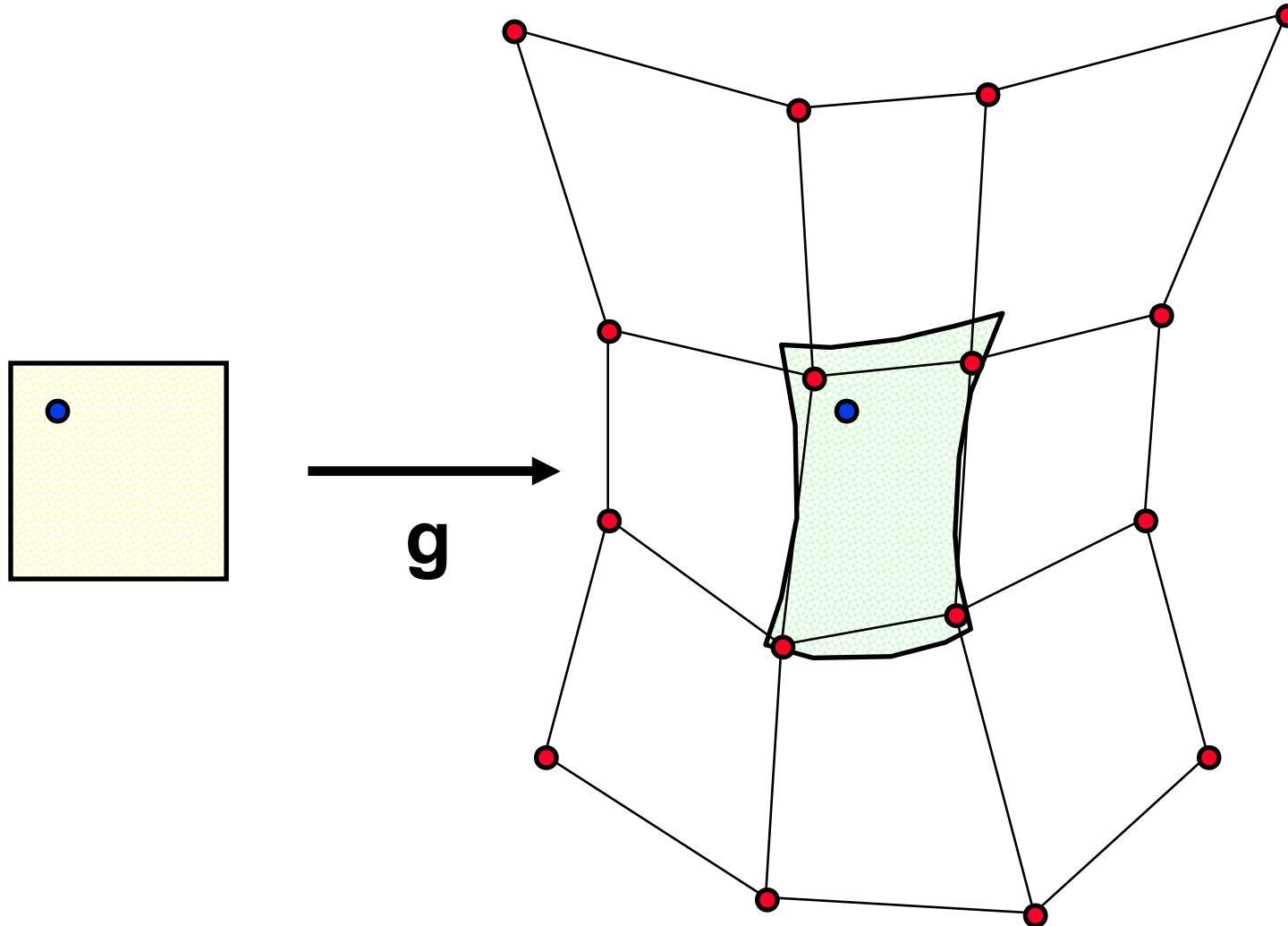


Higher-order approximations

- ◆ **quadratic or cubic interpolation**
 - continuity: 1st and 2nd derivatives (C^1, C^2)
- ◆ **triangle or quad topology**
 - need to know adjacent cells
- ◆ **inverse mapping** can be tricky
 - alternative approach ($\mathbf{g}^{-1} = \mathbf{g}_1 \circ \mathbf{g}_2^{-1}$)



