

Distributed Ray Tracing

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Distributed ray tracing

Better image quality (fidelity)

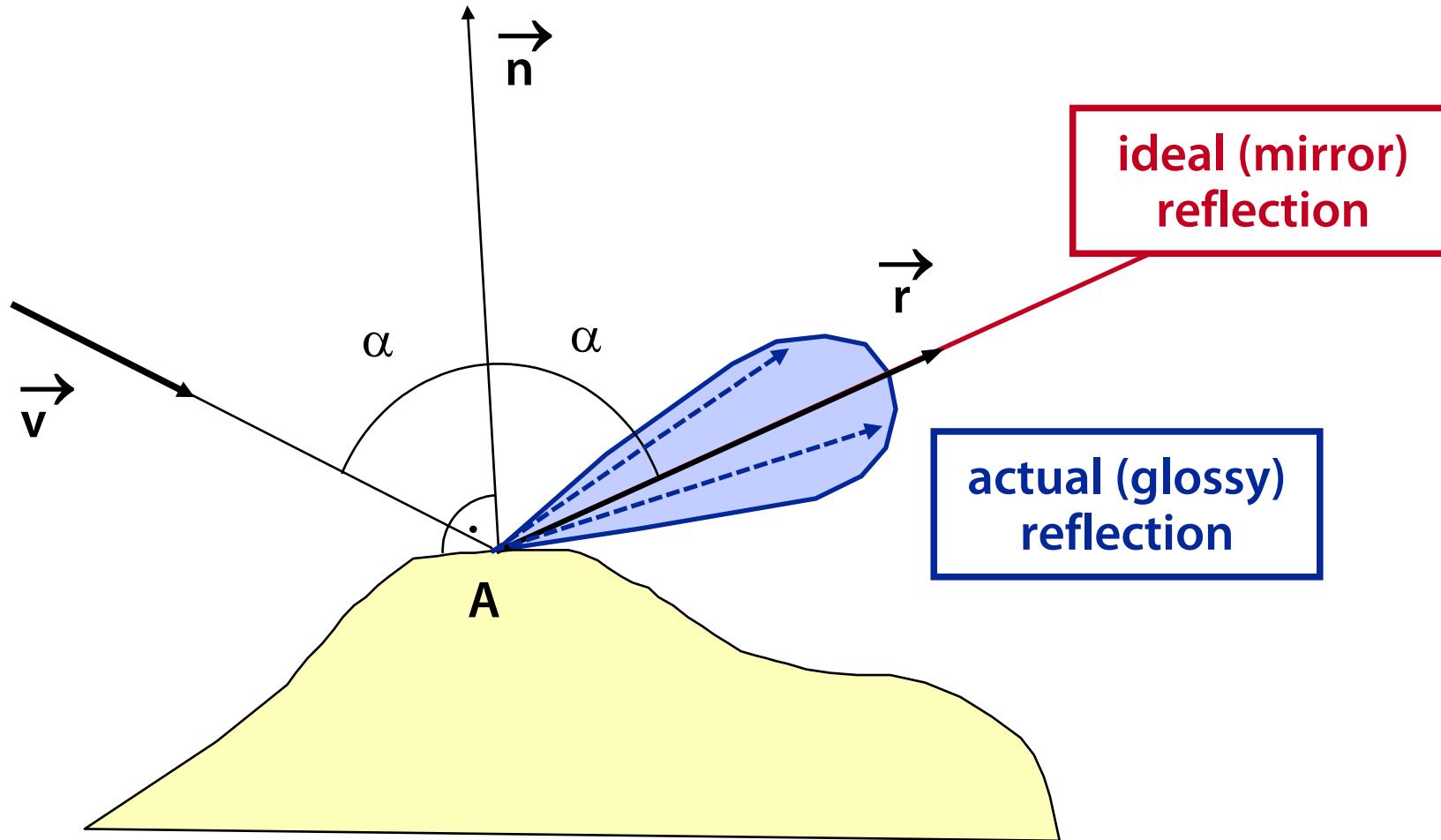
- soft shadows, glossy reflections, soft refractions
- motion blur
- depth of field imitation
- light dispersion (index of refraction depends on λ)

Introducing **new variables** to an image function

- reflection or refraction angle, wavelength, light source point, lens entry point, time...



Glossy reflection





Glossy reflection computation

Sharp reflection

$$I(V) = I(R)$$

(one reflected ray)

