

# Distributed Ray Tracing

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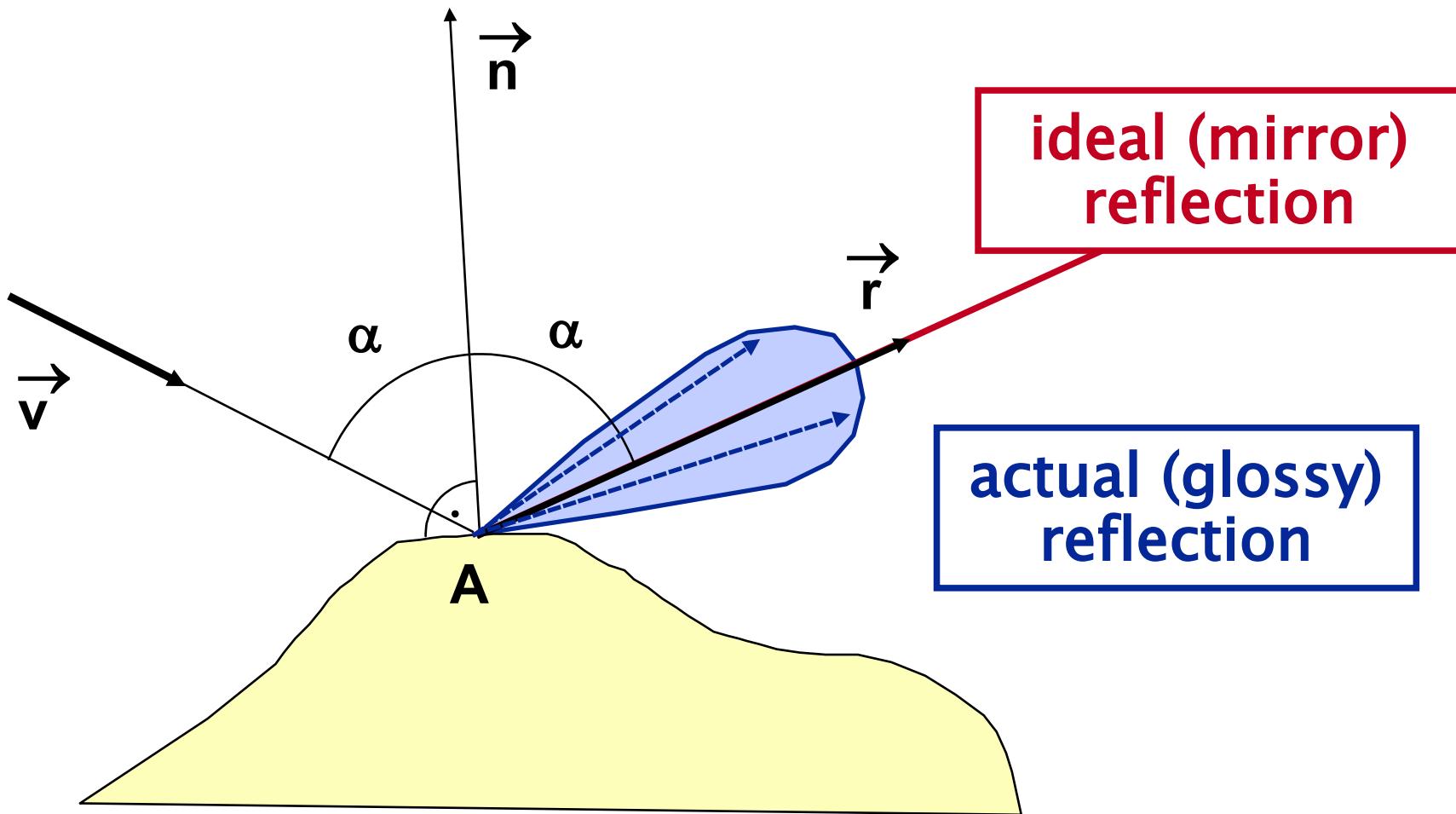


# Distributed ray tracing

- ◆ **better image quality** (fidelity)
  - soft shadows, glossy reflections, soft refractions
  - motion blur
  - depth of field imitation
  - light dispersion (index of refraction depends on  $\lambda$ )
- ◆ introducing **new variables** to an image function
  - reflection or refraction angle, wavelength, light source point, lens entry point, time, ..



# Glossy reflection





# Glossy reflection computation

Sharp reflection:

$$I(V) = I(R)$$

(one reflected ray)

Glossy reflection:

$$I(V) = \iint_{\text{sphere}} I(R(\varphi, \theta)) \cdot \underline{\text{BRDF}(\alpha, \beta, \varphi, \theta)} d\varphi d\theta$$

