

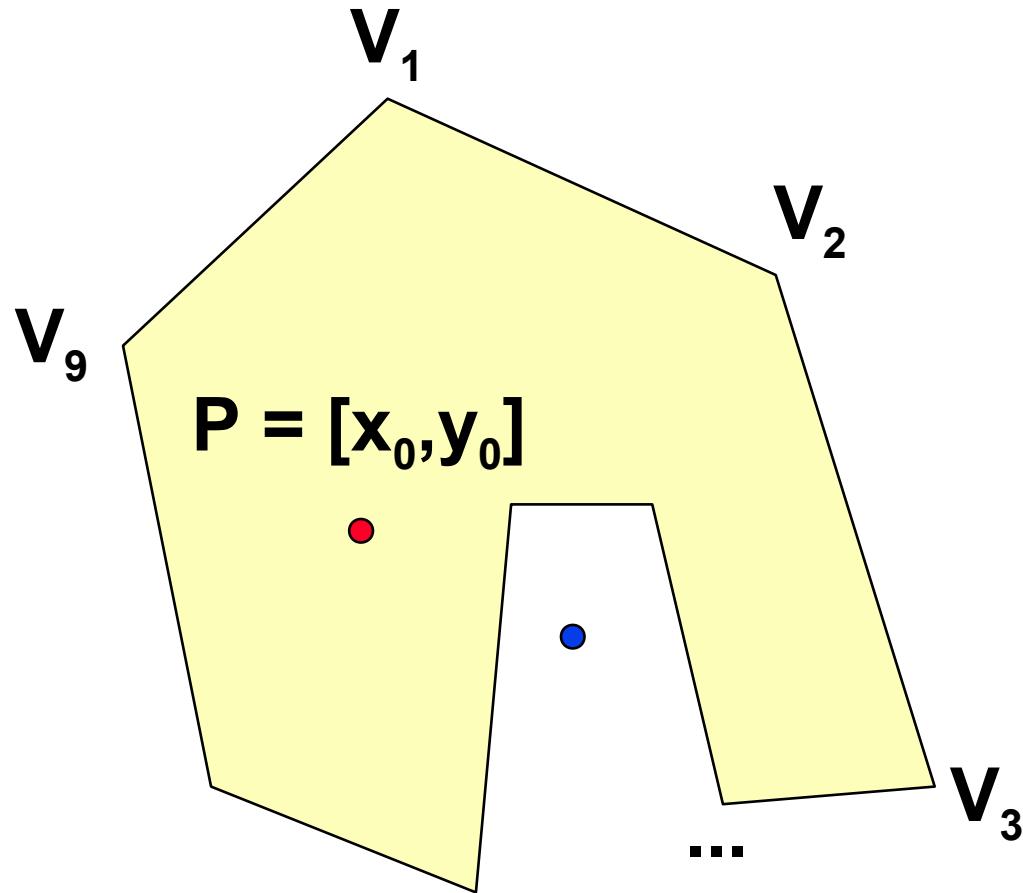
Planar test point × polygon

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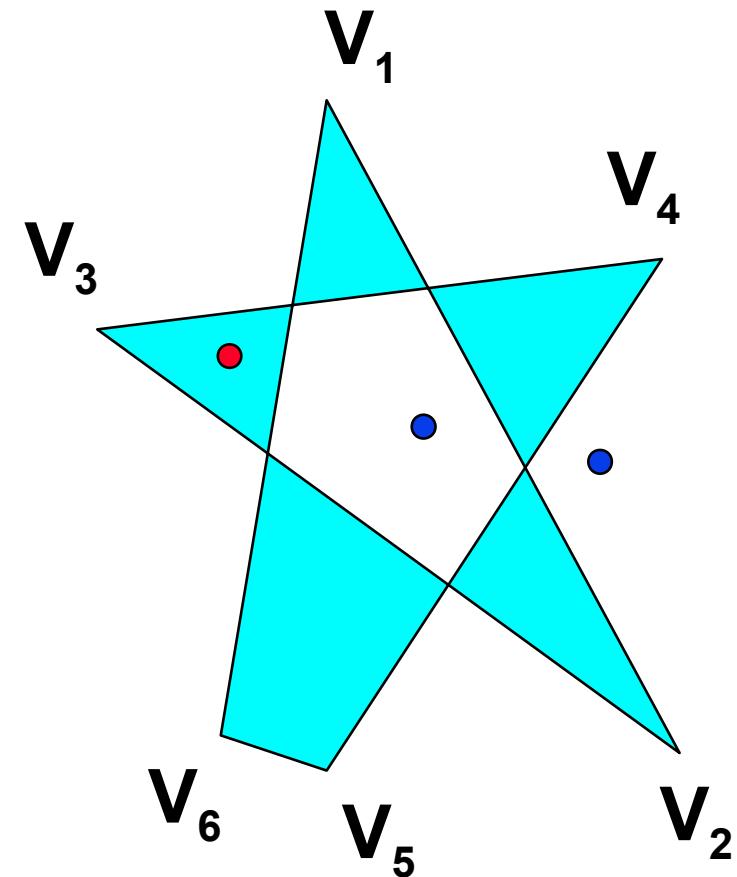
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<http://cgg.mff.cuni.cz/~pepca/>