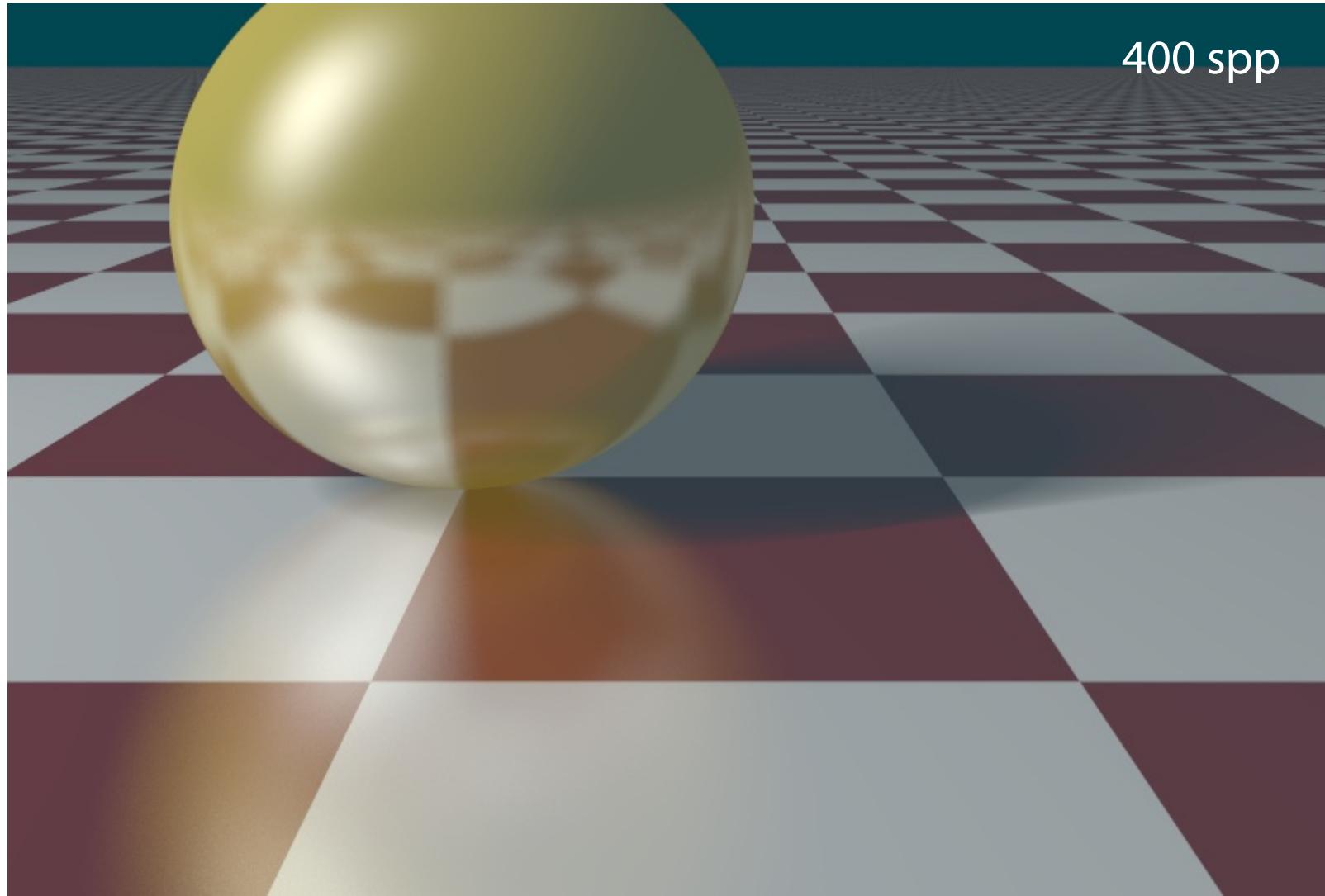
Glossy reflection

$$I(V) = \iint_{\text{sphere}} I(R(\varphi, \theta)) \cdot \underbrace{\text{BRDF}(\alpha, \beta, \varphi, \theta)}_{\text{reflectance function}} d\varphi d\theta$$

(weighted integral average ... over all reflection angles)