Bicubic B-spline approximation





Bicubic B-spline approximation

$$g(u, v) = \sum_{i=0}^3 \sum_{j=0}^3 C_i(u) C_j(v) P_{ij}$$

B-spline
blending functions:

$$C_0(t) = \frac{1}{6}(1-t)^3$$

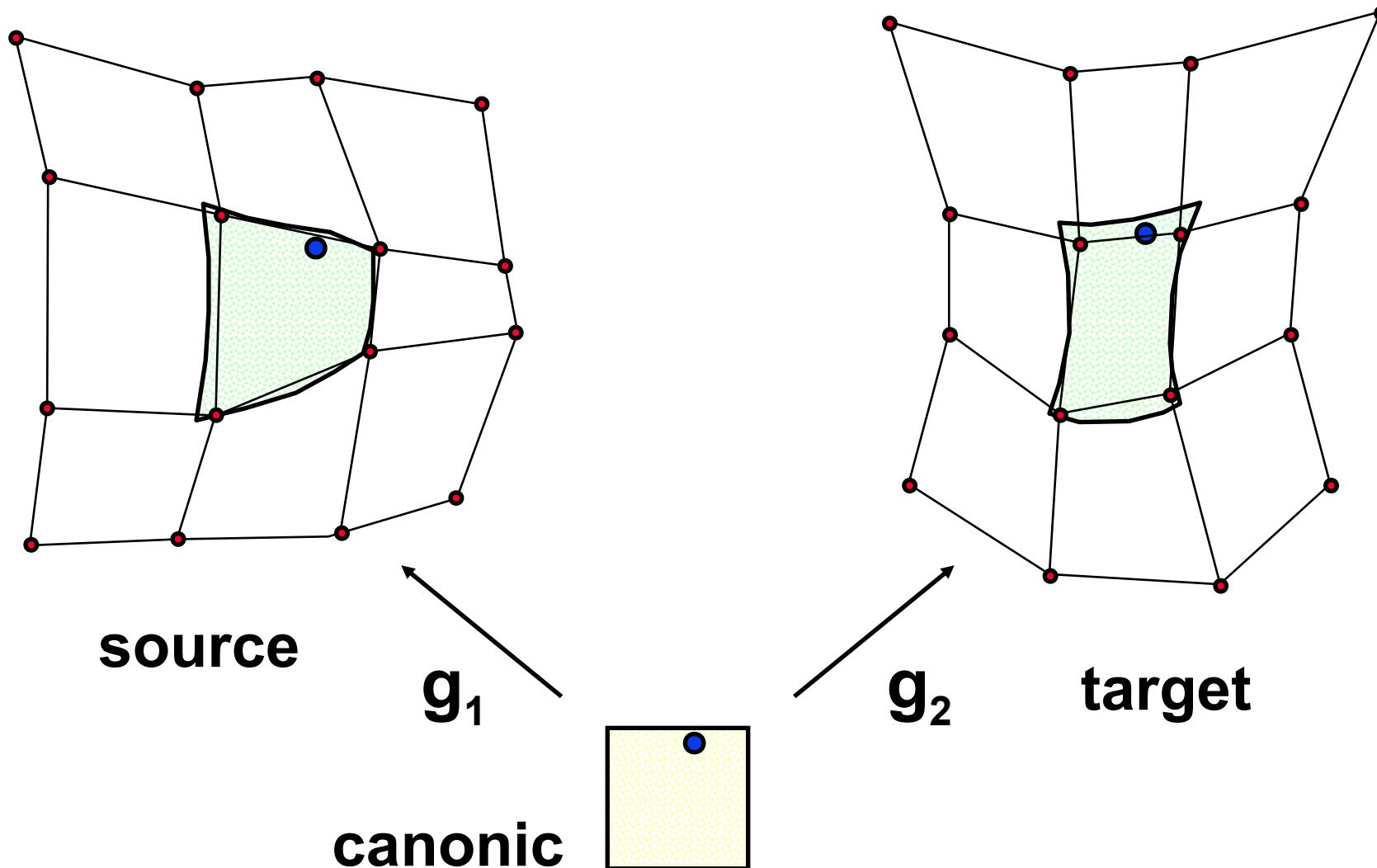
$$C_1(t) = \frac{1}{6}(3t^3 - 6t^2 + 4)$$

