



# Recursive Ray Tracing

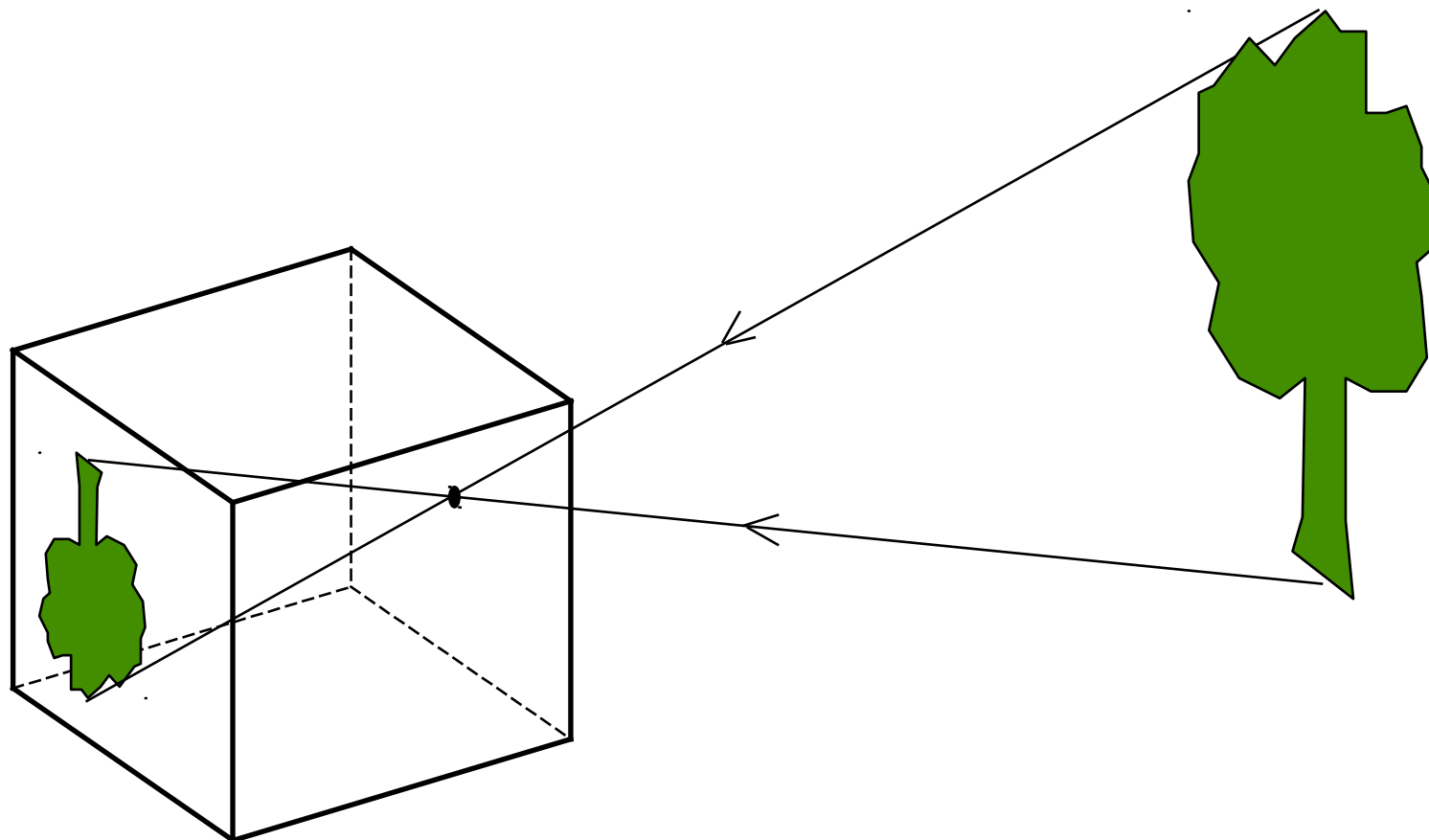
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