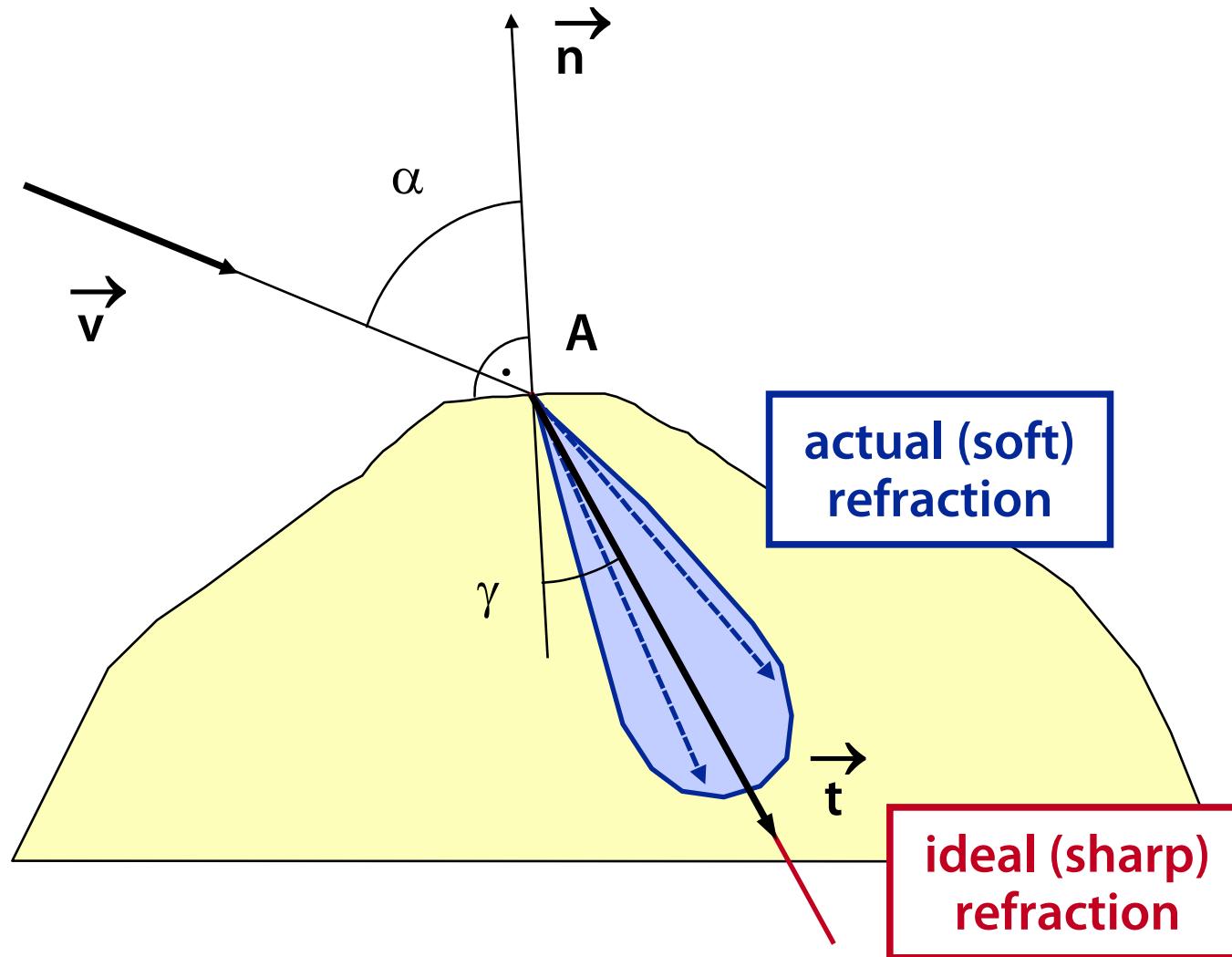


Glossy reflection – example



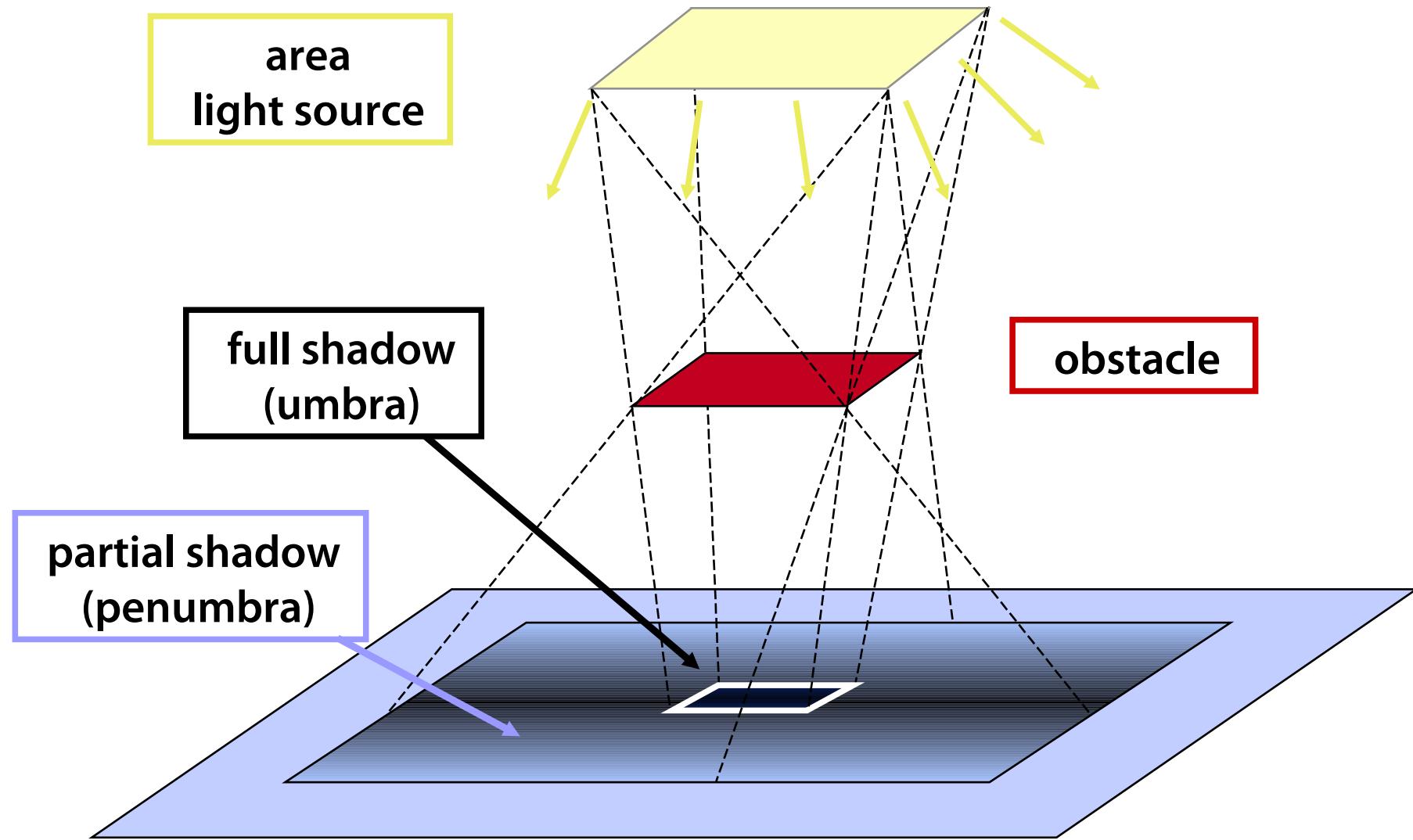


Soft refraction





Soft shadow





Soft shadow computation

Contribution of a point light source

$$I(A) = \begin{cases} I_L & \text{if source is visible from A} \\ 0 & \text{else} \end{cases}$$

Contribution of an area light source

$$I(A) = I_L \cdot S[\%]$$

visible portion of a light source



Soft shadow computation

Contribution of an inhomogenous light source

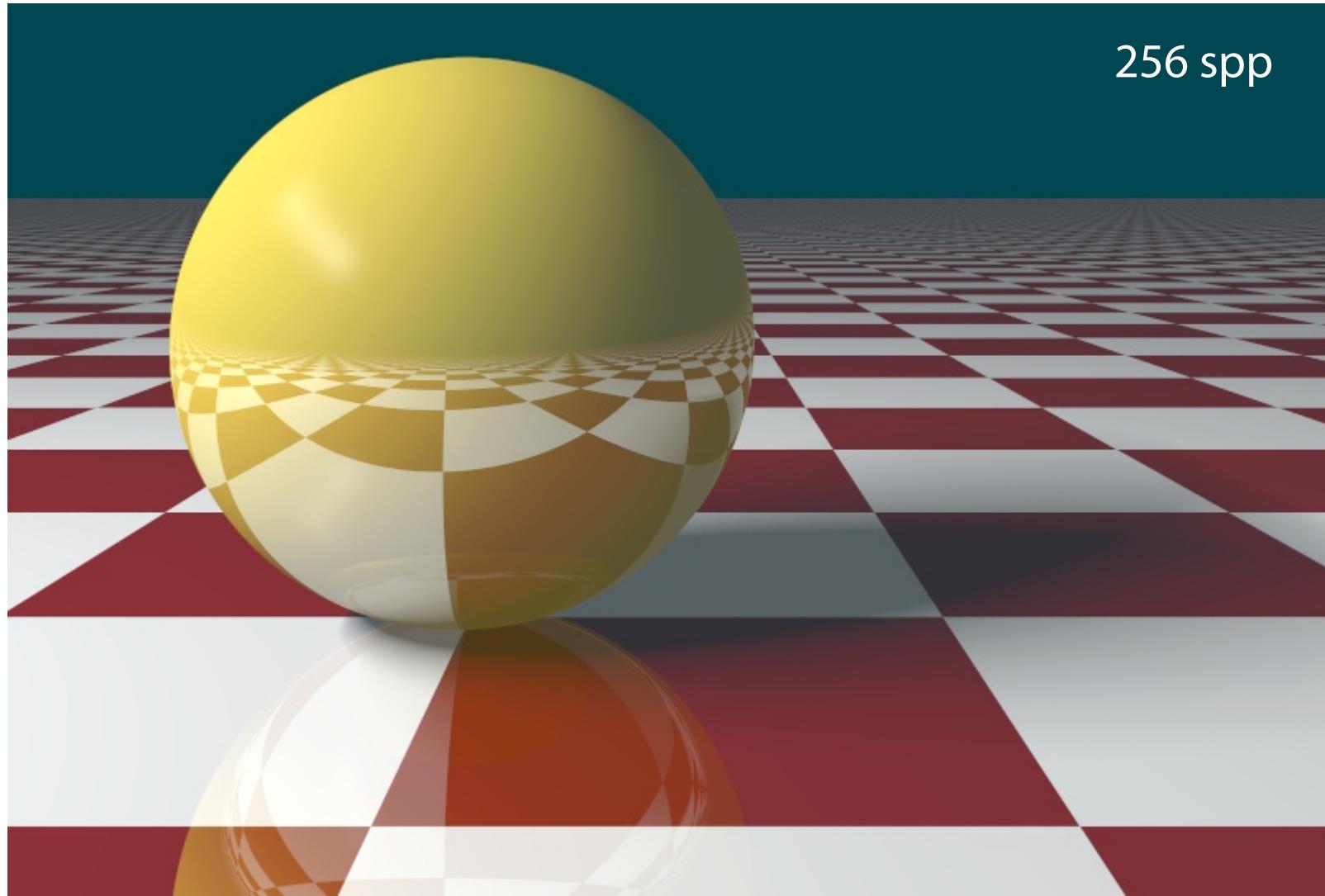
$$I(A) = \iint_{\text{light source area}} I_L(u, v) \cdot \underline{\text{vis}(A, u, v)} du dv$$