$$C_2(t) = \frac{1}{6}(-3t^3 + 3t^2 + 3t + 1)$$

$$C_3(t) = \frac{1}{6}t^3$$



Both nets are editable



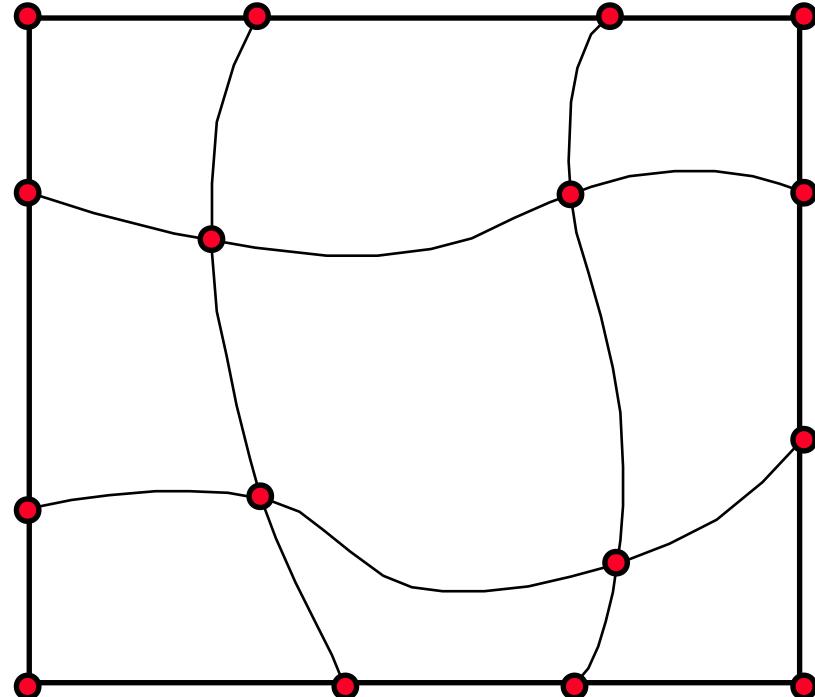


Dual-net algorithm

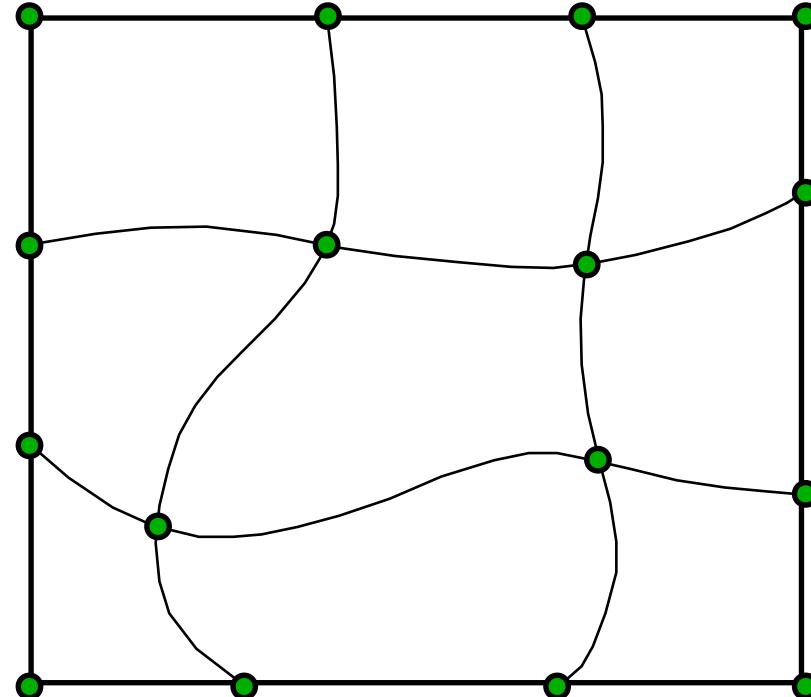
- ◆ only **forward mappings g_i** can be implemented efficiently (finite differences)
 - integer algorithm uses only addition and bit shifts in its inner loop
- concurrent **synchronous comput.** of g_1 and g_2
 - coverage-condition (every pixel of the target image has to be covered)
- **source pixels** are transferred using $g_2 \circ g_1^{-1}$
 - or opposite direction in case of filtering



