

Recent Challenges in Computer Animation of Characters

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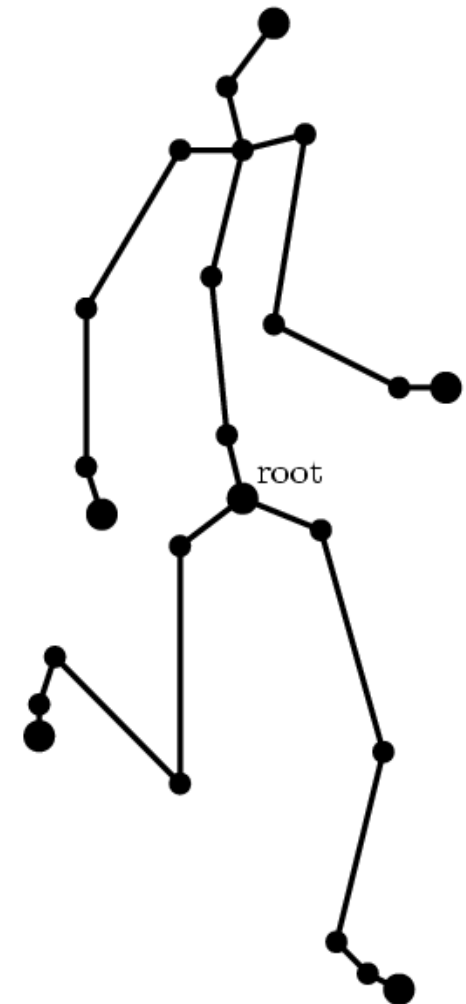
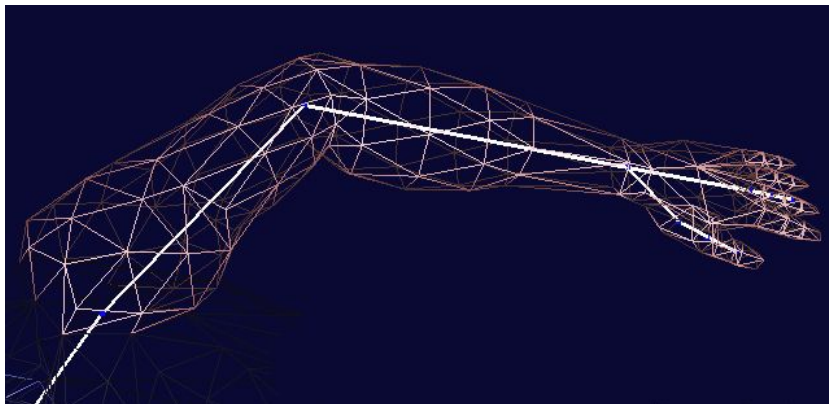
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Overview

- ◆ Human body modeling
- ◆ Obtaining of a realistic motion
- ◆ Motion editing and reuse
- ◆ Motion library
- ◆ Conclusion & future work

Human Body Modeling

- ◆ abstraction: skeleton + skin
- ◆ articulated figure
 - approximation of a real skeleton
- ◆ skinning



How to Obtain a Realistic Motion?

- ◆ keyframing, simulation, **motion capture**
- ◆ Motion capture
 - definition
 - technology
 - conversion to motion of the skeleton (joint orientations)
 - unique by naturalness and “aliveness” of the motion

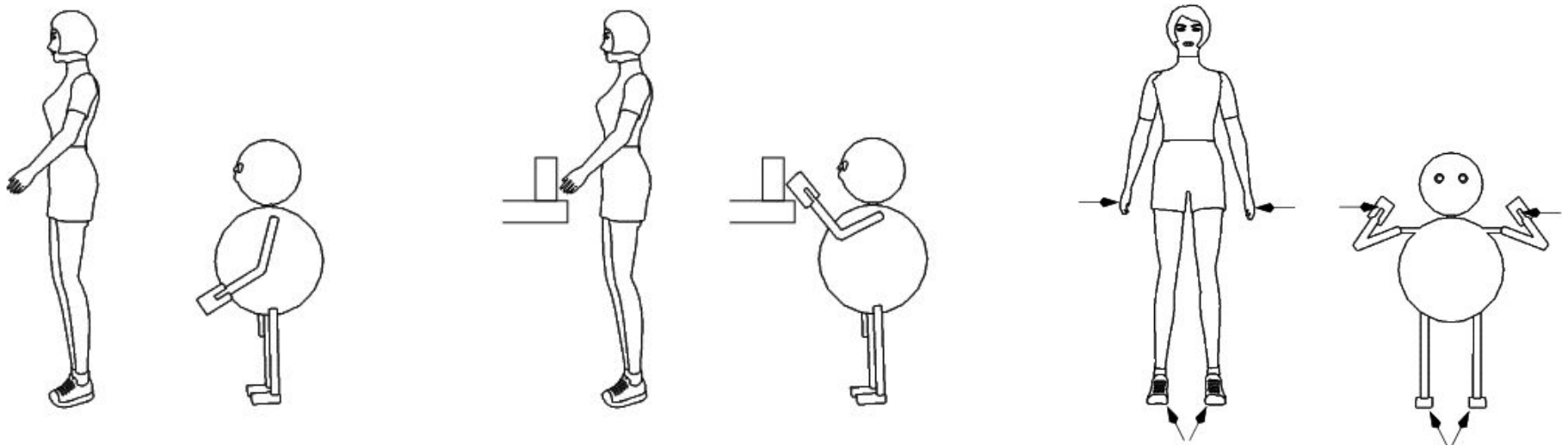


Motion Editing and Reuse

- ◆ Why to edit a realistic motion?
- ◆ preserve an “essence” of the motion, alter outer properties
- ◆ motion as a signal
- ◆ specialized techniques
 - path editing, blending, retargeting

Motion Retargeting Problems

- ♦ adapt an existing motion to a character with different proportions
- ♦ Preserve j. angles or end-effector positions?



Motion Library

- ♦ motivation
 - extensive reuse of motion
 - specification of motion “by example”
 - free realistic motion in a virtual environment
- ♦ basic motions stored in a library
- ♦ search the library for a best-fit motion and adjust it
- ♦ more complex motions by concatenation, looping, blending (interpolation), ...

Motion Library – A Math. View

- ♦ character posture – a point in multi-dimensional space P
- ♦ motion – a smooth curve in P
- ♦ → motion graph
- ♦ motion library – analogy to a basis
 - independence, completeness
- ♦ techniques from algebra, approximation or databases may be used

Motion Record in the Library

- ◆ understanding and parametrization of motion
- ◆ motion “normalization” for storage in library
- ◆ structured motion record
 - body model
 - kinematic record of the motion
 - constraints for interaction with environment
 - parameters
 - attributes

Conclusion & Future Work

- ◆ synthesis of motion using a motion library – a recent and perspective trend
- ◆ a number of unanswered essential questions
- ◆ related tasks
 - understanding of motion – identification of constraints and parametrization
 - choice of elementary motions forming a basis
 - search for best-fit motion