Polygon interior?



$$V_i = [x_i, y_i]$$





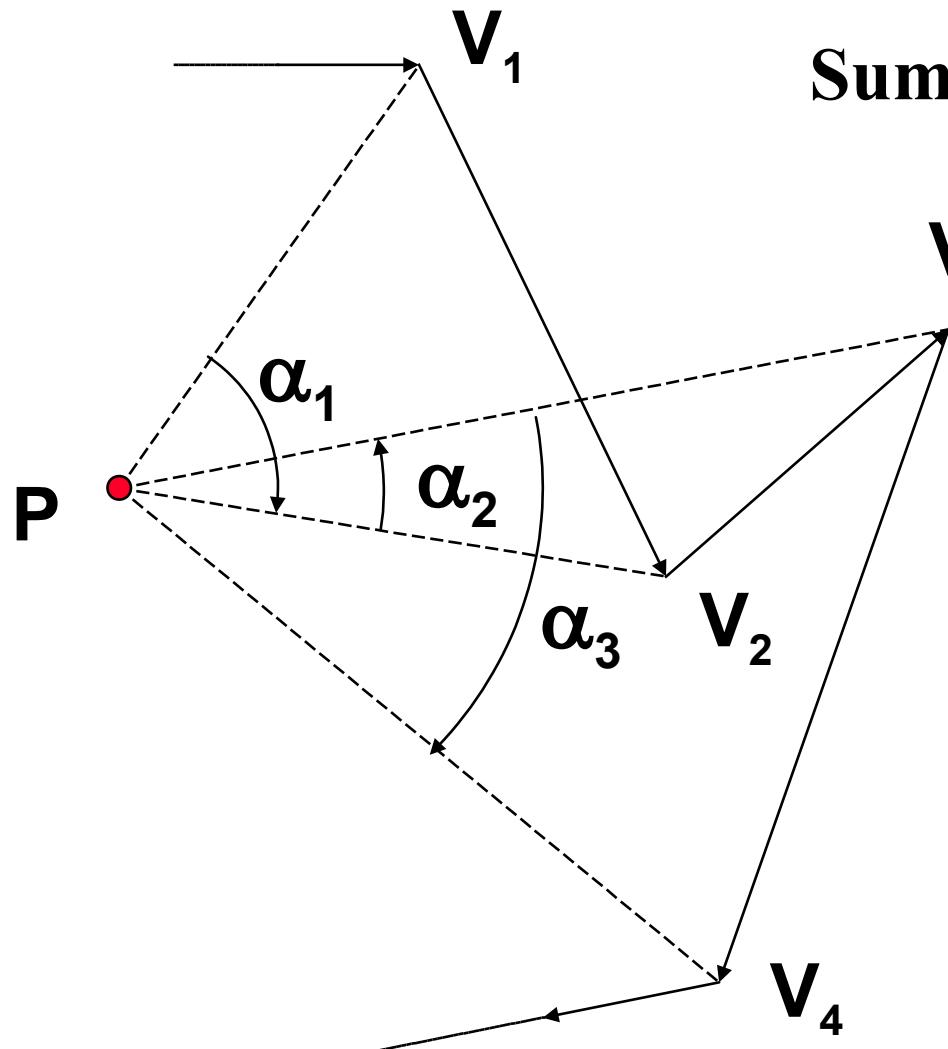
Different definitions

Point **P** lies inside the polygon [$V_1, \dots V_M$], if:

- ① it is separated from the outside (infinite component of the plane) by **odd number of borders** (“odd-even rule”, Jordan theorem)
- ② it is separated from the outside by **at least one border** (i.e. not element of the infinite component)
- ③ its **”winding number”** with respect to the polygon's outline **W** is **nonzero** (“thread loop + pin”)



Winding number computation



Sum of the oriented angles:

$$\sum_i \alpha_i = 2\pi \cdot W$$

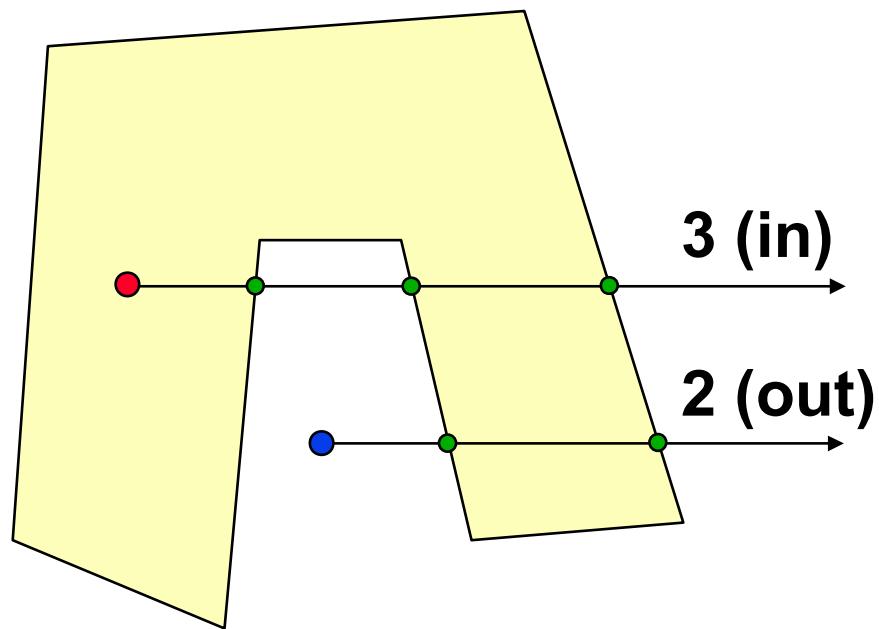
$0^\circ, \pm 360^\circ, \pm 720^\circ, \dots$

outside inside

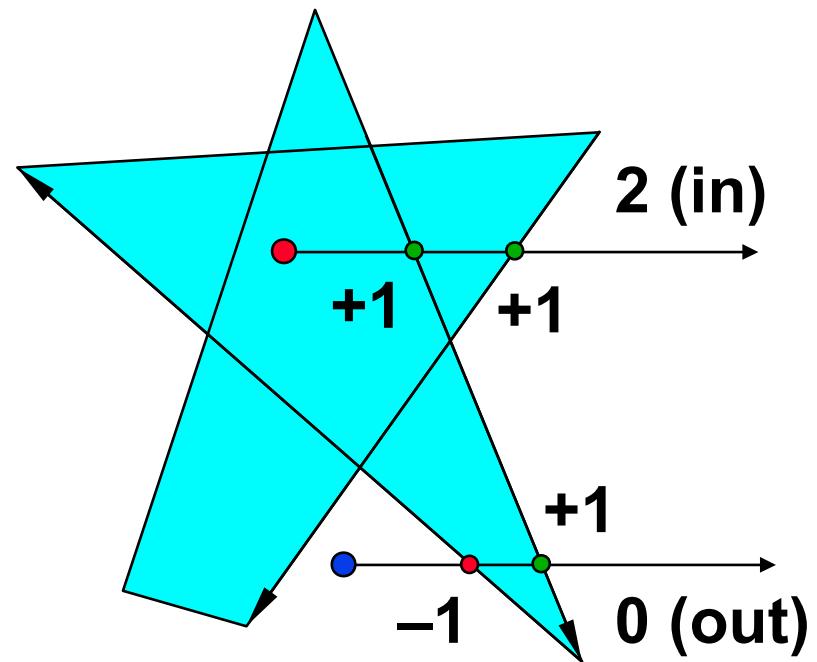
For efficiency:
table of $\text{arctg}(y/x)$