Spline net



source



target

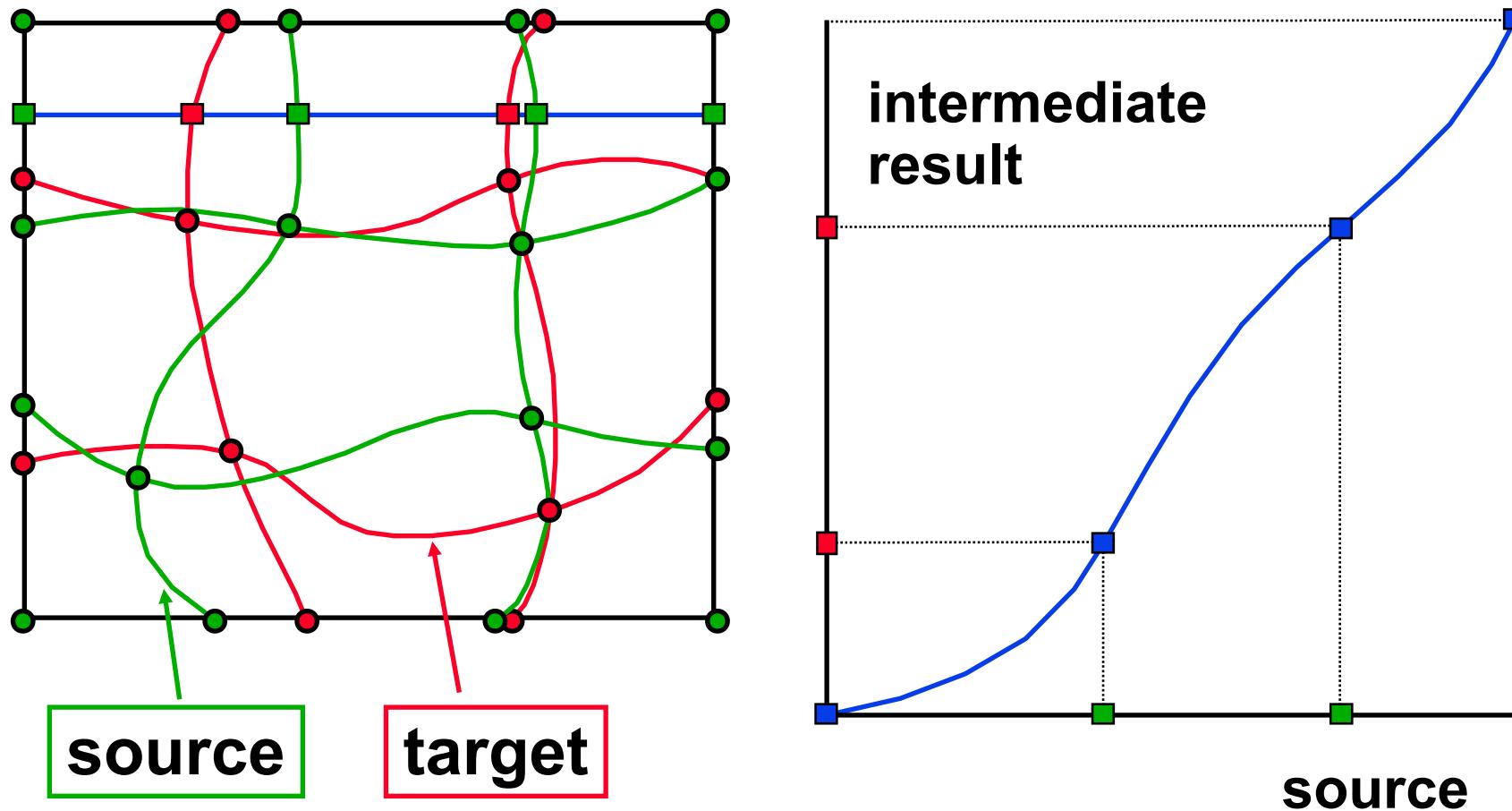


Two-pass algorithm

- **horizontal deformation** (each pixel row)
 - vertical spline curves intersect scanline ... control points for spline interpolation
 - horizontal splines has to be deformed as well
- **vertical deformation** (each pixel column)
 - defined by intersections of modified horizontal spline curves with vertical line



Horizontal phase – example

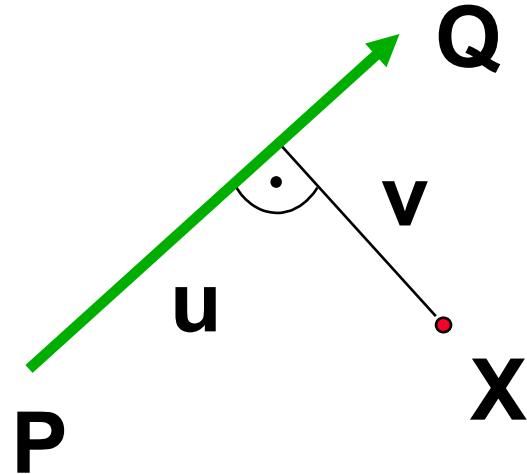




„Feature-based” warping

- ◆ **local deformation function**
 - user friendly, intuitive
 - no need to cover constant areas