visibility function

$$\underline{\text{vis}(A, u, v)} = \begin{cases} 1 & \text{if } S(u, v) \text{ is visible from } A \\ 0 & \text{else} \end{cases}$$



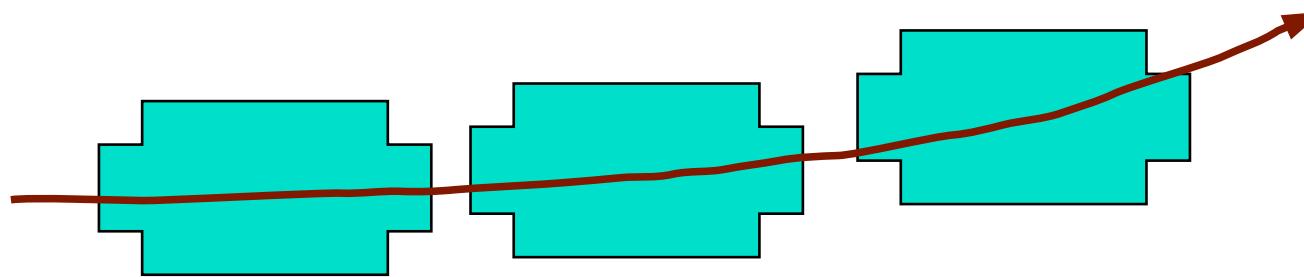
Soft shadow – example





Motion blur

path of the solid $s(t)$



Rendered interval
(shutter open time)