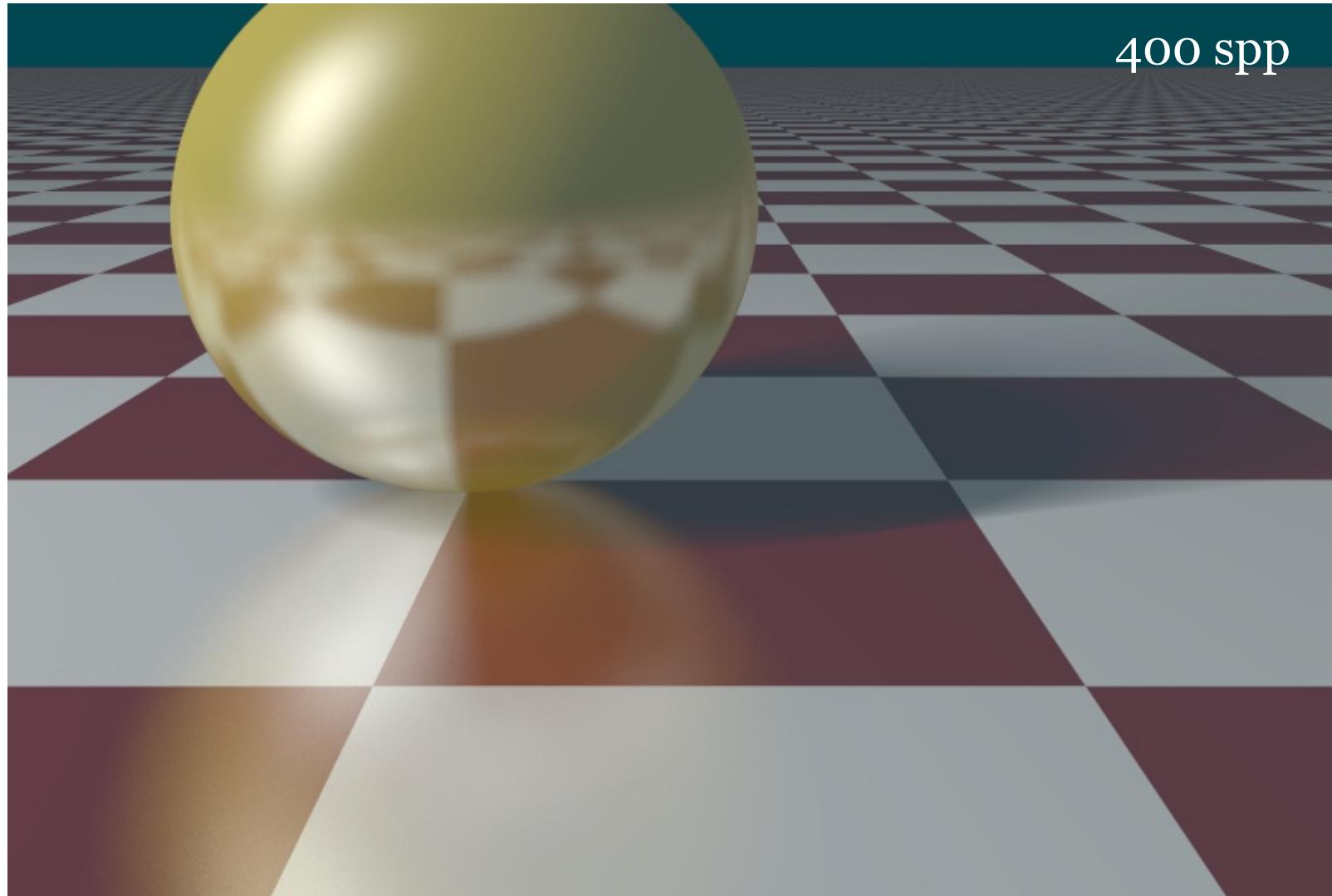
sphere

reflectance function

(weighted integral average .. over all reflection angles)