- ◆ **matching pairs of oriented segments** (arrows, „features”)
 - each feature has only limited influence
- ◆ **additional numeric parameters**
 - global or feature-specific
 - feature „strength“, influence radius, etc.

One feature ... affine transform



$$u = \frac{(X - P) \cdot (Q - P)}{\|Q - P\|^2} \quad (\text{rel})$$
$$v = \frac{(X - P) \cdot (Q - P)^\perp}{\|Q - P\|} \quad (\text{abs})$$

Backward mapping:

$$X' \rightarrow [u', v'] = [u, v] \rightarrow X$$

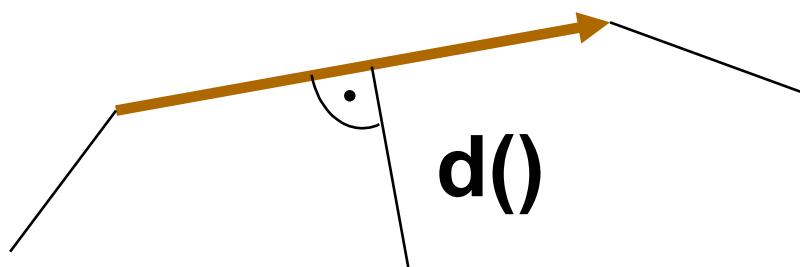
More features – radial interpolation

Weighting coefficient: $w = \left[\frac{(Q' - P')^p}{a + d(P', Q', X')} \right]^b$