Half line vs. polygon outline



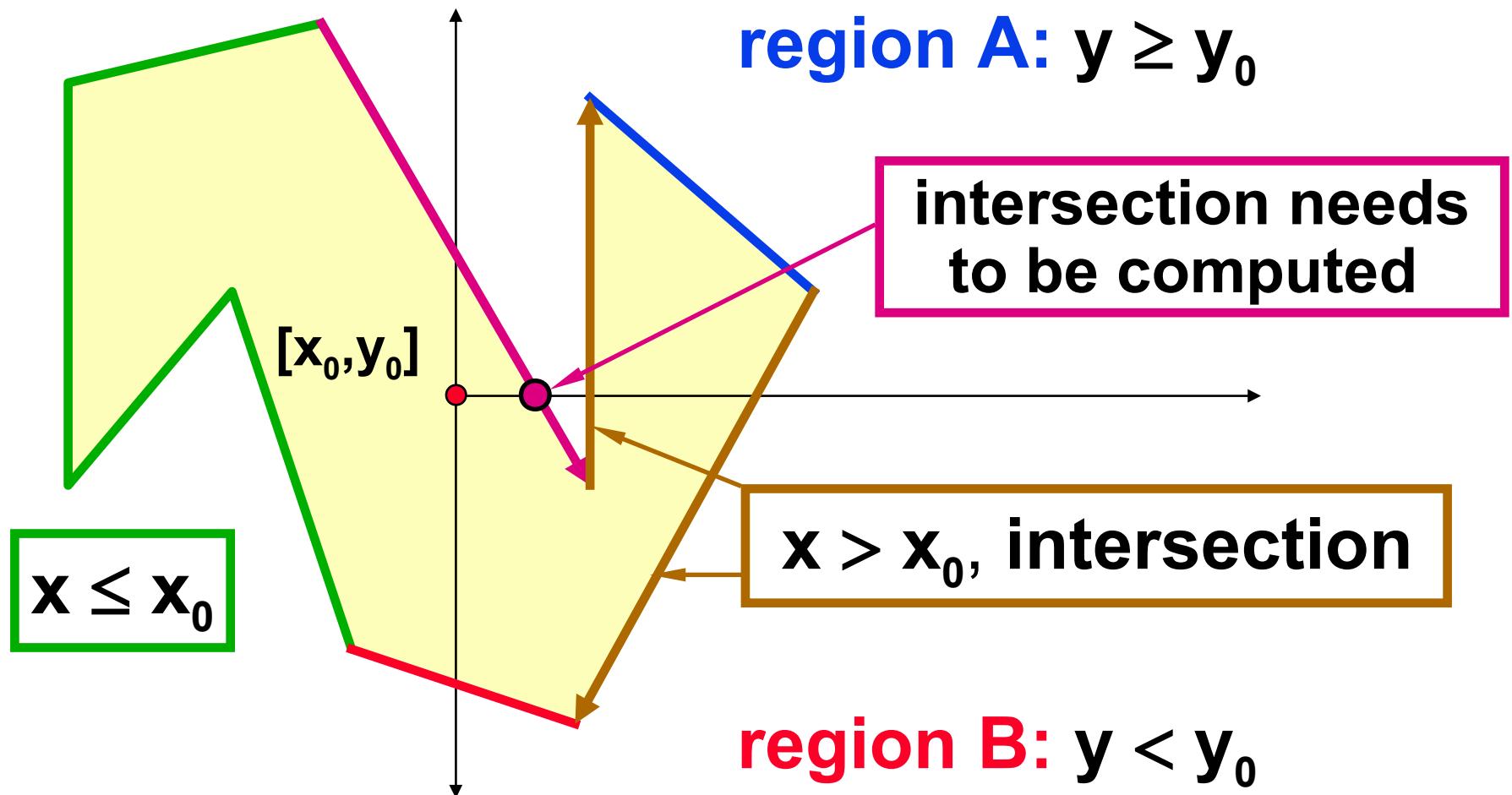
Definition 1
(nonoriented edges)



Definition 3
(oriented edges)



Implementation





Implementation

- ◆ sequential pass through edges $V_1V_2, V_2V_3, \dots V_MV_1$
 - every vertex has the flags $x > x_0, y \geq y_0$
- **trivial negative edges:** both vertices have equal boolean value of either condition:
 - $x \leq x_0, y \geq y_0$ or $y < y_0$
- **trivial positive edges** (intersection exists):
 - for both vertices: $x > x_0$
 - for exactly one vertex: $y \geq y_0$