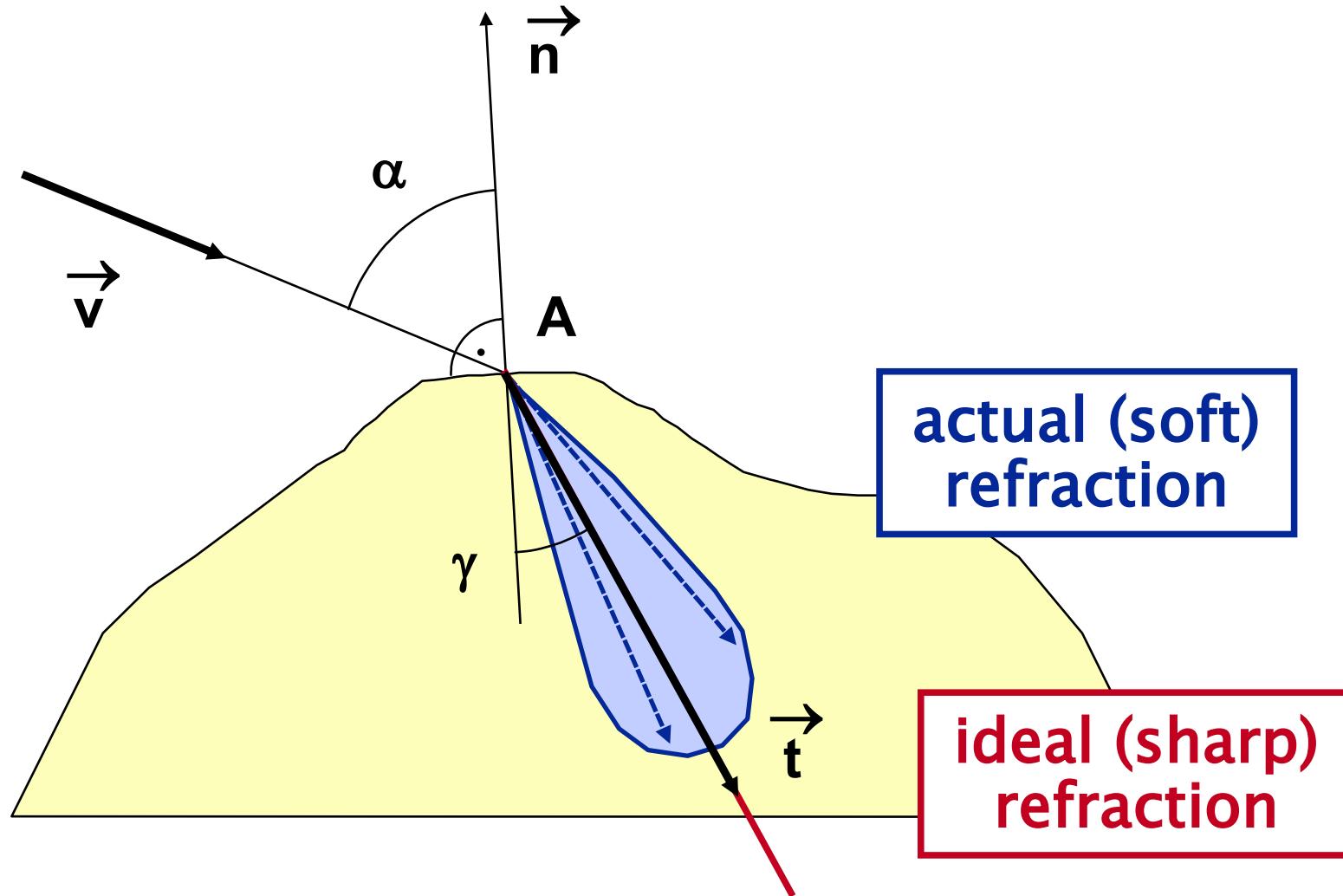


# Glossy reflection – example



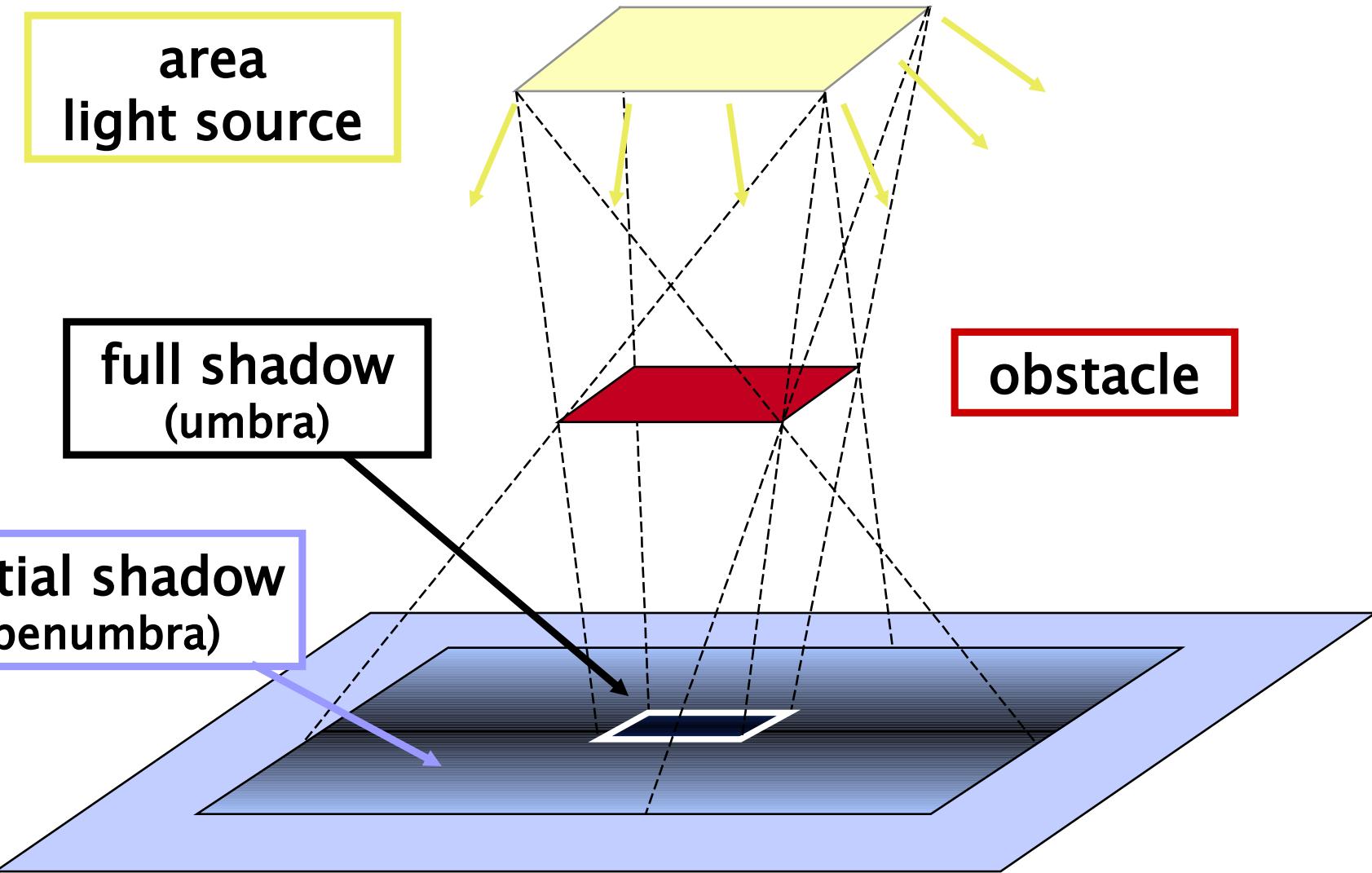


# Soft refraction





# Soft shadow





# Soft shadow computation

Contribution of a point light source:

$$I(A) = \begin{cases} I_L & \text{if source is visible from } A \\ 0 & \text{else} \end{cases}$$

Contribution of an area light source:

$$I(A) = I_L \cdot S [\%]$$

visible portion of a light source



# Soft shadow computation

Contribution of an inhomogenous light source:

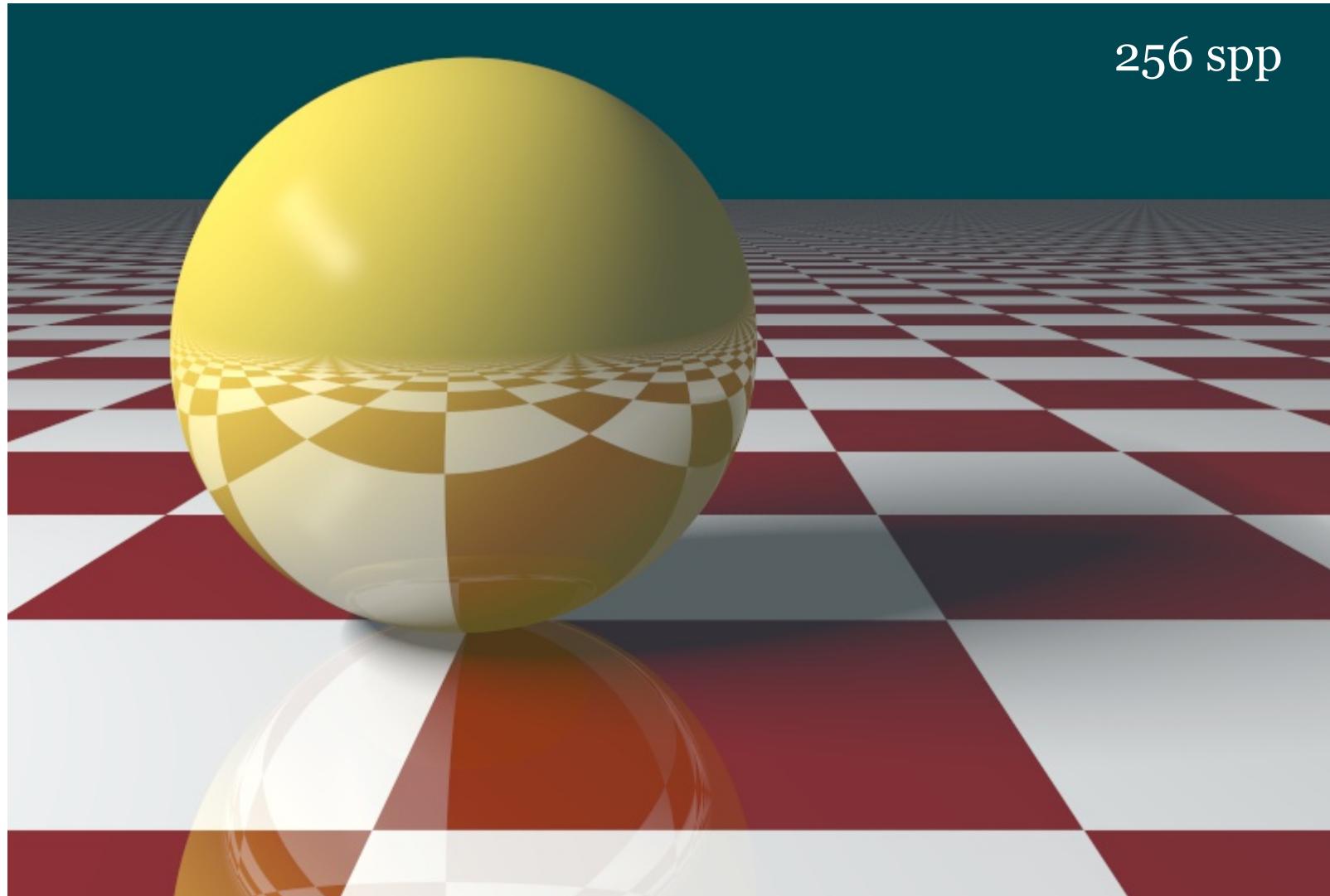
$$I(A) = \iint_{\text{light source area}} I_L(u, v) \cdot \underline{\text{vis}(A, u, v)} du dv$$

visibility function

$$\underline{\text{vis}(A, u, v)} = \begin{cases} 1 & \text{if } S(u, v) \text{ is visible from } A \\ 0 & \text{else} \end{cases}$$



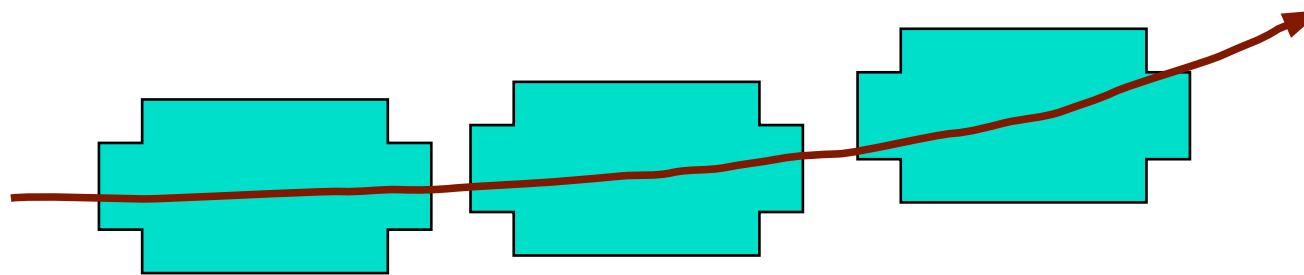
# Soft shadow – example





# Motion blur

path of the solid  $s(t)$



rendered interval:  
(shutter open time)

$[ t_1, t_2 ]$

scene rendering in time  $t$ :

$f(t) = f(x, y, t)$



# Motion blur

General motion blur:

$$f_{\text{blurr}} = \int_{t_1}^{t_2} f(t) dt$$



# Motion blur

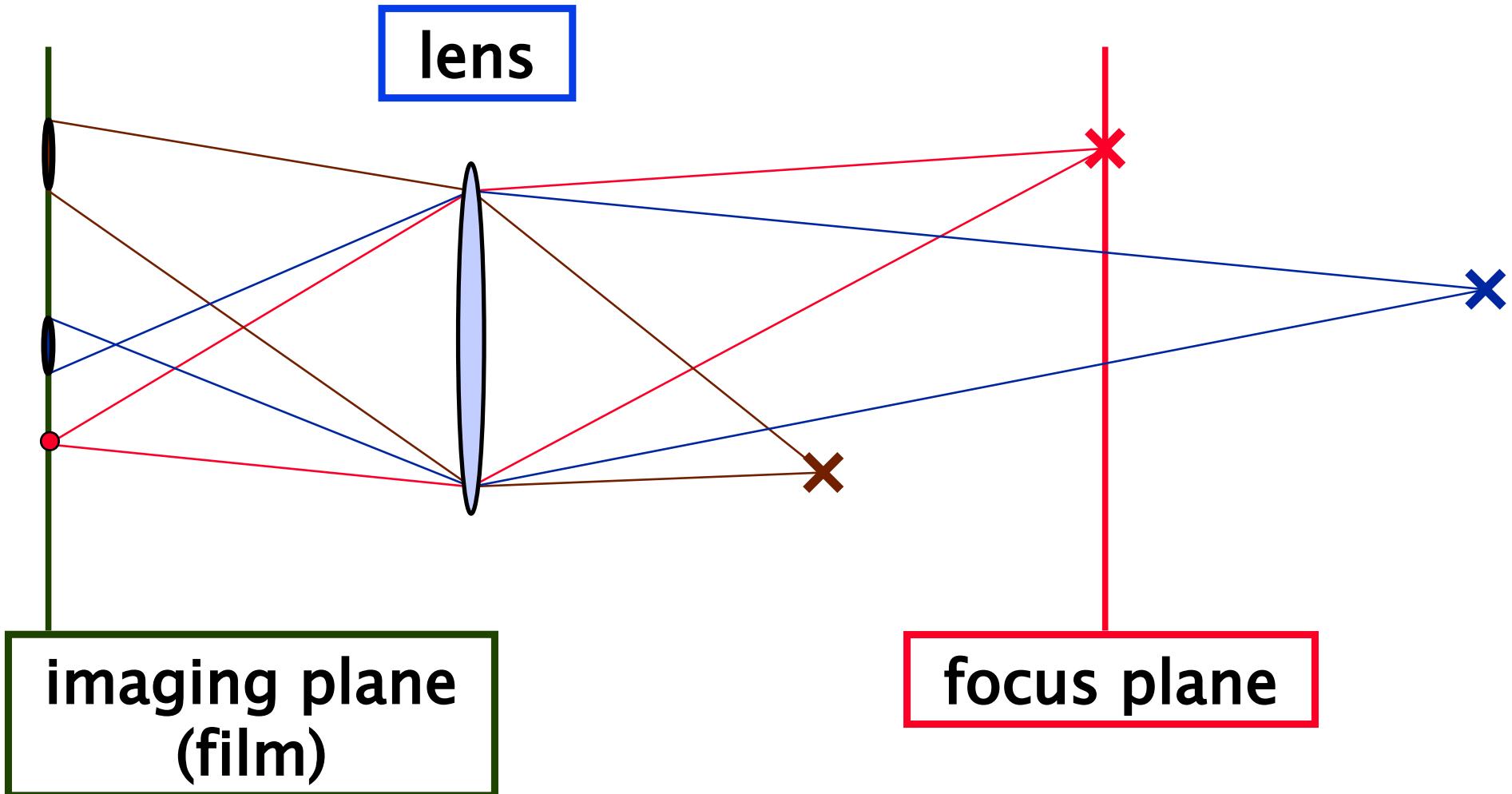
Scene with single moving object:

$$f_{\text{blurr}} = \frac{\int_{t_1}^{t_2} f(t) \cdot |s'(t)|^{-1} dt}{\int_{t_1}^{t_2} |s'(t)|^{-1} dt}$$

$$|s'(t)| \neq 0 \text{ on } \langle t_1, t_2 \rangle$$

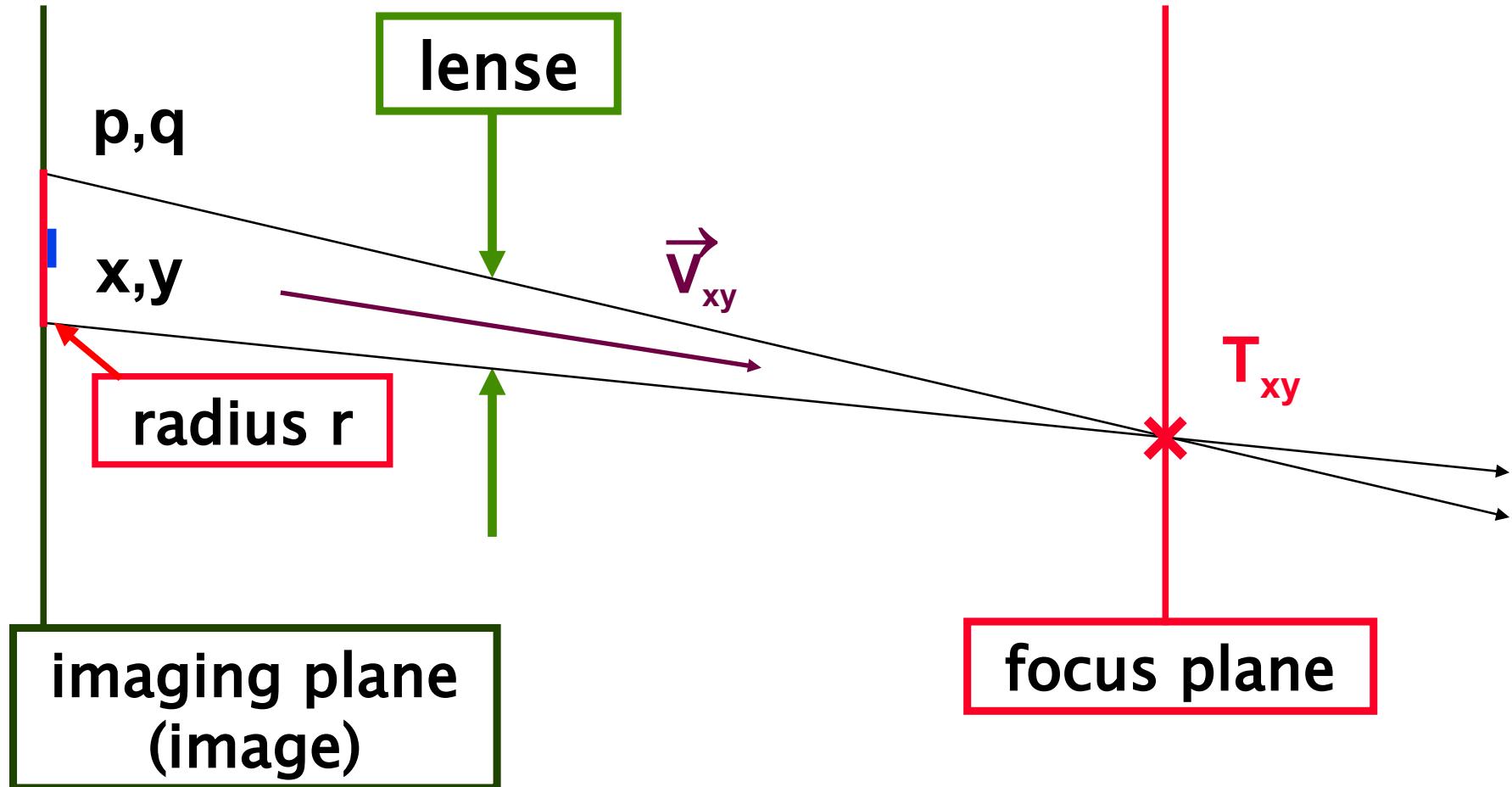


# Depth of field





# Geometric simplification





# Depth of field computation

Pinhole camera model:

$$f(x, y) = \left( V_{xy} \right)$$

$$V_{xy} = T_{xy} - [x, y, 0]$$

$$V_{pq} = T_{xy} - [p, q, 0]$$

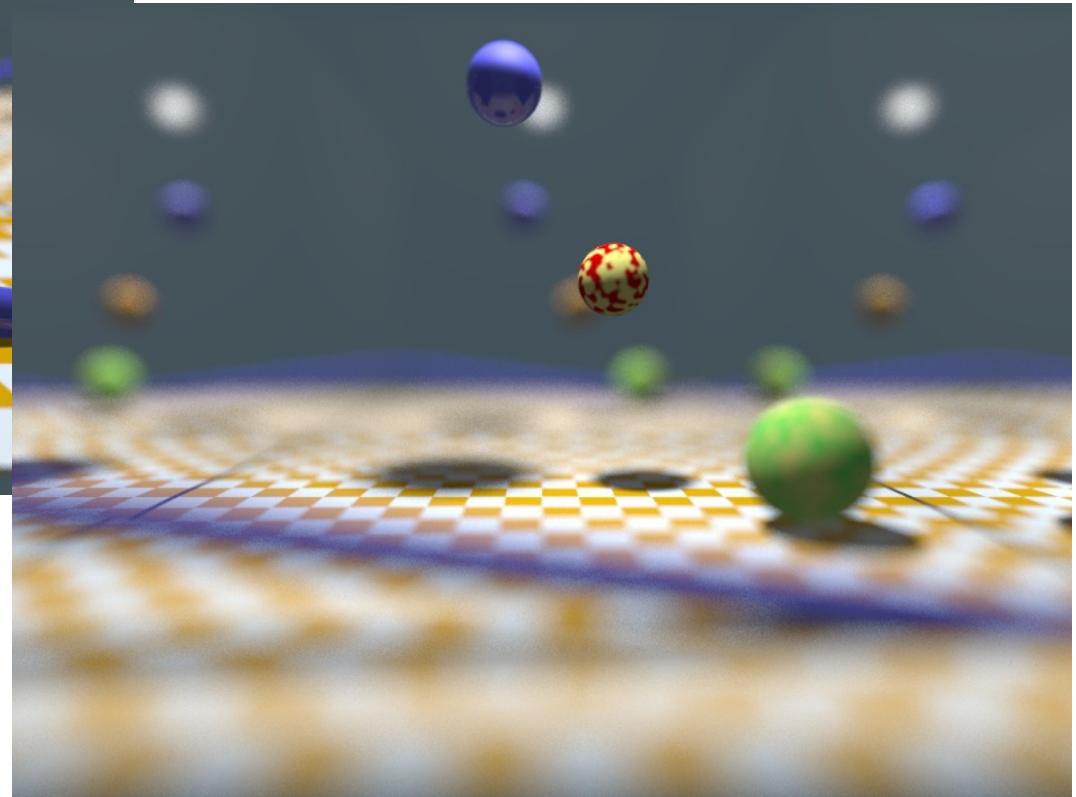
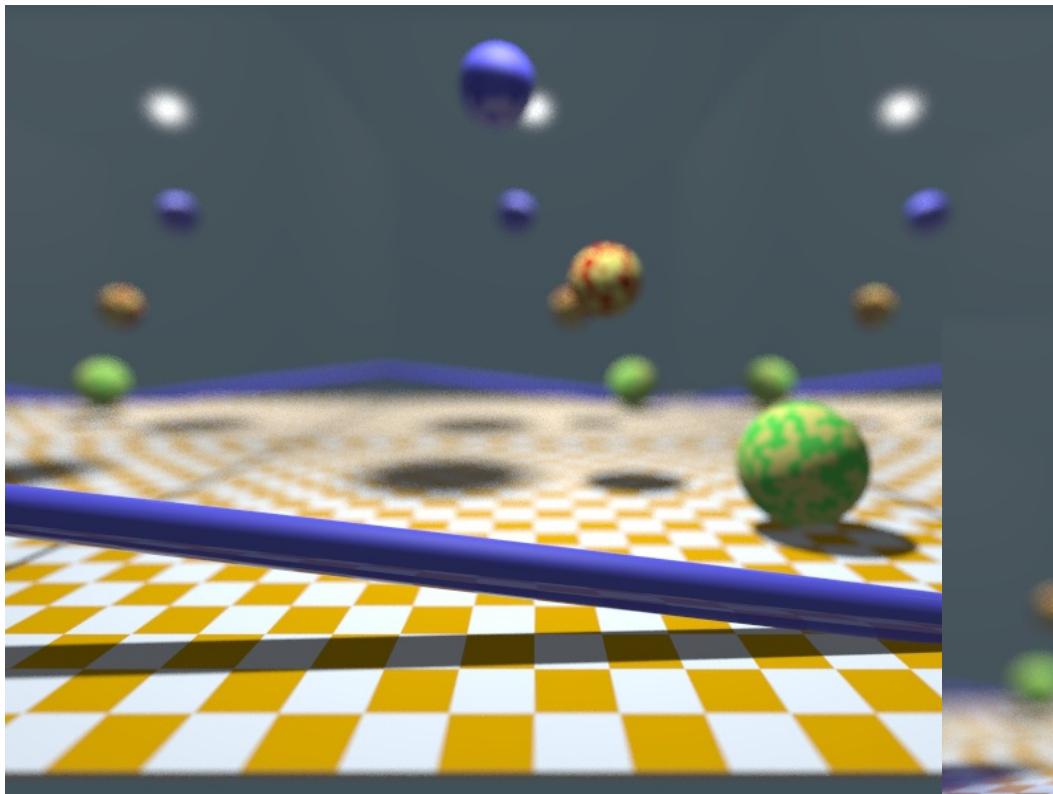
Lens with finite aperture:

$$f(x, y) = \int \left( V_{pq} \right) dp dq$$

circle around  $[x, y]$



# Depth of field – examples





# Light dispersion

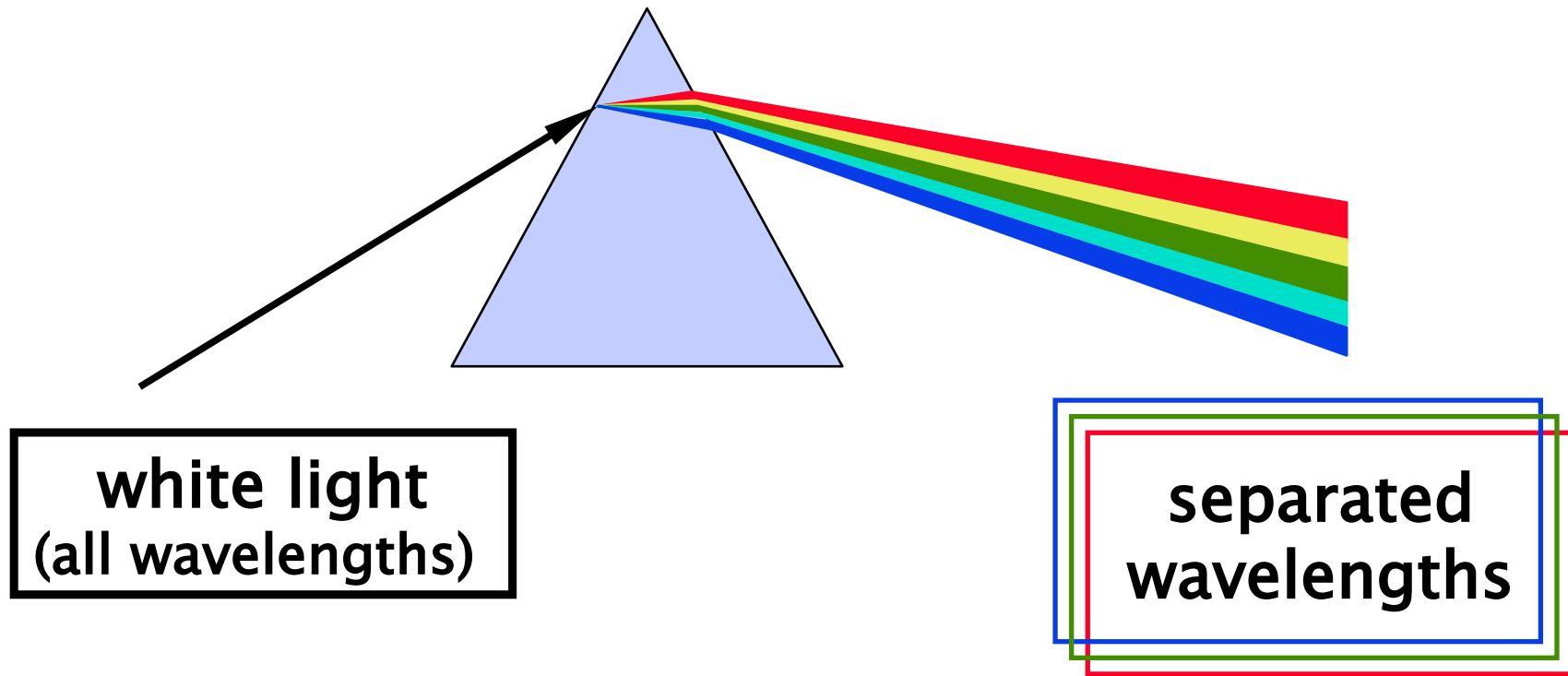


image function:  $f(\lambda) = f(x,y,\lambda)$



# Light dispersion computation

Pixel RGB color from spectral distribution:

$$R(x, y) = \int_{\text{spectrum}} f(x, y, \lambda) \cdot R(\lambda) d\lambda$$

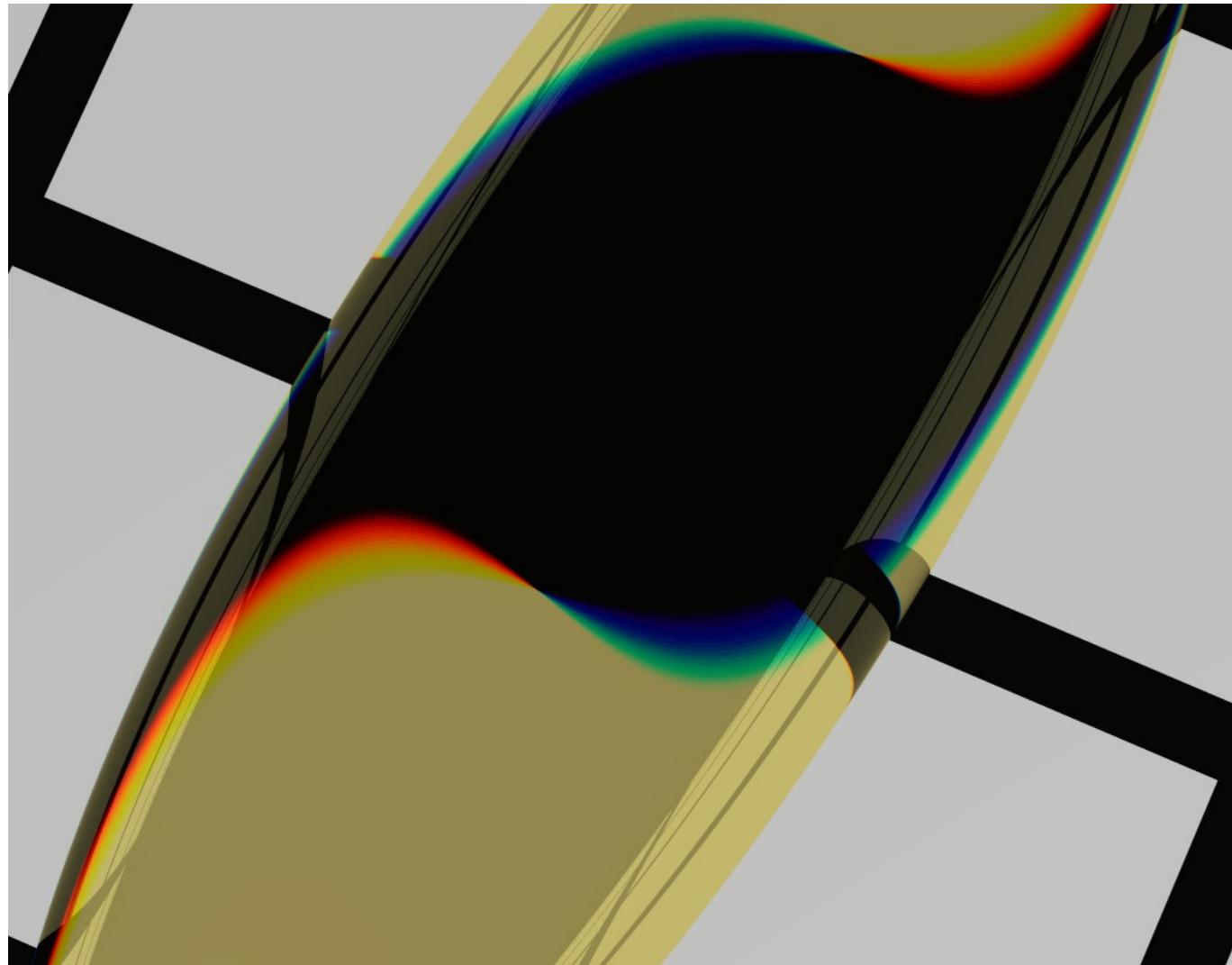
$$G(x, y) = \int_{\text{spectrum}} f(x, y, \lambda) \cdot G(\lambda) d\lambda$$