a accuracy on the features

b descend coefficient

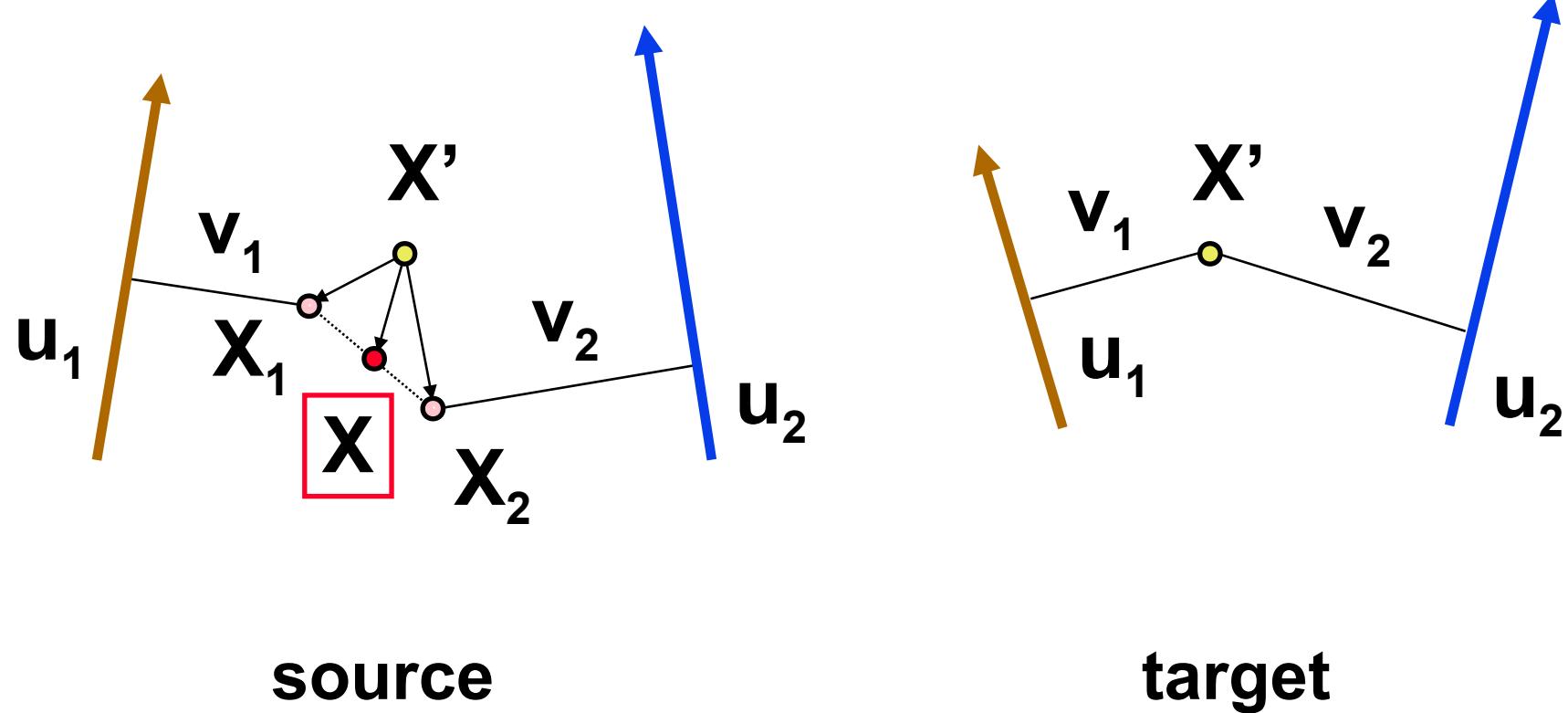
p influence of feature-length



$$X = X' + \frac{\sum w_i \cdot (X_i - X')}{\sum w_i}$$



More features – example





Feature layout

- ◆ source and target features should have „**equal topology**“
 - „image folding“ (non-continuous mapping)
- ◆ **features should not cross**
- ◆ if features must **touch**, it should happen in equivalent points
 - otherwise „ghosts“ could appear..
(„Don't cross the streams.“ - „Why?“ - „It would be bad“)



The End

More info:

- J. Gomes et al.: *Warping and Morphing of Graphical Objects*, C.N., SIGGRAPH'95
- T. Beier, S. Neely: *Feature-Based Image Metamorphosis*, SIGGRAPH'92