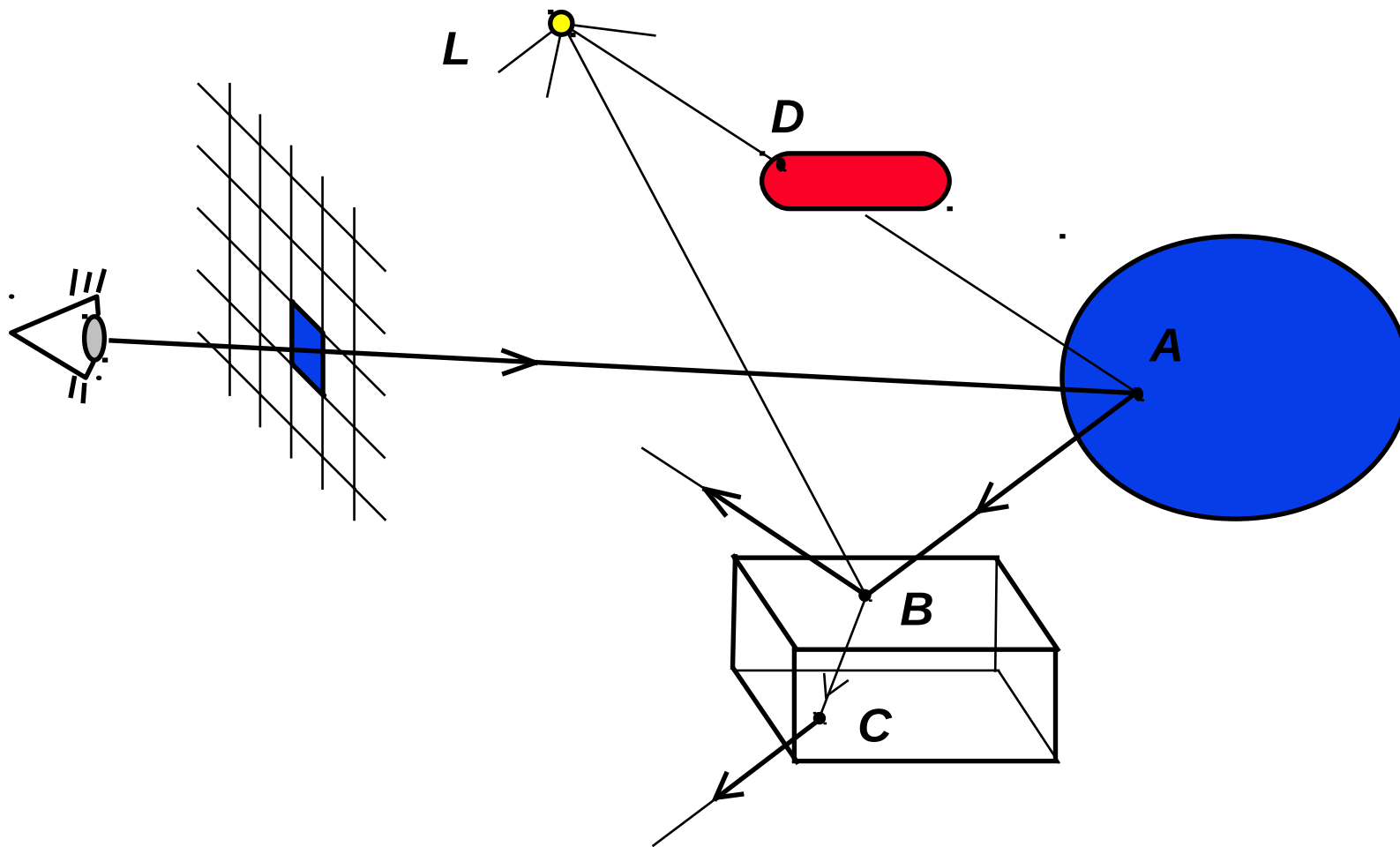
<http://cgg.mff.cuni.cz/~pepca/>