$$B(x, y) = \int_{\text{spectrum}} f(x, y, \lambda) \cdot B(\lambda) d\lambda$$

trichromatic  
spectral  
coefficients



# Light dispersion – example





# Implementation

- ▶ integral averaging is done **stochastically** (Monte-Carlo methods)
  - finite number of point samples (rays)
  - integral is estimated by a [weighted] sum
- ▶ **weighted** integral average
  - uniform sampling and appropriate weight function
  - nonuniform sampling (using the right density/PDF)



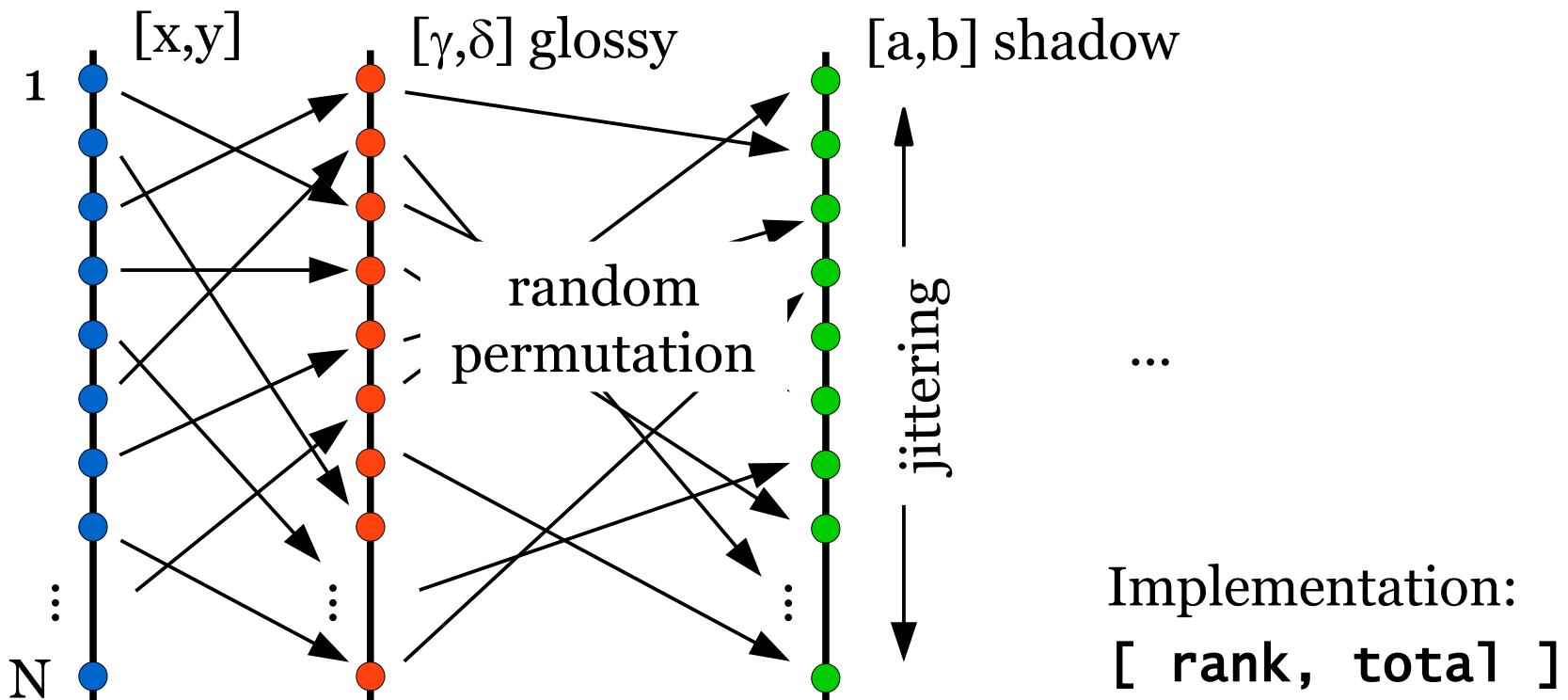
# Combining methods

- ▶ any methods can be **combined**
  - with anti-aliasing as well
  - higher order integrals – e.g. dimension 10:  
anti-aliasing (2), depth of field (2), glossy reflection (2),  
soft shadows (2), motion blur (1), light dispersion (1)
- ▶ **sampling method:**
  - jittering
  - independent jittering (“N rooks”) in form of **hidden sampling**
  - adaptive sampling



# Hidden sampling

- number of **samples per pix** (primary rays) is defined
  - every inner component is sampling independently
  - arbitrary number of additional (sampled) dimensions





# References

- A. Glassner:** *An Introduction to Ray Tracing*, Academic Press, London 1989, 171-199
- A. Watt, M. Watt:** *Advanced Animation and Rendering Techniques*, Addison-Wesley, Wokingham 1992, 262-265