$[t_1, t_2]$

Scene rendering in time t

$f(t) = f(x, y, t)$



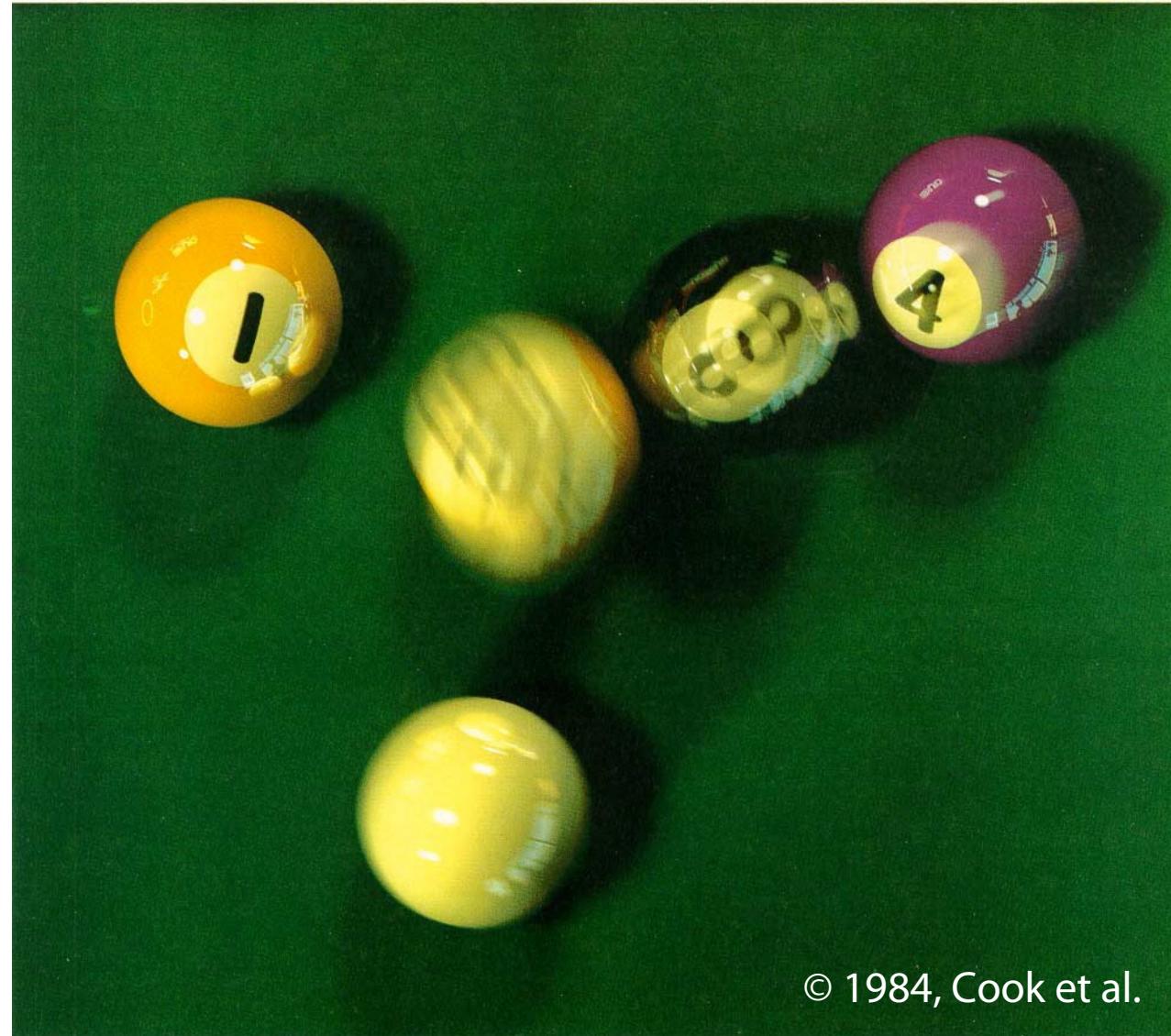
Motion blur

General motion blur

$$f_{\text{blurr}} = \int_{t_1}^{t_2} f(t) dt$$



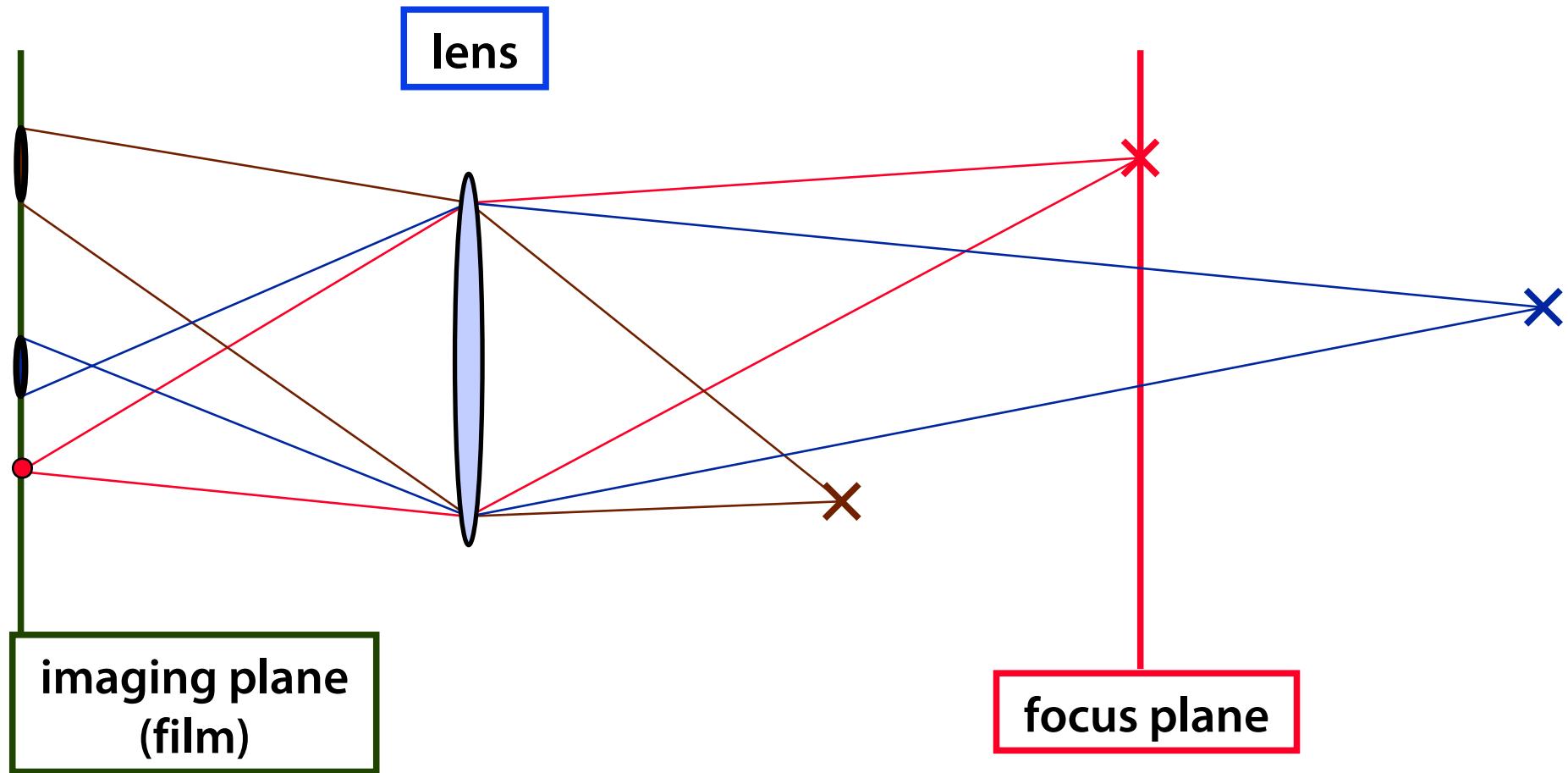
Motion blur – famous example



© 1984, Cook et al.