# Pinhole Camera Model

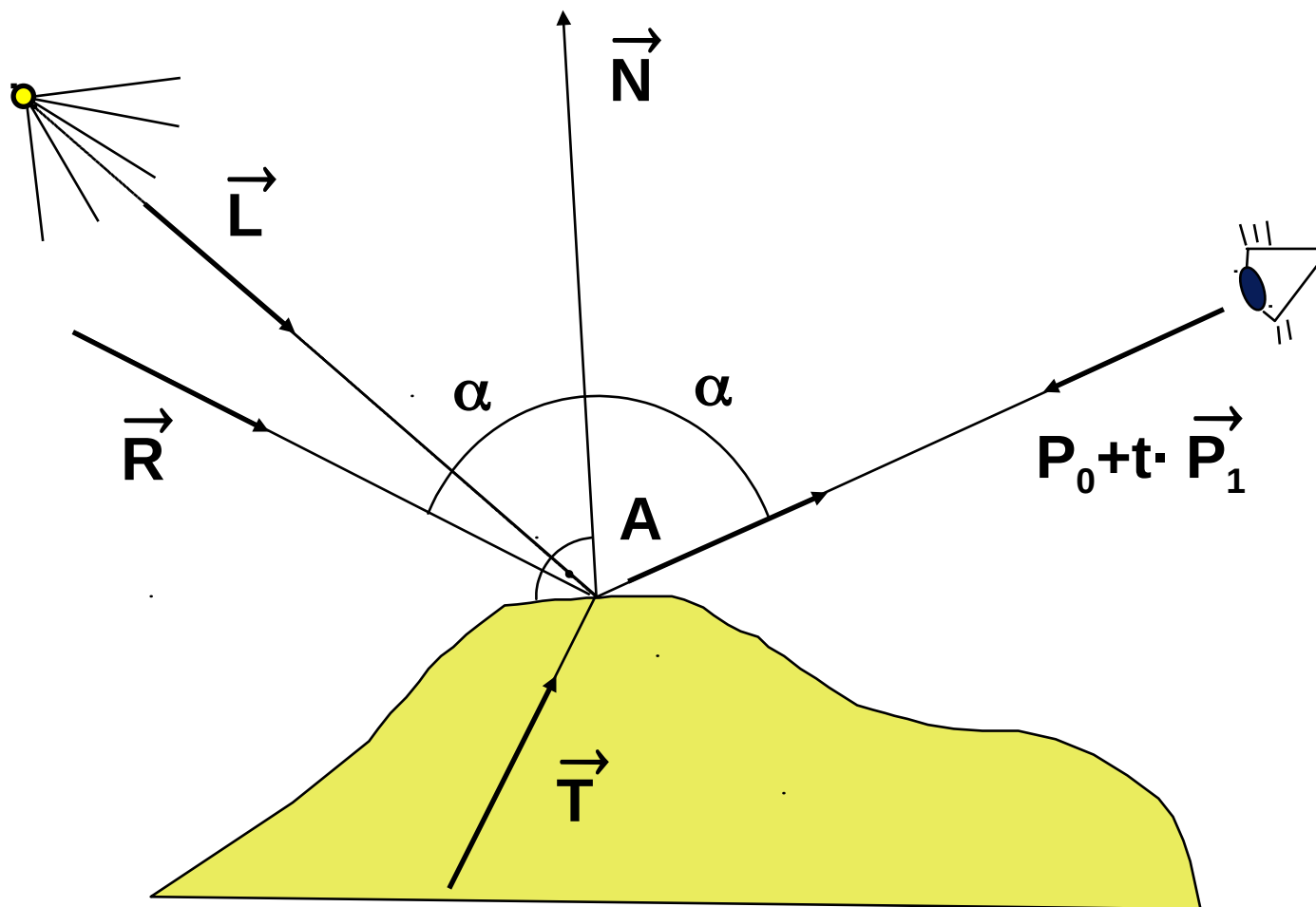


# Backward / Reverse Ray Tracing





# Lighting Computations





# Recursive Implementation

```
function Trace ( P0, P1 : Point3D; depth : integer ) : RGB;
    { P0..počátek paprsku, P1..směr, depth..počet odražení }
var A, R, T : Point3D;           { pomocné body a vektory }
    B : RGB;                       { výsledná barva }
begin
    A := Prusecik(Scena, P0, P1); { průsečík paprsku se scénou }
    if A==0 then Sleduj := Pozadi { paprsek na nic nenarazil }
    else
        begin                       { paprsek narazil na těleso }
            B := 0;
            for i := 1 to N do      { příspěvky od světelných zdrojů }
                if Prusecik(Scena, A, L[i]-A)==0 then B := B + kL * Svetlo(A, L[i]);
            hloubka := hloubka + 1;
            if hloubka <= maxhloubka then { konec rekurze }
                begin
                    if "A je odrazivé" then
                        begin
                            "spočítej R"           { odražený paprsek }
                            B := B + kR * Sleduj(A, R, hloubka);
                        end;
                end;
        end;
```



# Recursive Implementation

```
if "A je průhledné" then  
  begin  
    "spočítej T"           { lomený paprsek }  
    B := B + kT * Sleduj(A, T, hloubka);  
  end;  
end;  
Sleduj := B;              { nastrádaná návratová hodnota }  
end;  
end;
```