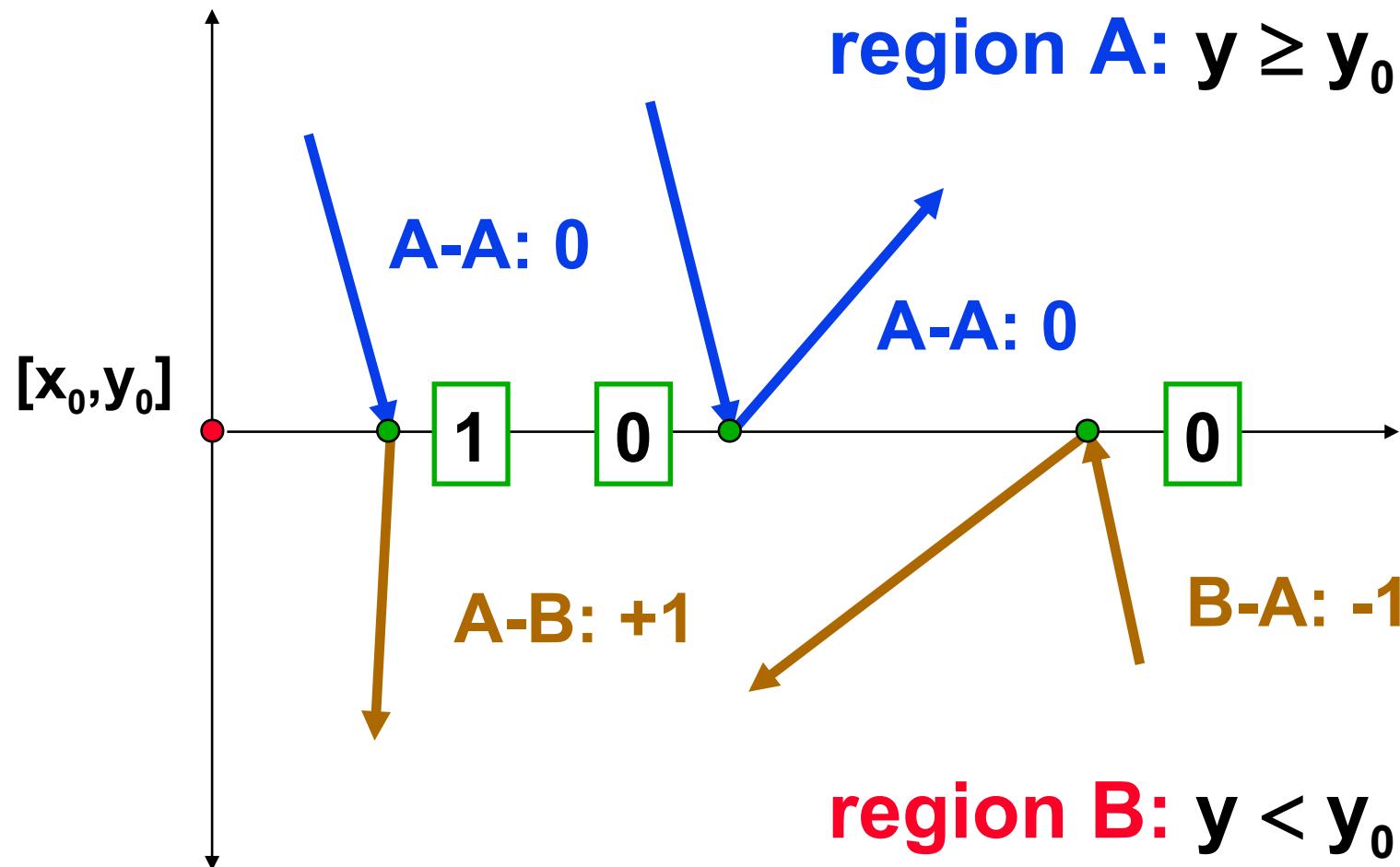


Implementation

- the rest of the edges are **nontrivial**:
 - for exactly one vertex: $x > x_0$
 - for exactly one vertex: $y \geq y_0$
 - the **exact intersection** of an edge with the half line $y = y_0$ has to be computed
- ◆ for any **positive edge** (intersection) the contribution is:
 - +1 or -1 according to edge orientation (definition ③)
 - +1 for an unoriented edge (definition ①)



Special cases





References

- A. Glassner: *An Introduction to Ray Tracing*, Academic Press, London 1989, 53-59
- J. Foley, A. van Dam, S. Feiner, J. Hughes: *Computer Graphics, Principles and Practice*, 34