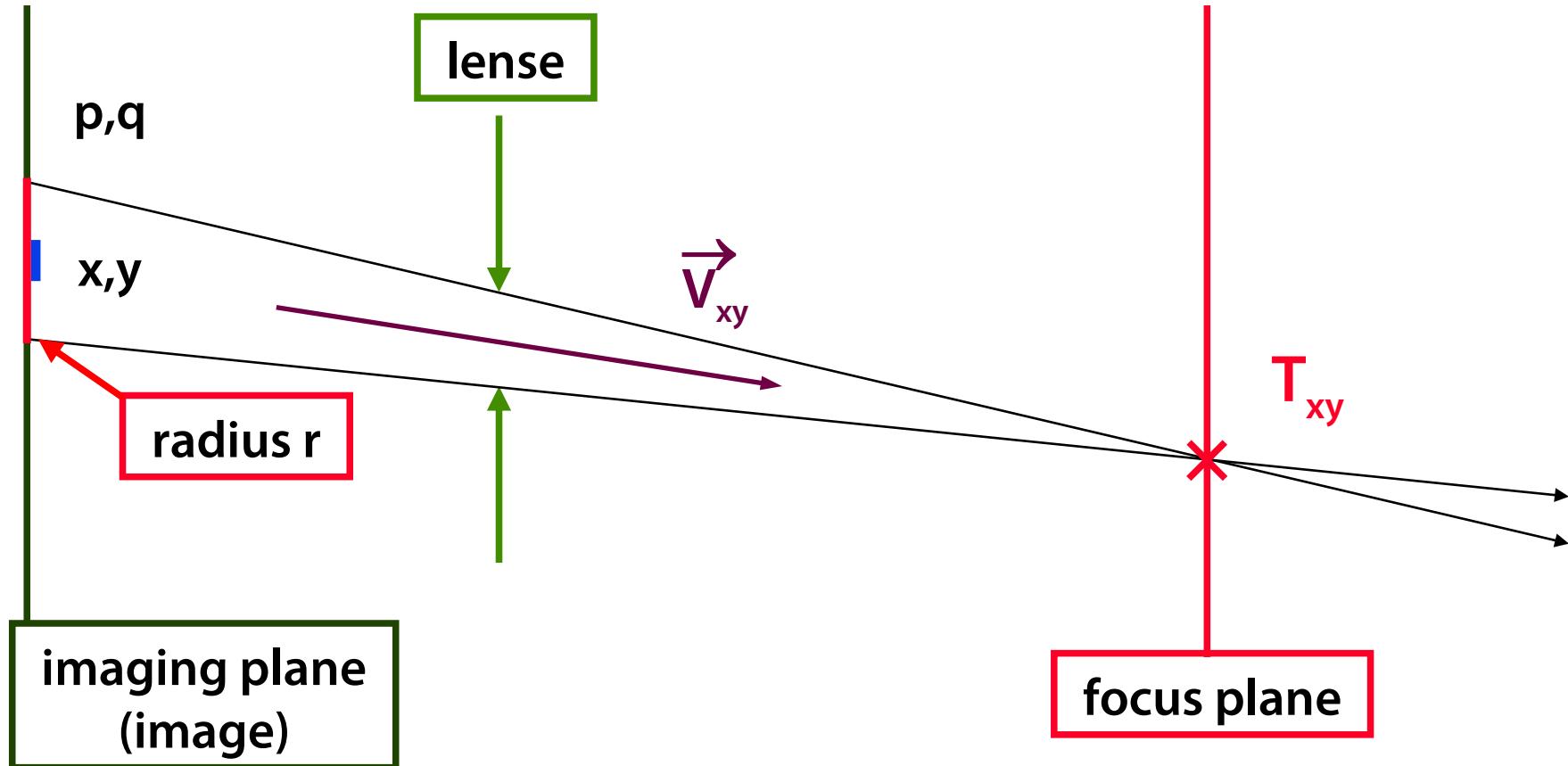


Depth of field





Geometric simplification





Depth of field computation

Pinhole camera model

$$f(x, y) = I(V_{xy})$$

$$V_{xy} = T_{xy} - [x, y, 0]$$

$$V_{pq} = T_{xy} - [p, q, 0]$$

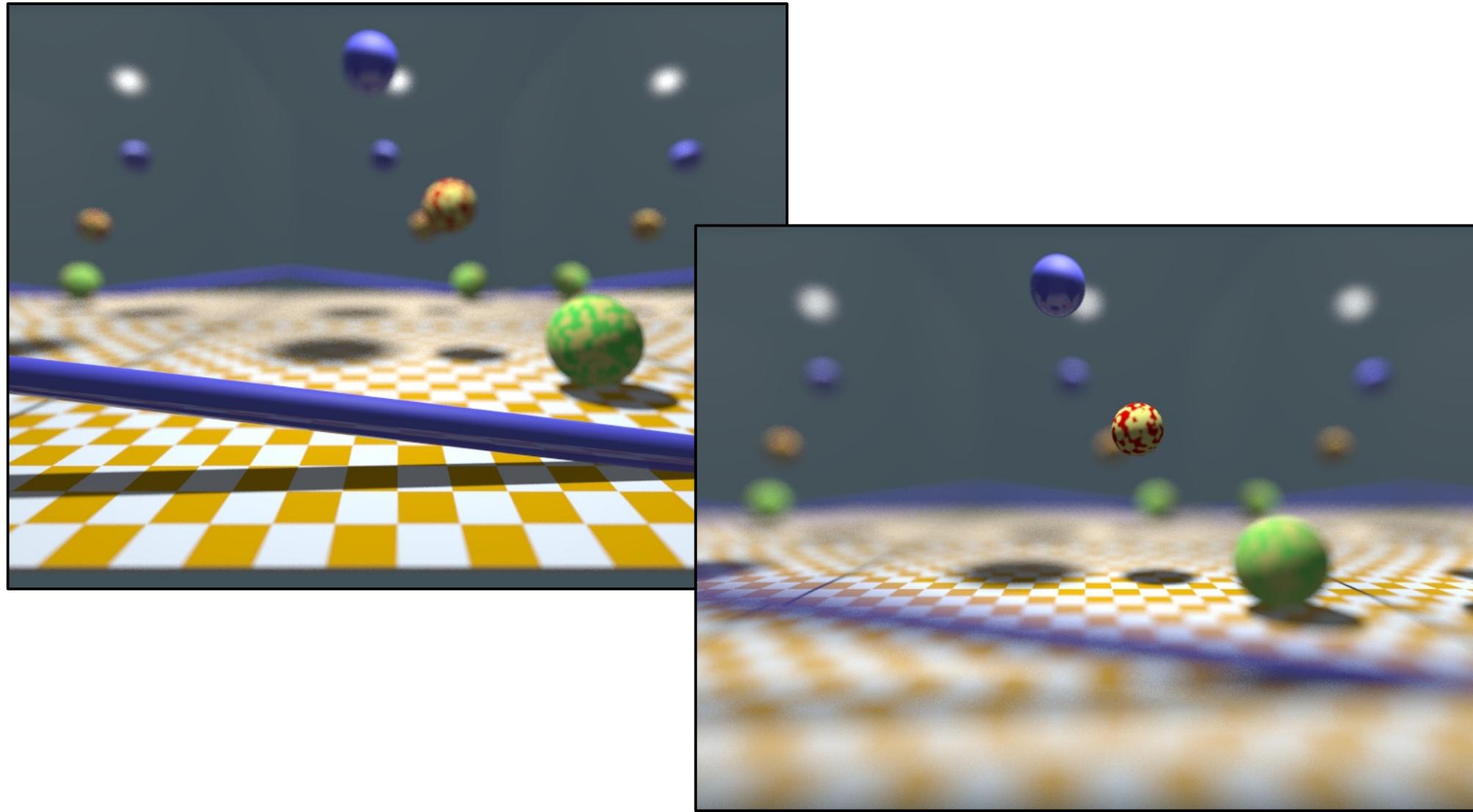
Lens with finite aperture

$$f(x, y) = \int I(V_{pq}) dp dq$$

circle around [x, y]