# Recursion Management

- ① **static** – limited by a constant (not suitable for scenes with many mirrors)
- ② **dynamic** – according to performance of the ray
  - ➔ „**performance**” is the percentage the ray can still contribute to the colour of a given pixel (primary rays: 100%)
  - ➔ Limit on the „performance” constant (e.g. 2-10%)
- ③ **Combined** – limit on the recursion depth, and the „performance” of the ray



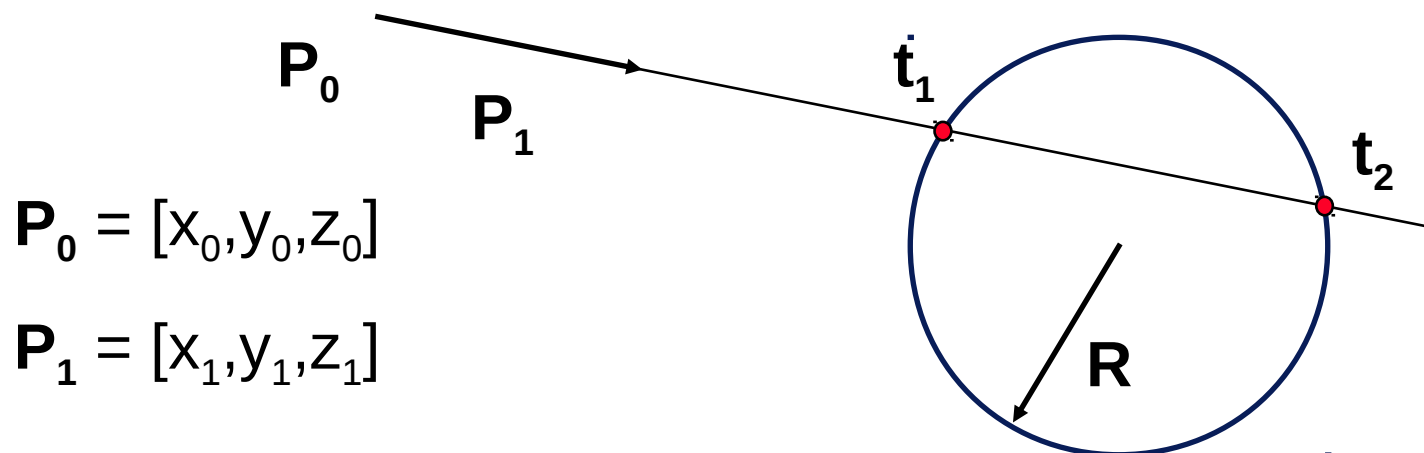
# Intersection Computations

- ① Intersection coordinates (or „infinity”)
  - ② ID of the solid (surface) that was hit
  - ③ Normal vector at the intersection
- ➔ **Time-consuming operation** (80-90% of render time)
    - Acceleration techniques extremely important
  - ◆ **Analytical solution** (sphere, cylinder, cube, ..)
  - ◆ **Numerical solution** (subdivision surfaces, higher order surfaces, rotational surfaces, ..)





# Ray - Sphere Intersections



$$\mathbf{P}_0 = [x_0, y_0, z_0]$$

$$\mathbf{P}_1 = [x_1, y_1, z_1]$$

➔ Ray:  $\mathbf{P}_0 + t \mathbf{P}_1, \quad t > 0$  (1)

➔ Sphere (at origin):  $\mathbf{x}^2 + \mathbf{y}^2 + \mathbf{z}^2 - \mathbf{R}^2 = 0$  (2)

➔ When substituting (1) into (2) we obtain a **quadratic equation** for  $t$ :

$$t^2 (\mathbf{x}_1^2 + \mathbf{y}_1^2 + \mathbf{z}_1^2) + 2t (\mathbf{x}_0 \mathbf{x}_1 + \mathbf{y}_0 \mathbf{y}_1 + \mathbf{z}_0 \mathbf{z}_1) + \mathbf{x}_0^2 + \mathbf{y}_0^2 + \mathbf{z}_0^2 - \mathbf{R}^2 = 0$$