Depth of field – examples





Light dispersion

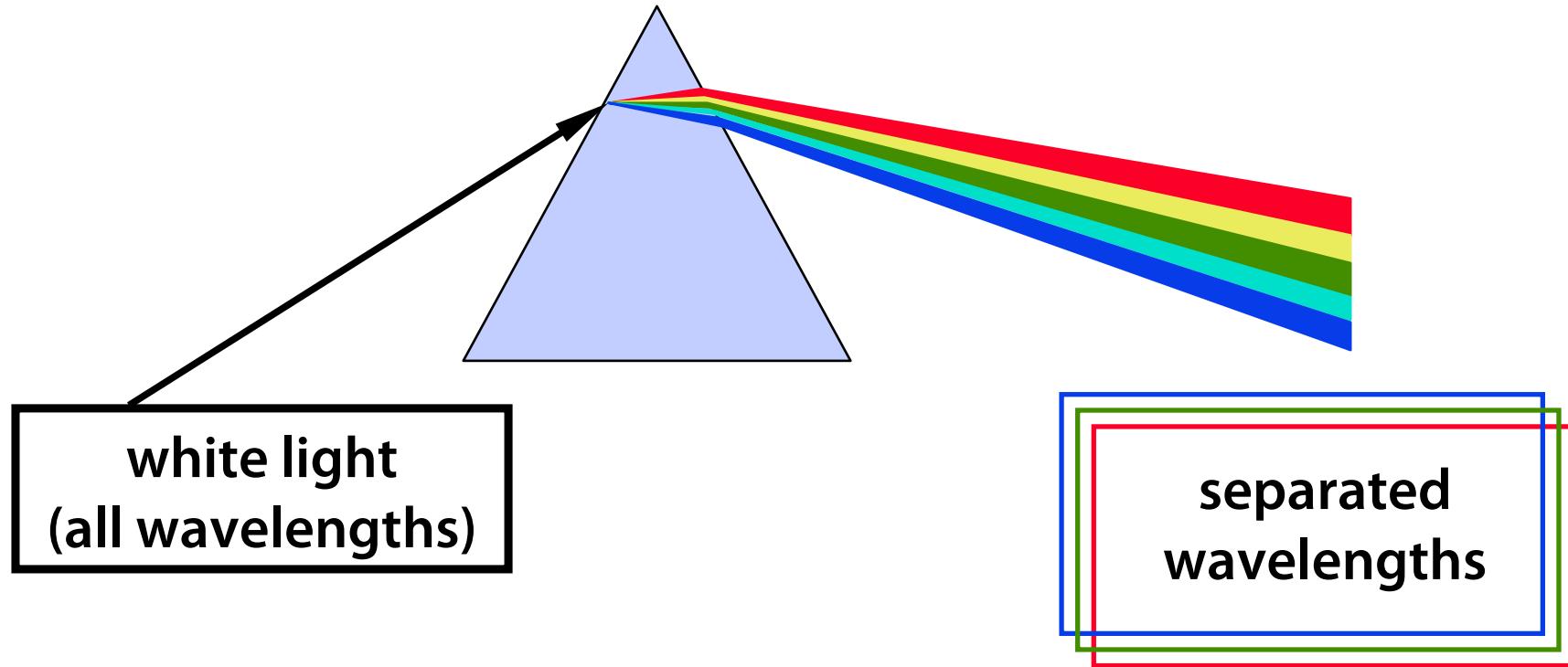


image function

$$f(\lambda) = f(x, y, \lambda)$$



Light dispersion computation

Pixel RGB color from spectral distribution

$$R(x, y) = \int f(x, y, \lambda) \cdot R(\lambda) d\lambda$$

spectrum

$$G(x, y) = \int f(x, y, \lambda) \cdot G(\lambda) d\lambda$$

spectrum

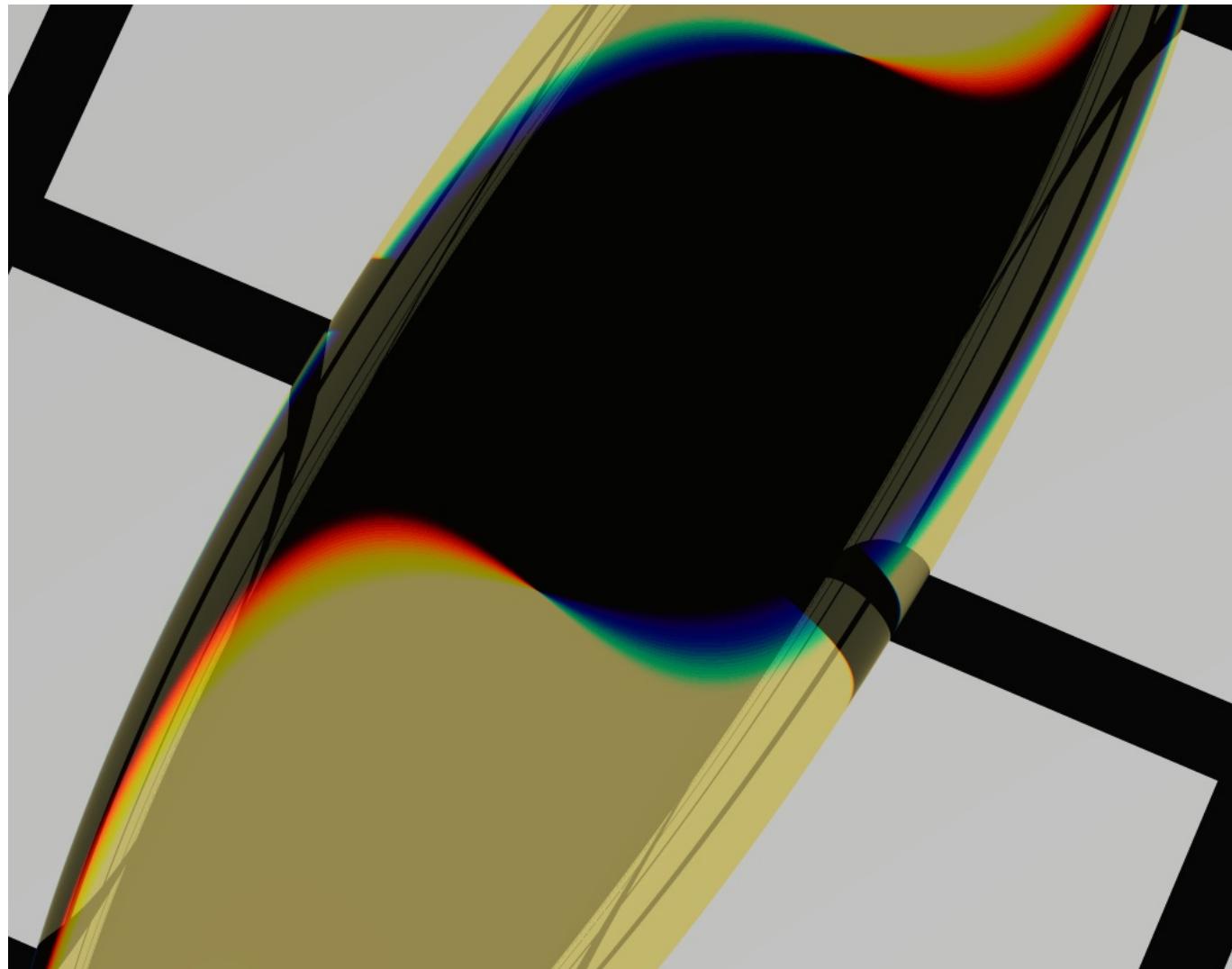
$$B(x, y) = \int f(x, y, \lambda) \cdot B(\lambda) d\lambda$$