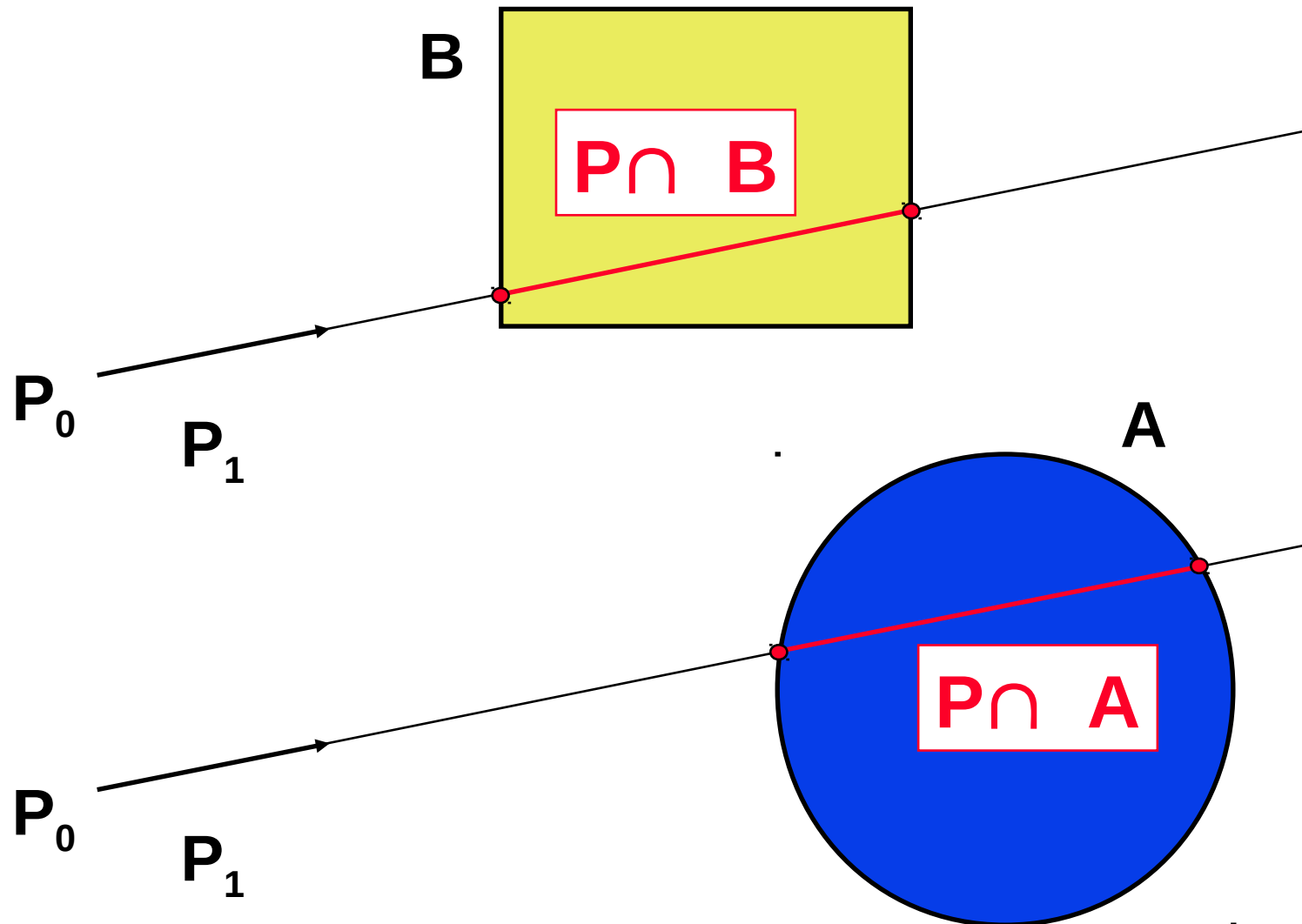


# Ray Intersections with CSG

- ◆ For **elementary solids**, intersections can be calculated
  - Start and end of ray traversal through a solid body
- ◆ **Set theoretic operations** on all intersections along the ray:
  - Distributive:  $\mathbf{P} \cap (\mathbf{A} - \mathbf{B}) = (\mathbf{P} \cap \mathbf{A}) - (\mathbf{P} \cap \mathbf{B})$
  - The usual ray-object intersection is an interval
- ◆ **Geometric transformations**:
  - The inverse transformation is applied to the ray