spectrum

trichromatic
spectral
coefficients



Light dispersion – example





Implementation

Integral averaging is done **stochastically** (Monte-Carlo methods)

- finite number of point samples (rays)
- integral is estimated by a [weighted] sum

Weighted integral average

- uniform sampling and appropriate weight function
- nonuniform sampling (using the right density/PDF)



Combining methods

Any methods can be **combined**

- with anti-aliasing as well
- higher order integrals – e.g. dimension 10:
 - anti-aliasing (2), depth of field (2), glossy reflection (2),
 - soft shadows (2), motion blur (1), light dispersion (1)

Sampling method

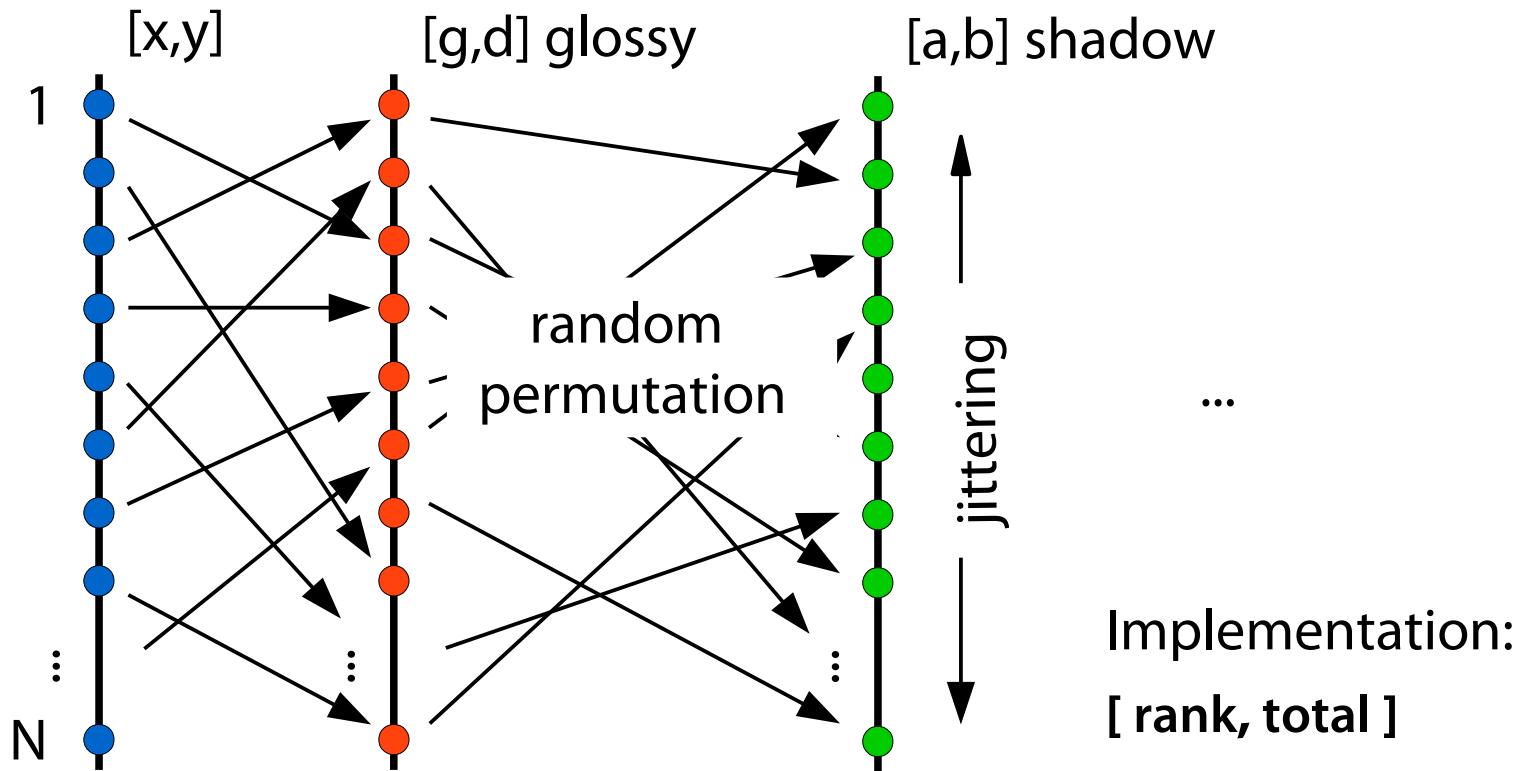
- jittering
- independent jittering (“N rooks”) in form of **hidden sampling**
- adaptive sampling



Hidden sampling

Number of **samples per pix** (primary rays) is defined

- every inner component is sampling independently
- arbitrary number of additional (sampled) dimensions





Literature

A. Glassner: *An Introduction to Ray Tracing*, Academic Press, London 1989, 171-199

A. Watt, M. Watt: *Advanced Animation and Rendering Techniques*, Addison-Wesley, Wokingham 1992, 262-265