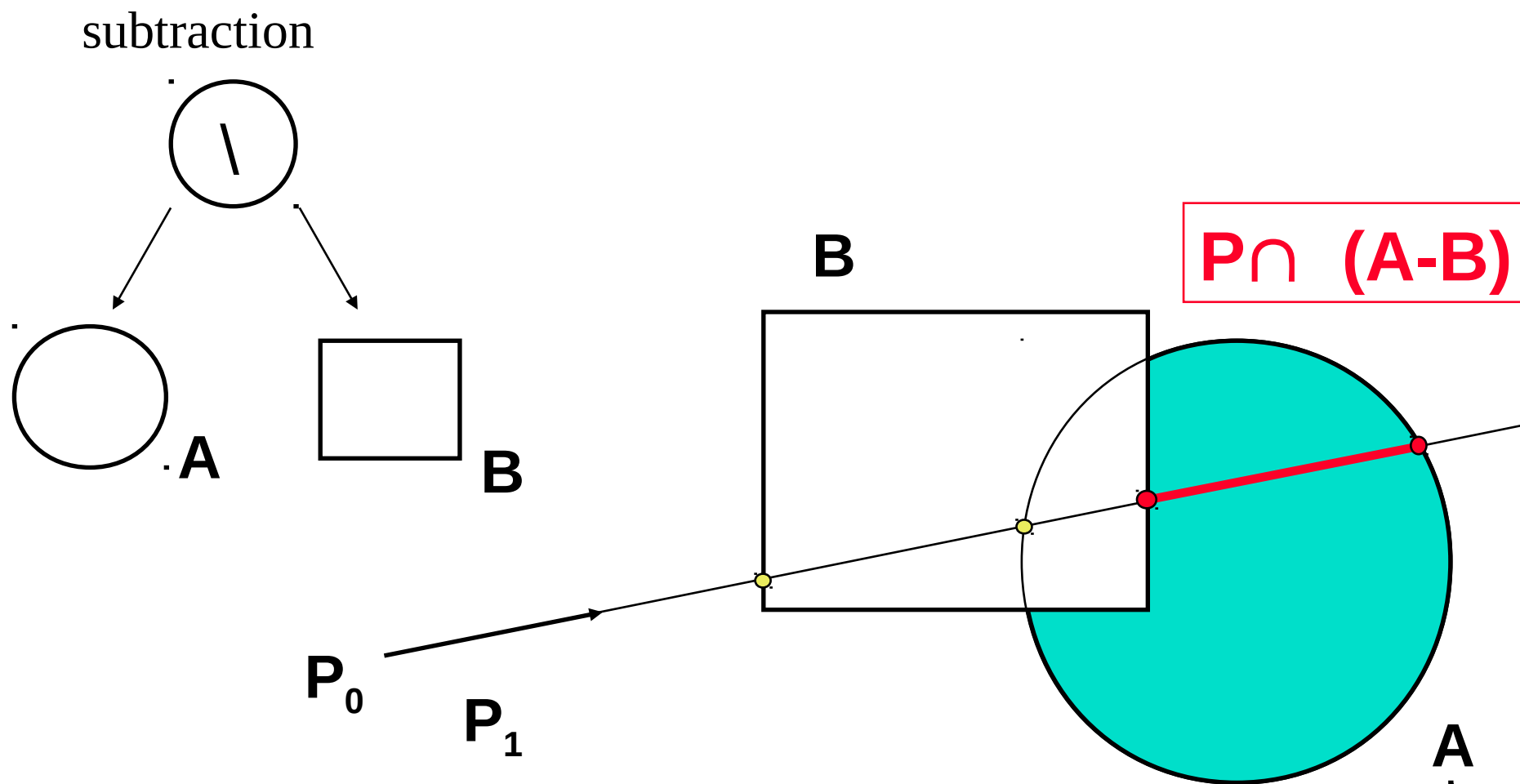


# Intersection $P \cap A, P \cap B$



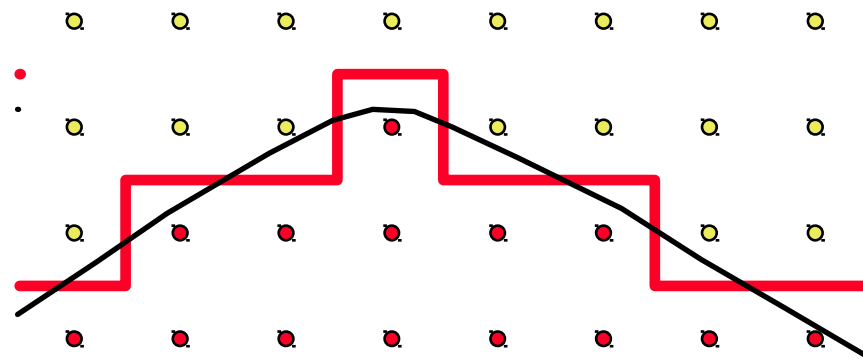


# Intersection: $P \cap (A-B)$





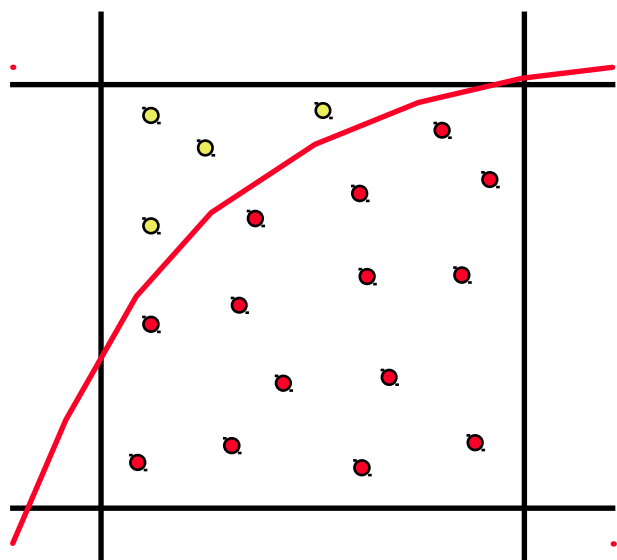
# Anti-aliasing



- ◆ Only one ray per pixel leads to „aliasing”
  - Jagged edges
  - Interference
- ◆ **Increased resolution** only solves the problem partially (and at great expense)



# Multiple Sampling



- ◆ Multiple rays are shot into each pixel
- ◆ The resulting colour is obtained via arithmetic mean
- ◆ Transitions are softer (no jaggies)
- ◆ The rays should cover the pixel area evenly, but not regularly!

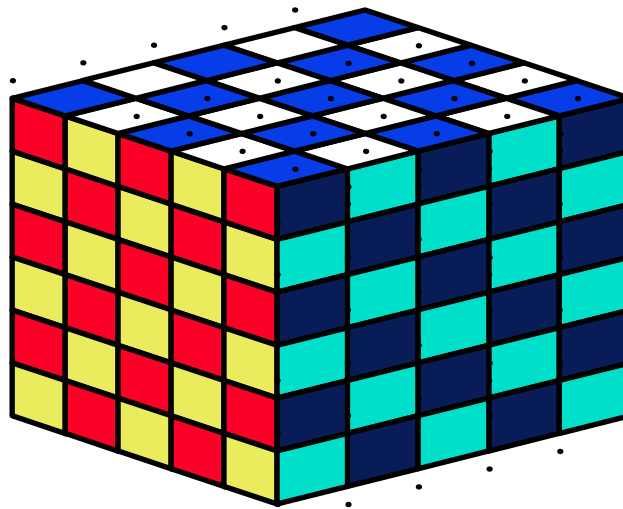


# Textures

- ◆ Changing the **colour** on object surfaces
- ◆ They can also affect **reflectivity** ( $k_D$  and  $k_S$ ), **normal vectors**, ...
- Realistic capture of **material properties** is possible (micro-structure)
  - Wood, orange skin, polished metal ..
- Replaces complex **geometry** (water waves, ..)



# 2D Textures



- ◆ Covers the object surface (like wallpaper)
- ➔ **Texture mapping:**  $[x,y,z] \rightarrow [u,v]$
- ➔ **Custom texture:**  $[u,v] \rightarrow \text{colour (normal, ..)}$





# 3D Textures

- ◆ Model changes that occur **inside a solid**
- ◆ Mimics the **internal structure of materials** (wood, marble, ...)
- It is not necessary to perform a **mapping**
- **3D texture:  $[x,y,z] \rightarrow \text{colour}$**  (reflectance, etc.)
- ▲ Frequently, **3D noise functions** are used (simulation of natural phenomena)

# End



## Further information:

- **A. Glassner: *An Introduction to Ray Tracing*, Academic Press, London 1989, 1-31**
- **Jiří Žára a kol.: *Počítačová grafika*, principy a algoritmy, 374-378**